Unique No.: 195888

Date of Entry: 01/04/91

1

DATA ENTRY INFORMATION SYSTEM (DATASET INVENTORY - DINDB)

Accession No.: 7500530 Reference No.: L01166 Former Accession No.: Former Reference No.: (Resub ONLY) -----_____ _____ Media-In (DINDB): 09 - Digital Magnetic Tape Exchange Format: E134 - Moored Buoy Data Processing Format: L124 - Level 1, No Active QA Processing * Note * If data is F022, create an additional record for C022. Country/Institute Code: 31R9 Country/Platform Code: 3119 Platform Type (DINDB): 03 - Buoy Orig. Cruise ID: 16-59 Cruise Start Date: 05/01/64 Project Code: 0078 Cruise End Date: 09/01/73 Data Use Code (DUC): 3 ______ Number of Stations: 23 Number of Records: 145,900 If stations/records not appropriate then: Units: Number: _____ Ocean Area: Code 1: 57Meaning: North Pacific OceanCode 2:Meaning:Code 3:Meaning: _____

DINDB Transaction Date:

ACCESSION NO. <u>7500530</u>	FILETYPE	L124	TRACK NO. LO1166	PROJEC IDENTI		ON	
	Bumble	e Bee Buc	oy Data 1964-1973	3			
STEP	DATE,	INIT.	TAPE OR DISK DSN	NO. FILES	LRECL	BLK SIZE	NO. RECORDS
ORIG. TAPE	01/08/91	HEC	Dod946-A01339	42	80	4000	145,900
DUPLICATE TAPE			W11962				
REFORMATTED TAPE							
REFORMATTED DISK							
FIRST MULCHEK							
FINAL MULCHEK						· ·	
MPD75 OR F022					1		
DATA SET FINALIZED							

ERRORS REPORTED TO PRINCIPAL INVESTIGATOR:

ADDITIONAL ERRORS/CORRECTIONS (NOT REPORTED TO P.I.)

COMMENTS (TRACKS DELETED, FIELDS DELETED, ETC.)

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ID#: 73-LOS 30 ORIGINATOR'S TAPE Assigned NODC 7-#8244 NORPAX DATA DOCUMENTATION FORM RESPONSIBLE COMPUTER SPECIALIST: BONITA PLOASE Institution: 512 Physical Location of Data: NORPHY KIDG. BRIEF DESCRIPTION OF DATA (include area and time of coverage, frequency of cbs., original source of raw data) BUMBLE BEE BUDY DATA, CONSVERTED TO ENGR UNITS INITING EUDYS 15,18,19,22,29,30- MAY/1964 - FEB/1967 REGULAR BUDYS 34-59-FEB/1968 - 1973_ 10B: NR. EXCEPT PPORTION OF BUOY 40 +46 (FILES 11 # 19)-EVERY 6. MIN ABEL FACSIMILE SHADE IN GENERAL AREA OF COVERAGE BUNBLE MES BUOK 3 155 740 CONSERTED WARD TROPS CARCHIVE, WORKING \$NODE (Section .) File Name D 1001101 000,335 J Generated Under S 195 372 402 Account Number_ 1408 44 3 ĸ 444 479 ťC. Card - Tray(s) . Card - Box(es) A 214 551 R Card - Drawer(s) ťD S Recording Mode: BCD / EBCDIC / BINARY / ASCII / ____ Number of Tracks (Channels): SEVEN / NINE Density: 200 / 556 / 800 / 1600 bpi / λ P Parity: ODD / EVEN Blocked Data: NO / YES 50 LOGICAL RECORDS / PHYSICAL RECORDS Physical Record Length in Bytes (characters): 4000 where the byte (character) is 8 bits 83 CHART & DEVICAL SECOND Labeled Files: <u>NO</u> / YES - describe BRIEF DESCRIPTION OF FILE ORGANIZATION Number of files_ 4(2) Approximate number physical records per file (if known) Variale EOF BETWEEN CRUISES & BETWEEN BUOYS, 12 EOF'S AT EOT W IS DATA SORTED / SEQUENCED? BY EUOY (16-51) BY CRUISE, BY DITTE, BY HOURS IF NORPAX GENERATED DATA: Data created 2/9/25 by program TETRIN (SPACIO

FILES 8-28,30-42 BUDYS 35-49,51-39

LOGICAL RECORD FORMAT DESCRIPTION

1					
FIELD	POSITION	FIELD		ATTRIBUTES	USE and MEANING
NAME	from start	LENG	ΙΗ		
	of record measured		• •.		
	in <u>CHAR</u>				
	(e.g.bits,	•			
(e.g.	bytes, char.,				Include datum (if used) and other
temp.)	col.)	No.	Units	(e.g. F4.1)	data processing techniques
I.D.	· /	3	CHRAN	A3	"SIO"
STH NO.	4	R.	Di Ciri	12	No of BUOY
YR.	6	2		I2	Last TWO DIGITS OF YR 620
DAY	. 8	_	DAYS	I3	JULIAN DATE 1-365
TIME	11	4	41.5.	T.I.	GMT TIME OF OBS.
1 M.SEA	15	3	°C	F3.1 V	SEA TEMP. (C) AT IM. DEPT,
500	18	3		11	······································
10	21	3	11	1.	30
30	24	3	· · ·		
50	27	3	· · ·		75
75	30 33	-3	ų.		100
150	36	3	.,		150
300	39	5	<i>.</i> ,	·.	300
AIR	42	3		· L	AIR TEMPERATURE
1100	45	3	De Gr.	F3.0	CONVERSS HOG. FROM TRUE N
W. PIR	48	.3		F3.0	WIND PIRECTIONS "
W.SPD	51	2	nils.		ω ω ω ω
BDA. JP. 150 P.	53	4			BAR. PRESSURE
3000. 2	57	2010		F3.0	(FILE 30, BODY 51 - HOT WIRE MOTING WAS BOOM OF PTH PRESSURE
DIDUR.T.	63	.4		Ful. O	BOOM DEPTH PRESSURE
SOLDR	67	· el			FILLS 35-42 EVENSSSS9- MOT WIRE LS-65 FILS SOLAR RADIATION 600
W. TRAKS		4		F4.0	WIND TRANSPORT
1.n. 1.1.G	75	Ny's	°C-	F3 1	Im. LAG
San Lotin	1 78	1-5	- C	F 5 1	Sm. LAG
RTW:db	ta Managemei 9/72	50			

FILES 1,2 BUSYS 16,15,19,22 LOGICAL RECORD FORMAT DESCRIPTION

TELD	POSITION	FIELD		ATTRIBUTES	USE and MEANING
IAME	from start of re cord	LENG	тн		
	measured				
	in <u>CLIP</u> R				
e.g.	(e.g.bits, bytes,char.,				Include datum (if used) and other
e.g. emp.)	col.)	No.	Units	(e.g. F4.1)	data processing techniques
10.	1	3	CLIP		"SIO"
STA.NO.	4	2	1	· I 2	NO OF BUDY
YR.	6	2	11	I2	LAST 2 DIGITS OF YR GE
DAY	8	3	DATS		JULIAN DATE 1-365
TINE	11	21	1.13	14	GMT TIME OF OBS.
PIRT.	15	2	۰F	F2.0	Rex Terme (°F)
m SEN.	17	3	0°C	F3.1	SED TEMP (C) AT I.M. DEM
Dm "	20	3	10	F.3. 1	10
°O ••• "	23	(2012)	ы и ¹	F3.1	30
0 m "	26			F.3.1	60
00, " 50, "	29	53	,	F3 / F3 /	100 150
U.SPD	32	2	K	F2.0	WIND 520. (K)
U. DIR.	35 37	3	DEG	F3.0	WIND DIESTION (FROM THEIR
100	40	3	11.	F3.0	ComPriss NOG. (From Theur N)
INE T.	43	2	KG	F2.0	MODR. LINE TENSION (KG)
BLINK	45	32	13'	32X I4	BLAWK
1.0.	77	4	DIGIT	Z4	10 NO.
• •	}	50			
•					
	7	ł			
			1		
		l			
		{· .	1		
. •					
	· ·		1.		•
-	1	l'	1	1	

FILES 3,4,5 BUDYS 29,30 LOGICAL RECORD FORMAT DESCRIPTION

FIELD	POSITION	FIELD	ATTRIBUTES	USE and MEANING
NAME	from start	LENGTH		
	of.record			
	measured			· ·
	in <u>C//AC</u>			
•	(e.g.bits,			
le.g.	bytes, char.,			Include datum (if used) and other
temp.)	<u>col.)</u>	No. Units	(e.g. F4.1)	data processing techniques
ID.		3 CHH	H3	"SIO
STA NO.	4	2 01417	1 I 2	No OF BUDY
1R	6	2	172	LAST 2 DIGITS OF YR QQ
		1 I		
DAY	8		T3	JULIAN DATE 1-365
TIME	11.	4 ARS	II4	GMT TIME OF DBS.
HIRT.	15	2 0F	FZ.O	AIR TEMP (°F)
LIDG				Compriss HOO ("From Trevel
•	17	3 Pet		
W. DR.	20 23	3	F3.0	WIND DIRECTION (FROM "
W.SPo.	23	$ \mathcal{A} K$	F2.0	WIND SPEED (K)
· /.		3 .	F 3.1	SEN TEMP (°C) AT IM DEP
45	25	3 ·C	F3.1	
15	28		•	
65 85	31	1 1	F3 1	65-
85	34	3	F3.1	55
105		3 .	13.1	105
125	37	3 "	F3.1	1
	40			
250	43	3	F3.1	0.3-
BLANK	46	35 8		BLANK
JEN W	76			
· · · .		80		
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RTW:db 9/72

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FILES 6,7 BUDYS 34,35 LOGICAL RECORD FORMAT DESCRIPTION

e.g.	from start of record measured in <u>C.MAR</u> (e.g.bits, bytes,char., col.) / / / / / / / / / / / / / / / / / / /	LENG No. 32231	1	A3	Include datum (if used) and other data processing techniques STO NO OF Buol
e.g. emp.) 10. 57.2 7.2 7.2 7.2 7.2 7.2 7.2 7.2	measured in <u>C.I.A.R</u> (e.g.bits, bytes,char., col.) / 6 8 // 6 8 // 15 /8	らんていて	C1#R D-G-TS	A3 I2	data processing techniques SID NO OF BUD1
e.g. emp.) 10. 5777 YR 0777 7777 EH 101 50 200 300 300 300 300 300 500	in <u>C.MAR</u> (e.g.bits, bytes,char., col.) 	らんていて	C1#R D-G-TS	A3 I2	data processing techniques SID NO OF BUD1
e.g. emp.) 10. 57.2 Y.R 0.27 Y.R 0.27 7.77 E.H 1.01 57 75 100 200 300 300 400 500	(e.g.bits, bytes,char., col.) / / / 6 8 // / 8 // / 5 / 8	らんていて	C1#R D-G-TS	A3 I2	data processing techniques SID NO OF BUD1
e.g. emp.) 10. 57.2 Y.R 0.27 Y.R 0.27 10. 57 100 300 300 300 300 500 500	bytes, char., col.) -/ -/ 6 8 11 15 18	らんていて	C1#R D-G-TS	A3 I2	data processing techniques SID NO OF BUD1
emp.) 10. 57.2 YR 07.7 YR 07.7 10.7 57 100 200 300 300 400 500	col.) -/ -/ -/ 	らんていて	C1#R D-G-TS	A3 I2	data processing techniques SID NO OF BUD1
10. 577 YR 077 107 575 100 300 300 300 300 300 500 500	1168158	らんていて	C1#R D-G-TS	A3 I2	NO OF BUDI
5717 YR OHY TIME EH IM 500 200 300 300 300 300 500	68158	2231	0.6173	I2	NO OF BUDI
5717 YR OHY TIME EH IM 500 200 300 300 300 300 500	68158	2231	0.6173	I2	NO OF BUDI
YR OHY TIME EH IM 1011 50 75 100 300 300 300 300 500	68158	231			
OHY TIME EH INI JON 50 75 JOD 200 300 300 400 500	8 1 5 1 8	3	Diry	173	
TIME EH/M 10,11 50 75 100 300 300 300 300 300	11 15 18	2/	DAY		LIST 2 DIGITS OF TR. 60
TIME EH/M 10,11 50 75 100 300 300 300 300 300	11 15 18	2/		T 3	JULIAN DATE 1-365
EH /11 1011 50 75 100 200 300 300 400 500	15	. 4	LIRS	74	GRIT TAME OF DOS.
10,11 57 75 100 200 300 400 500	18	2			
57 75 100 200 300 400 500	-	3	°C		SEA TEMP. AT. Im. DENT.
57 75 100 200 300 400 500		3	· · ·	F31	10 10
75 100 200 300 400 500	21	3	•	F31	
100 200 300 400 500	24	3	· · ·		25
0.00 300 400 500	,		·	FBIL	
300 400 500	27	33		F3-1	100
400 500	30	s) m	"	F3.1	
400 500	33	3	"	F3.1	. * * 300 [™]
500		3	,	F3.1	. 400
· · · · · · · · · · · · · · · · · · ·	36				/ / /
AIR T.	39	3		F3.1	500
	,	· r		F3.1	AIR TEMP.
HOG	42	(r, i)	DEG	F 310	Compass HOG I Kom TREE N
·	45			F3.0	WIND DIR. FROM TRUE N.
J. Pik.	48	يك			
N. 5, 0.	50	4	m/s	F2.0	WIND SPEED
BAR, Par	,		mB	F4.0	BARDMETRIC PRESSURE
DENTIL V.	54	il		F3.0	DEPTH PRESSURE
	57		1.6	F4.0	
UNIO CELL			1		LOAD CELL
SOLAR	61	4		4 F4, 1	SOLAR KADIATION
BLANK	, 69 -	12	. 19 in		BUNDE
	, 67 -	80		·	
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FILE 29 BUDY SD LOGICAL RECORD FORMAT DESCRIPTION

FIELD	POSITION	FIELD	-	ATTRIBUTES	USE and MEANING
NAME	from start	LENGT	H	а. А.	
	of record			•	
	measured				
	in <u>CHPR</u>				
	(e.g.bits,				
(e.g.	bytes, char.,				Include datum (if used) and other
temp.)	col.)		Units		data processing techniques
		3	CHAR		"SIO
STA.	4	2	OrGiris	1.2	NO OF BUDY
YR.	6	2	••	72	LAST TWO DIGITS OF YR 60
	. 0	· •	OHYS		
DAY	Y	_			JULIAN PATE 1-365
TIME	11	4	LIK'S.		Grit TIME OF OBS.
IM SEH	15	3	°C	F3,1	SEA TEMP (C) AT IM DEPT
2.5	18	3	•,	F3.1	· · · 2.5 · ·
5	21	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	11.	F.3. 1	1 h h h h
	24	3	4.	F3.1	
7.5		1 . 1	l:	and the second	1 7.5
10 "	27	3	•.	F.3.1	
12.5	30	3	G .,	F3.1	
15 "		.3	b.	F3.1	1 15 1
20 "	33	2	,	F3.1	20
25 "	36	u) u) (u	~	F3.1	
	39	2			
35 "	42	300	<i>י</i> .	F3.1	35
45 "	1.5	3	~	F3.1	4/5
60 "	4.5	3	\mathbf{u}^{\pm}	F3.1	1 · · · · · · · · · · · · · · · · · · ·
i · · ·	78	30		4	BLANK
BLINNE	51	and the second s			
		80			
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NORSHITE		<u> </u>		l	<u> </u>
NORPAX Da RTW:db	ta Managemer 9/72	ιť	•	. ·	

Temperature 1 st cand -Salinity Signa - Trippie 67- 750 - 0001 2nd card - Ofgen -0001 apparent of ygen Utilization 100- 0003 -Percent offger Saturation 100 0002 -Chlouphyll 501. 5000 -3 rd card - phyphate - 100.0010. Silicate _ 100-0030-Matcate - 100-0021-Mitute - 100.0020ammonia - 100-0041 - 2010-4th card -Mitrate Selecte Matio No ETS - 501-5007 -Carlon 14 501-5003 -21 REA - 100. 5009 034 5th Card -Deserved organic mitroger (516- 84 Total Particlas 100-8600 Particle ava no mo 1 Arr. Sing Particle Volume At 6 th card -

75-0530

Njert in 0078- IDOE/NORPAK Peatform - SIO BZIOY Project in 0078. Parmeter 0.188 - an Temperatra 0180 - Minter Timp. 0189 - Wind Direction 0.190 - Minnid Speed 0191 - Barometric Prisence. 0184 Prestine 0065 Sola Radiation

Searce observation Hank -Write Type # 8244 in unarte alumn.

yage 1 7 2

\$20 Bury Jocations

7 may 64 -\$1972 200 Bury #16

ر، دچه ° بخت

32° 10'N

30° 51.5'N

29° 58.8'N

6°05'N

9° 38'N

36° 39.7'N

36° 39.0'N

128° 38'W

132° -46.8'W

128° 37.8 W

Slo Buoy # 18

Sell Bury #19

1800 Busy # 22

solo Bury # 29

\$00 Surg # 30

1 \$10 Busy# 34

" \$10 Burry 14 35

1 \$ 10 Bury # 38

v \$00 Bury # 39

~ \$10 Bury # 40

1 10 Bury # #2

~ \$10 Burry # 45

41° 59.5'N 42° 55.5'N

42° 28.2'N

43° 35.8'N

41° 00.0'N

140° 01.0'W 118° 51' W 119° 00 W

122°07.2'W

122° 07.0'W

163° 59'W

158° 15.0'W

158° 01.5 W

157° 46.5'as

147° 57.8'W

NODC ACC # 75-0530

UNIVERSITY OF CALIFORNIA, SAN DIEGO

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SANTA BARBARA - SANTA CRUT

SCRIPPS INSTITUTION OF OCEANOGRAPHY

12 February 1975

POST OFFICE BOX 1529 LA JOLLA, CALIFORNIA 92037

Mr. Nelson Ross NODC Liaison Officer National Marine Fisheries Service P.O. Box 271 La Jolla, California 92037

Dear Nelson:

Enclosed is a tape of all data that we processed from our bumblebee buoy platforms. These data are contained on one 9 track, 1600 bpi magnetic tape. Included with the tape is a listing of the first record of each file and a complete set of documentation which provides detailed information as to the technical characteristics of the tape as well as logical record format. With this documentation and the copy of the tape, it should be possible for any reasonable computer programmer to read and understand these data.

I trust that you will send this on to the proper office at NODC for permanent retention as the national record of this scientific data from this series of platforms. If the people in Washington have any questions concerning the technical nature of this data set, please let them call me directly at 714/452-4495.

Thank you for your help on this matter.

Sincerely yours,

Richard T. Wert NORPAX Data Manager

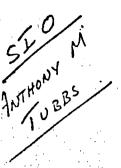
cc:

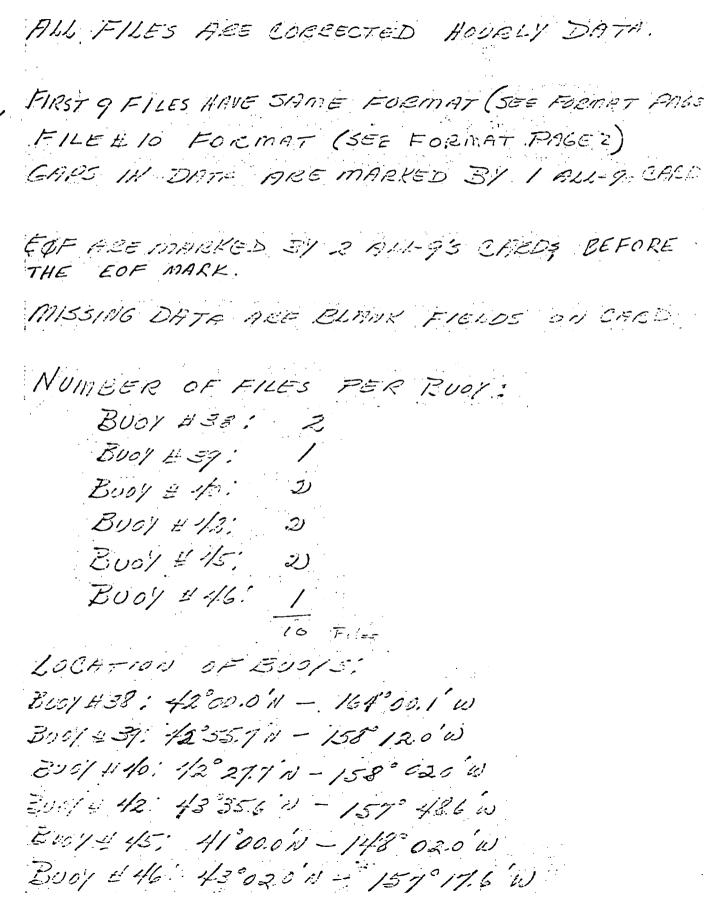
Dr. James J. O'Brien Code 481 Office of Naval Research, Arlington, Virginia

cc:

Dr. Curtis A. Collins IDOE - NSF, Washington DC 20550

TAPE LACES NODC-1 DENSIEY MY (2005 p.L.) AB CODE BED (CRED INRES TECHOS) Frank





0 MULTAPI File#1 3952 Records Budy#38 Course 1-3 Time Period (1500) 9 Oct- 1968 To (0700) 23 Man 1969 Veer Day 253 To 082 Yean Week. 41 To 13 Gaps in Data None File #2 25-44 Records Buoy # 38 Course 4-5 Time Ferriod: (1900) 2 June 1969 To (2300) & Dec 1969 Veer Day: 153 70 338 Veer Vieck: 23 70 49 Gaps in Data: Day 192(2300) To Day 197(0900) and Day 200 (0,00) To Day 275 (0,300) File#3 1309 Recends Buoy # 39 Course 1 Time Ferrod: (2400) 11 Oct 1968 To (1600) 6 Dec 1968 Ver Dev : 255 To 341 Ver Week: 41 To 49 Caps in Data: None Caps in Data: None Filer 4 2207 Records Booy = # 40 Course 1-3 Time tenrod (0.500) az -Sept-1968 To (2300) 1 In 1969 Vear Day: 266 70 001 Vear likek: 39 70 1 Geps in Deta Day 283 (0800) To Day 288 and Day 240 (1400) To Day 345 (2100)

MULTAPIL (cont) File#5 1445 Records Buoy#40 Cruise 4-5 Time Ferrod: (0100) 2 May 1969 To (1900) 22 Nov 1969 Ver Del: 122 To 326 Ver Week: 18 To 48 Gaps in Dala Der 128(0800) To Day 273(File#4 4639 Records Bury# 42 Course 1-3 Time Period: (0600) 20 Sept 1968 To 6000) 1 Apr 1969 Ver Day: 264 To 091 Ver Week: 38 To 14 Caps in Data: None 1 # 7 Records Booy # 42 Course 4 Time Period (2000) 3 Jone 1969 To (0400) 12 Sept 146 Vear Der 1 154 70 255-Vear Week 23 70 37 Caps in Data: None

MOLTAPZ File #1 3294 Records Buoi/#45 Course 1-3 Time Period (0200) 20 Oct 1965 To (0500) 6 Mar 1969 Year Day: 294 To 065 Year Week: 43 To 10 Gaps in Darla None File#2 7399 Records Buoi #45 Course 4-6 Time Period (2000) June 10, 1969 To (0200) Apr 15, 1970 Vear Day 161 To 105 Vear Week 24 To 14 Capis in Data: Day 263 (1600) To Day 263 (2000) The #3 1710 Records Buoy #46 Cruise 4-5 Time Period (0400) May 26, 1969 - (1900) Nov 21, 1969 Year Day 146 To 325 Year Week 22 To 47 Gaps in Dala Day 161(1000) To Day 269(2400)

PARAMETERS	I. Do	STA.	YR. YR. 10. DAY	TIME	SEA 1M		iom	30M	50M	75M	100 M	150M			COMPAS. HEADIN	
UNITS					°C	°C	•	•	•	•			•	°C	DEG.	2
CARD COL.	1-3	4-5 6	-7 8-10	11-14	15-17	18-20	21-23	24-26	27-29	30-32	33-35	36-38	39-41	42-44	45-47	\leq
EXAMPLE	SIO	406	8 265	1712	168	166	166	163	106	<u>^95</u>	^ 90	_90	<u>~76</u>	160	120	(
READ FORMAT	(3X,	, I 2, I	2,13,	14,	F3.1,	F3.1,	F3.1,	F3.1,	F3.19	F3.1,	F3.1,	F3.19	F3.19	وا.F3	F3.0,	
COMMENTS					16.8%					9.5°C				16.0°C	TRUE	NORTH
	12										· · ·		17			· · ·
PARAMETERS		WIND	BAP			DEPTH		M DEPTI SSURE	~	RING		SOI	LAR ³		JIND ⁴ RANSP	
UNITS .	DEG.	M'/SEC	MB	•	DECIE	ARS	DECI	BARS	5	KG.		GM-	-CAL		KM.	
CARD COL. S	48-50	51-52	53-56		57-	59	60 -	- 62	63	8-66	· .	67 -	70	7	1-74	
EXAMPLE S	150		100!	5	14	6	30	56	2	04		117	3		778_	·····
READ FORMAT		F2.0,	F4.0	,	F3.	ο,	F3	.0,	F	4.0,	• •	F4.	1,		F4.0)
COMMENTS 2	150° TRUE				. ·						•	117.3 GM-C			778 K	Μ.
· · · · · ·										i.es			•		·	

200

1. DIRECTION BOW OF BUOY IS HEADING.

2. DIRECTION FROM WHICH WIND IS BLOWING.

3 TEGRATED GM-CAL/CM2, 1 HOURL ACCUMULATIONS

NORTH PACIFIC SIUDY DUDY DATA FURMA!

PARAMETERS	I.D.	STA.	YR.	YR. DAY	TIME	SEA		1 1	_30M	50M	75M	100 M	150M	•		COMPASS HEADING	
UNITS						°C	°C	•	•	•	•	•	•	•	°C	DEG.	ζ
CARD COL.	1-3	4-5	6-7	8-10	11-14	15-17	18-20	21-23	24-26	27-29	30-32	33-35	36-38	37-41	42-44	45-47	5
EXAMPLE	SIO	40	68	265	1712	168	166	166	163	106	<u>,</u> 95	_90		76	,160	120	\rightarrow
READ FORMAT	(3X,	, I2,	12,	13,	14,	F3.1,	F3.1,	F3.1,	F3.1,	F3.19	F3.1,	F3.1,	F3.19	F3.19	F3.19	F3.0,	5
COMMENTS						16.8%	,				9.5 C	.[16.0°C	TRUE N	IORTH /
•		• •				ţ	. 2	5	-1	4		-7		- 1	7		

		13	1.9	15 1	V _	16	17	6
7	WIND	WIND	BAR.	150M DEPTH		MOORING LINE	SOLAR3	WIND ⁴
PARAMETERS	DIR.	SPEED	PRESSURE	PRESSURE	PRESSURE	TENSION	RADIATION	TRANSPORT
UNITS	DĘG.	M/SEC	MB.	DECIBARS	DECIBARS	KG.	GM-CAL	KM.
CARD COL. 5	48-50	51-52	53-56	57-59	60-62	63-66	67 - 70	71-74
EXAMPLE	150		1005	146	306	204	1173	<u>^778</u> (
READ FORMATS	F3.0,	F2.0,	F4.0,	F3.0,	F3.0,	F4.0,	F4.1,	F4.0)
COMMENTS 2	TRUE						117.3 GM-CAL	778 KM.

1. DIRECTION BOW OF BUOY IS HEADING.

7 . .

2. DIRECTION FROM WHICH WIND IS BLOWING.

3. I GRATED GM-CAL/CM2, HOURLY CCUM.

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(IM LAG, °C	5M LAG,°C
COL.	COL
75-77	78-80
F3.1	3 .1

ACCESSION NUMBER

7500530

DATA DOCUMENTATION FORM

NATIONAL OCEANOGRAPHIC DATA CENTER RECORDS SECTION WASHINGTON, D. C. 20390

This form should accompany all data submissions to NODC. Section A, Originator Identification, must be completed when the data are submitted. It is highly desirable for NODC to also receive the remaining pertinent information at that time. This may be most easily accomplished by attaching reports, publications, or manuscripts which are readily available describing data collection, analysis, and format specifics. Readable, handwritten submissions are acceptable in all cases. All data shipments should be sent to the above address.

A.ORIGINATOR IDENTIFICATION

THIS SECTION MUST BE COMPLETED BY DONOR FOR ALL DATA TRANSMITTALS

I. NAME AND ADDRESS OF INSTITUTION, LABO UNIVERSITY	RATORY, OR	ACTIVITY WITH	WHICH SUBM	ITTED DATA AR	E ASSOCIATED				
SCRIPPS IN.	STITU T	ION OF	DCEANOGR	АРНУ					
P.O. BOX 109 LA JOLLA, C	ALIFOR	RNIA 92	037						
EXPEDITION, PROJECT, OR PROGRAM DURING		3. CRUISE NUI		BY ORIGINATO	R TO				
NORTH PACIFIC BUOY I	ROGRAM	16 18	19 22	[29 cm	renchat				
('GEOPHYSICAL MEASUREN	NENTS")	differ see	ent data f	format and a	wangement,-				
4.PLATFORM NAME (S) 5. PLATFORM TY		6. PLATFORM	AND OPERATOR	7. DA	TES				
SID BUDY (E.G., SHIP, BI		PLATFORM	OPERATOR	FROM: NO DAY/YR					
BUDY ("PR	OTOTYPE	U.S.	U. S.	MAY 17, 64	DEC. 27 '64				
8 ARE DATA PROPRIETARY ? NO YES IF YES, WHEN CAN THEY BE RELEASE FOR GENERAL USE ? YEAR MONTH_		II. PLEASE DARKEN ALL MARSDEN SQUARES IN WHICH ANY DATA CONTAINED IN YOUR SUBMISSION WERE COLLECTED. GENERAL AREA							
9. ARE DATA DECLARED NATIONAL PROGRAM (DNP) ? (ie., SHOULD THEY BE INCLUDED IN WORLD DATA CENTERS HOLDINGS FOR INTERNATION EXCHANGE ?) NO YES PART (SPECIFY BELOW)	278 4	140° 140° 180° 140° 140 277 244 237 257 700		14 T07 144 78 7073 108	40° 60° 80° 100° 214 245 277 244 245 277 244 245 277 244 40° 212 207 212 207 212 207 214 40° 213 40° 214 40° 214 40° 217 40° 218 40° 218 40° 218 40° 218 40° 219 40° 210 40° 219 40° 200 40°				
10. PERSON TO WHOM INQUIRIES CONCERNING DATA SHOULD BE ADDRESSED WITH TELEPHONE NUMBER (AND ADDRESS IF OTHER THAN IN ITEM-1) Anthony M. Tubbs	407 777 777 777 777 777 777 777 777 407 40	021 014 315 1356 351 392 347	All All <td>ad 001 034 55 300 335 41 336 371 77 372 407 78 70 79 408 443 74 444 477 85 440 515 21 516 551</td> <td>Cost Cost <thcost< th=""> Cost Cost <thc< td=""></thc<></thcost<></td>	ad 001 034 55 300 335 41 336 371 77 372 407 78 70 79 408 443 74 444 477 85 440 515 21 516 551	Cost Cost <thcost< th=""> Cost Cost <thc< td=""></thc<></thcost<>				

NODC-3167/49 (8-70)

B. SCIENTIFIC CONTENT

Include enough information concerning manner of observation, instrumentation, analysis, and data reduction routines to make them understandable to future users. Furnish the minimum documentation considered relevant to each data type. Documentation will be retained as a permanent part of the data and will be available to future users. Equivalent information already available may be substituted for this section of the form (i.e., publications, reports, and manuscripts describing observational and analytical methods). If you do not provide equivalent information by attachment, please complete the scientific content section in a manner similar to the one shown in the following example

EXAMPLE	(HYPOTHETICAL	INFORMATION)
		-

NAME OF DATA FIELD	REPORTING UNITS OR CODE	METHODS OF OBSERVATION AND INSTRUMENTS USED (SPECIFY TYPE AND MODEL)	ANALYTICAL METHODS (Including modifications) And Laboratory procedures	DATA PROCESSING TECHNIQUES WITH FILTERING AND AVERAGING
Salinity	700	nansen bottles	Inductive salinometer (Hytech model 5 510)	(not applicable)
		STD Bishett-Berman Model 9006	N/A-	Values averaged over 5 meter intervale
Water color	Forel scale	Visual comparison with forel bottles	N/A	N/A-
Sediment pize	Sunita and percent by weight	Ewing corer	Standard sienes. Carbonate graction removed by acid Treatment	Same as "Sedimentary Pock Manual," Jolk '65

(SPACE IS PROVIDED ON THE FOLLOWING TWO PAGES FOR THIS_INFORMATION)

B. SCIENTIF CONTENT METHODS OF OBSERVATION AND ANALYTICAL METHODS DATA PROCESSING REPORTING UNITS NAME OF DATA FIELD INSTRUMENTS USED (INCLUDING MODIFICATIONS) TECHNIQUES WITH FILTERING OR CODE AND LABORATORY PROCEDURES AND AVERAGING (SPECIFY TYPE AND MODEL) air Temperature Degrees F. all sensors continuously Jellow Springs Instrument Sea Temperature - Degrees C activate a series of dials at six depths in Co. thermistor # 44030 on an instrument panel meters - 1, 10, 30, installed in cable ase analog data are obtained 60, 100, 150 embly. Readout is by pleviodically photo electrical analog indic graphing the panel, the data being stored on ating thermometer measure ment, Various range readouts are used with film. Pictures of the 10° and 20° spans. Readout dials are examined by manufactured by Burnett hand to digitize the Electronics to our bridge data. designes. Constant surrent regulated power supply in each indicator Knots converted to Belfast Model C rup Knots Wind Speed m/sec. in computer anemometer process. Wind Direction True direction, apparent wind directions Electrical indicating apparently to nearest 5, are combined in computer process, with magnetic volt meter, sensor vane driven potionater, degrees, from buoy headings and Belfast Inst. Co., Model C. which wind is blowing magnetic deviation to produck true wind directions .

B. SCIENTIFIC CONTENT

NAME OF DATA FIELD	REPORTING UNITS OR CODE	METHODS OF OBSERVATION AND " INSTRUMENTS USED (SPECIFY TYPE AND MODEL)	ANALYTICAL METHODS (Including modifications) And laboratory procedures	DATA PROCESSING TECHNIQUES WITH FILTERING AND AVERAGING
Buoy Heading	compase North			
Mooring Line Tension	arbetrary unite - very likely Kilograms	Specially constructed Braincon solicon gauge load cell.		Line tension in milliampe of electric current converted to kilograma by computer process.
	· · ·			

C. DATA FORMAT

This information is requested only for data transmitted on punched cards or magnetic tape. Have one of your data processing specialists furnish answers either on the form or by attaching equivalent readily available documentation. Identify the nature and meaning of all entries and explain any codes used.

 List the record types contained in your file transmittal (e.g., tape label record, master, detail, standard depth, etc.).

2. Describe briefly how your file is organized.

3-13. Self-explanatory.

14. Enter the field name as appropriate (e.g., header information, temperature, depth, salinity).

15. Enter starting position of the field.

16. Enter field length in number columns and unit of measurement (e.g., bit, byte, character, word) in unit column.

17. Enter attributes as expressed in the programming language specified in item 3 (e.g., "F 4.1," "BINARY FIXED (5.1)").

18. Describe field. If sort field, enter "SORT 1" for first, "SORT 2" for second, etc. If field is repeated, state number of times it is repeated.

C. DATA FORMAT

COMPLETE THIS SECTION FOR PUNCHED CARDS OR TAPE, MAGNETIC TAPE, OR DISC SUBMISSIONS.

I. LIST RECORD TYPES CONTAINED IN THE TRANSMITTAL OF YOUR FILE GIVE METHOD OF IDENTIFYING EACH RECORD TYPE

80 - character card imag Observed records, with t	e on tape. time increasing by the hour.						
Also end-of-file records.							
2. GIVE BRIEF DESCRIPTION OF FILE O	RGANIZATION						
	· · · · · · · · · · · · · · · · · · ·						
BY BUOY (OR STATION)	NVABER.						
There were five broys #'s 16,18,19,22,29, with the last (29) of somewhat revised data format.							
There is one listing, (a	r file) for each buoy.						
3. ATTRIBUTES AS EXPRESSED IN PL-I							
FORTR							
4. RESPONSIBLE COMPUTER SPECIALIST: NAME AND PHONE NUMBER							
ADDRESS							
COMPLETE THIS SECTION IF DATA ARE	ON MAGNETIC TAPE (NODC COPY)						
	9. LENGTH OF INTER- RECORD GAP (IF KNOWN) 3/4 INCH						
	IO. END OF FILE MARK						
	(Following card [] OCTAL 17						
6. NUMBER OF TRACKS SEVEN	of nines) 10000 360 Hex						
NINE	II. PASTE-ON-PAPER LABEL DESCRIPTION (INCLUDE ORIGINATOR NAME AND SOME LAY SPECIFICATIONS OF						
	DATA TYPE, VOLUME NUMBER)						
	DATA TYPE, VOLUME NUMBER) TAPE NO. T168929 by Originator (S.I.O.) NO. 2152 NODC Copy. Creation date 24th ang. 71						
8. DENSITY	NO. 2152 NODE Copy.						
200 BPI 1600 BPI	Creation date 24th any. 71						
556 BPI	IZ PHINICAL BLUER POINTH IN BITLES						
800 BPI	80 X 10 blocking factor 13. LENGTH OF BYTES IN BITS						
]	8						

15. POSITION FROM - I 17. ATTRIBUTES 14. FIELD NAME **I6. LENGTH** 18. USE AND MEANING MEASURED IN. NUMBER UNITS (e.g., bits, bytes "SIO" Bytes З 1 A3 (Originator ID) I2 Station (buoy)# 4 2 I2 2 year 6 I3 Day of Year 3 8 I4 Time (hr. min.) 4 11 F 2.0 2 air Temp. 15 6F3.1 18 Sea Temperature 17 at 1 M, 10M 30 M, 60 M, 100 M, and 150 M F 2.0 F 3.0 - (relative to buoy heading) F 3.0 - (compass, north) 2 wind Speed 35 " Direction 3 37 Buoy Heading 3 40 F2.0 mooring Line Tension 43 2 32 X (blanks) 32 45 IY 4 Sequence humber 77

FIELD NAME	15. POSITION FROM - 1 MEASURED	16. LENG	тн	17. ATTRIBUTES	18. USE AND MEANING
	leg, bits, bytes	NUMBER	UNITS		
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14. FIELD NAME	15. POSITION FROM - I MEASURED	16. LENG	тн	17. ATTRIBUTES	18. USE AND MEANING
	IN	NUMBER	UNITS		
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14. FIELD NAME	FROM - I	16. LENG		18. USE AND MEANING
	IN (e.g., bits, bytes	NUMBER	UNITS	
				· · ·
		.:		

ACCESSION NUMBER

71-1049

DATA DOCUMENTATION FORM

NATIONAL OCEANOGRAPHIC DATA CENTER RECORDS SECTION WASHINGTON, D. C. 20390

This form should accompany all data submissions to NODC. Section A, Originator Identification, must be completed when the data are submitted. It is highly desirable for NODC to also receive the remaining pertinent information at that time. This may be most easily accomplished by attaching reports, publications, or manuscripts which are readily available describing data collection, analysis, and format specifics. Readable, handwritten submissions are acceptable in all cases. All data shipments should be sent to the above address.

A.ORIGINATOR IDENTIFICATION

THIS SECTION MUST BE COMPLETED BY DONOR FOR ALL DATA TRANSMITTALS

I. NAME AND ADDRESS OF INSTITUTION, LABORATORY, OR ACTIVITY WITH WHICH SUBMITTED DATA ARE ASSOCIATED UNIVERS ITY OF CALIFORNIA								
-	SCRIPPS IN			-	1 CALOUX			
	P.D. BOX 10			OLEAN	06 KAPAJ			
· ·	LA JOLLA	•	LIFORNIA	t				
EXPEDITION, PROJECT, OR DATA WERE COLLECTED	EXPEDITION, PROJECT, OR PROGRAM DURING WHICH				BY ORIGINATOR	NTO		
NORTH PACIFIC BUG	of program			29				
("Geophysical m	("Geophysical measurements")							
4.PLATFORM NAME (S)	5. PLATFORM TYPE	• •	6. PLATFORM A	ND OPERATOR		TES		
SIO BUOY	(E.G., SHIP, BUOY		PLATFORM	OPERATOR	FROM: MOYDAY/YR	TO: MO DAY YR		
	BUOY ("PROTO"	τγρε")	V.S.	U.S.	Feb. 5, 67	June 22,69		
IF YES, WHEN CAN TH	& ARE DATA PROPRIETARY ?			II. PLEASE DARKEN ALL MARSDEN SQUARES IN WHICH ANY DATA CONTAINED IN YOUR SUBMISSION WERE COLLECTED. GENERAL AREA				
9. ARE DATA DECLARED NATIONAL PROGRAM (DNP) ? (ia, SHOULD THEY BE INCLUDED IN WORLD DATA CENTERS HOLDINGS FOR INTERNATIONAL EXCHANGE ?) NO YES PART (SPECIFY BELOW)		278	40° 140° 180° 140° 140 277 234 237 272 237 272 234 254 254 254 252 252 252 252 25	125° 105° 80° 45° 2233 70° 105° 72 2777 70° 72 101 101 105 101 105 101 101 101	8 (073108	40° 40° 100° 244 7 744 279 254 7 74 279 254 7 74 212 40 212 200 212 200 212 200 213 40° 214 100 214 100 214 200 214 200 217 200 207 207 207 207 207 207 207		
IQ PERSON TO WHOM INQUIR DATA SHOULD BE ADDR TELEPHONE NUMBER (A OTHER THAN IN ITEM-I Anthony M.	20° 341 331 43° 449 45° 555 100° 120° 1	071 016 071 016 312 315 772 337 478 423 446 439 536 331 536 331 536 531 536 531 572 547 60° 160° 160° 160°	1001 00 310 32 346 34 337 37 418 41 459 44 526 526 526 55 120° 100° 80°	001 (034, 5 300 335 1 336 371 (27 407 3 408 44.3 9 444 479 5 440 515 1 516 551	C027 C027 <th< td=""></th<>			

NODC-3167/49 (8-70)

B. SCIENTIFIC CONTENT

Include enough information concerning manner of observation, instrumentation, analysis, and data reduction routines to make them understandable to future users. Furnish the minimum documentation considered relevant to each data type. Documentation will be retained as a permanent part of the data and will be available to future users. Equivalent information already available may be substituted for this section of the form (i.e., publications, reports, and manuscripts describing observational and analytical methods). If you do not provide equivalent information by attachment, please complete the scientific content section in a manner similar to the one shown in the following example

EXAMPLE (HYPOTHETICAL INFORMATION)

NAME OF DATA FIELD	REPORTING UNITS OR CODE	METHODS OF OBSERVATION AND INSTRUMENTS USED (SPECIFY TYPE AND MODEL)	ANALYTICAL METHODS (INCLUDING MODIFICATIONS) AND LABORATORY PROCEDURES	DATA PROCESSING TECHNIQUES WITH FILTERING AND AVERAGING
Salinity	700	nansen bottles	Inductive salinometer (Hytech model 5 510)	(not applicable)
		STD Bishett-Berman Model 9006	N/A-	Values averaged over 5 meter intervale
Water color	Forel scale	Visual comparison with forel bottles	N/A	N/A-
Sediment singe	& units and percent by weight	Ewing corer	Standard sience. Carbonate fraction removed by acid Treatment	Same as "Sedimentary Pock Manual," Jolk '65

(SPACE IS PROVIDED ON THE FOLLOWING TWO PAGES FOR THIS INFORMATION)

		B. SCIENTIF	CONTENT	
NAME OF DATA FIELD	REPORTING UNITS OR CODE	METHODS OF OBSERVATION AND INSTRUMENTS USED (SPECIFY TYPE AND MODEL)	ANALYTICAL METHODS (INCLUDING MODIFICATIONS) AND LABORATORY PROCEDURES	DATA PROCESSING TECHNIQUES WITH FILTERING AND AVERAGING
air Temperature Buoy Heading Wind Direction Wind Speed Sea Temperature at seven depths - 1, 45,65, 85, 105, 125, 250 meters. Note: Moorring a is absent from	FOR IN FOR IN FIRST ORDER C THIS ON	FORMATION ON UN OF THESE TWO F THE DATA FIE VE BUOY STATION	DATA DOCUMENTION	ETC. REFER TO THE

B. SCIENTIFIC CONTENT

NAME OF DATA FIELD	REPORTING UNITS OR CODE	METHODS OF OBSERVATION AND INSTRUMENTS USED (SPECIFY TYPE AND MODEL)	ANALYTICAL METHODS (INCLUDING MODIFICATIONS) AND LABORATORY PROCEDURES	DATA PROCESSING TECHNIQUES WITH FILTERING AND AVERAGING
			· · ·	
	·			
			· ·	

C. DATA FORMAT

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 List the record types contained in your file transmittal (e.g., tape label record, master, detail, standard depth, etc.).

2. Describe briefly how your file is organized.

3-13. Self-explanatory.

14. Enter the field name as appropriate (e.g., header information, temperature, depth, salinity).

15. Enter starting position of the field.

16. Enter field length in number columns and unit of measurement (e.g., bit, byte, character, word) in unit column.

17. Enter attributes as expressed in the programming language specified in item 3 (e.g., "F 4.1," "BINARY FIXED (5.1)").

18. Describe field. If sort field, enter "SORT 1" for first, "SORT 2" for second, etc. If field is repeated, state number of times it is repeated.

C. DATA FORMAT [SEE FIRST DDF]

COMPLETE THIS SECTION FOR PUNCHED CARDS OR TAPE, MAGNETIC TAPE, OR DISC SUBMISSIONS.

I. LIST RECORD TYPES CONTAINED IN THE TRANSMITTAL OF YOUR FILE GIVE METHOD OF IDENTIFYING EACH RECORD TYPE

2. GIVE BRIEF DESCRIPTION OF FILE ORGANIZATION

3. ATTRIBUTES A			
	AND PHONE NU		
ADDR	IE35		
	THIS SECTION I	F DATA ARE	ON MAGNETIC TAPE
5. RECORDING MODE	🗌 вср		9. LENGTH OF INTER~ RECORD GAP (IF KNOWN) 3/4 INCH
			IO. END OF FILE MARK
6. NUMBER OF TRACH			
(CHANNELS)			II. PASTE-ON-PAPER LABEL DESCRIPTION (INCLUDE ORIGINATOR NAME AND SOME LAY SPECIFICATIONS OF DATA TYPE, VOLUME NUMBER)
7. PARITY			
8. DENSITY	200 BPI	1600 BPI	
	🔲 556 BPI	,	12. PHYSICAL BLOCK LENGTH IN BYTES
	800 BPI		13. LENGTH OF BYTES IN BITS
1	Lil		

RECORD FORMAT DESCRIPTION RECORD NAME Observed Record

14. FIELD NAME	FROM - I MEASURED	16. LENG	тн	17. ATTRIBUTES	NB. USE AND MEANING
	IN (e.g., bits, bytes	NUMBER	UNITS		
"SIO"	1	ς	Bytes	A3	
(Originator ID Station (buoy) #	4	2		I2	
Year	6	2		IZ.	
Day of year	8	3		I3	
Hour and minute	11	4		I 4	
him Temperature	15	2		F2.0	
Buoy Heading	17	3		F3.0	
wind Darection	20.	3.		F 3.0	
" Speed	23	2	Ň	F 2.0	
a Temperature at IM, 45 M,	25	21		7 F3.1	·
65M, 85M, 105M, 125M,				•	
and 250 M.					
blanks	46	31		31×	
Seguence Number	77	4	ļ	エ サ	
		i			

14. FIELD NAME	15. POSITION FROM - I MEASURED	16. LENGTH		ļ	18. USE AND MEANING
	(e.g., bits, bytes	NUMBER	UNITS		
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RECORD FORMAT DESCRIPTION

14. FIELD NAME	15. POSITION FROM - 1 MEASURED	IG. LENG	тн	18. USE AND MEANING
	(e.g., bits, bytes	NUMBER	UNITS	
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RECORD FORMAT DESCRIPTION

RECORD NAME _____

4. FIELD NAME	15. POSITION FROM - I MEASURED	16. LE.NG	TH	I7. ATTRIBUTES	18. USE AND MEANING
	IN (e.g., bits, bytes)	NUMBER	UNITS	1	
			I.		
		ļ			
		ļ	}		

75-05 30 Date: 2/10/75 ID#: ORIGINATOR'S TAPE Assigned NODC #8244 NORPAX DATA DOCUMENTATION FORM DOF A: 4:06 PNSIBLE COMPUTER SPECIALIST: RONTA MORE Institution: 510 Physical Location of Data: NORPHY KLDG. BRIEF DESCRIPTION OF DATA (include area and time of coverage, frequency of cbs., original source of raw data) BUMBLE BEE BUOY DATA, CONVERTED TO ENGR UNITS INITIAL BUDYS 16,18,19,22,29,30- MAY/1964-FEB/1967 REGULAR BUDYS 34-59-FEB/1968-1973_ 10BS/ HR EXCEPT PORTION OF BUOY 40146 (FILES 11 & 19)-EVERY 6 MIN. LABEL FACSIMILE SHADE IN GENERAL AREA OF COVERAGE BUMBLE BEE BUOK 7 753 784 Con Rom CONVERTED DATA TARE the €|217|252/ (ARCHINE, WORKING &NODE (3) A (5) 124 135 075 File Name D 077 631 376 I 315 310 Generated Under 1151 346 341 336 371 107 342 S 397 1117 38.2 377 372 407 403 171 Account Number --Ж 439 434 154 475 444 479 400 С Card - Tray(s) 480 515 sn| [485] Card - Box(es) 521 516 551 \$76 Card - Drawer(s) 552 587 Recording Mode: BCD / EBCDIC / BINARY / ASCII / ____ Number of Tracks (Channels): SEVEN / NINE Т Density: 200 / 556 / 800 / 1600 bpi / ____ Α P ODD / EVEN Parity: E Blocked Data: NO / YES 50 LOGICAL RECORDS / PHYSICAL RECORDS S Physical Record Length in Bytes (characters): 4000 where the byte (character) is 3 bits YO CHAR/LOGICAL RELOKO Labeled Files: <u>NO</u> / YES - describe_ BRIEF DESCRIPTION OF FILE ORGANIZATION Number of files 42Approximate number physical records per file (if known) Variable EDF BETWEEN CRUISES & BETWEEN BUDYS, 12 EDF'S AT EOT HOW IS DATA SORTED / SEQUENCED? BUOY (16-59) BY CRUISE, BY DATE, BY HOUR IF NORPAX GENERATED DATA: Date created 219/75 by program TPTOM (SPECIPLE

FILES 8-28,30-42 BUDYS 38-49,51-39

LOGICAL RECORD FORMAT DESCRIPTION

LD	POSITION	FIELD		ATTRIBUTES	USE and MEANING
ID	from start	LENG		ATTRIBUTES	
	of record				
	measured				
	in CHAR				
	(e.g.bits,				
(e.g. temp.)	bytes,char., col.)	No.	Units	(e.g. F4.1)	Include datum (if used) and other data processing techniques
		·	Units		
ID.		3	CHAR	A3	"SIO"
STA, NO.	4	d.	OI GITS	12	No of BUOY
YR.	6	2	τ _ρ	I2	Last Two DIGITS OF YR 621
DAY	8	3	DAYS	I3 ·	JULIAN DATE 1-365
TIME	11	4	NKS.	I.I	GMT TIME OF OBS.
1 M.SEA	15	3	0c	F3.1	SEA TEMP. (C) AT IM, DEP
5m	18	3	- 4	<i>ii</i>	12 1 1 1 5 m 1
10	21	(v)	11	11	10 m
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	27	3		6	······································
75	30	3	•,	t.	3 3 3 75
100	33	3	· , ·		601
150	36	3	<i>U</i> .		AN AN 150 A
300	39	B	"	- N	1 · · · · · · · · · · · · · · · · · · ·
AIR	42	ŝ,	11 1	· · ·	AIR TEMPERATURE
HOG.	45	3	DEG.	F3.0	COMPRESS HOG, FROM TRUCK
W. DIR	48	.3		F3.0	WIND PRECTIONS :
W.SPD	51	2	m/s.	1	$w_{1}NOSOD.$
BAS. F.	5.3	2/37	mB.	L 1 - 1	BAR. PRESSURE
150 m. P.	57	3	08.	F3.0	150 M. DEPTH PRESS
300m. P.	60	3		F3.0	FILE 30, BODY SI- "HOT. WIRE HNEM. BOOM. DEPTH PRESSURE
MOUR.T.	63	.4	KE-	Fel. O	MODE 1115 5 44 100 FILLS 35-42 BUDYS 5559- 110T WIRE 13-65
SOLAR	67	· el·	Gon-Coto	F4.1 2	SOLAR RADIATION
W. TRANS	71	4	Km.	F4.0	WIND TRANSPORT
6.1.1.G	75	Z	°C:	F3:1	Im. LAG
. Lotter	78	3	- C	F3.1	Sm. LAG
NORPAX Da	ta Managemer	المسلما			`

NORPAX Data Management RTW:db 9/72 S FILES 1,2 BUDYS 16,18,19,22 LOGICAL RECORD FORMAT DESCRIPTION

LD	POSITION	FIELD		ATTRIBUTES	USE and MEANING
NAME	from start	LENG	TH	}	
	of record measured				
	in <u>CLA</u> R			. .	
	(e.g.bits,				
(e.g.	bytes, char.,		<u></u>		Include datum (if used) and other
temp.)	col.)	No.	Units	(e.g. F4.1)	data processing techniques
1.0.	· · / · · · · ·	3	CHAR	P3	"STO"
STA.NO.	4	2	DIEIT	N I 2	NO. OF BUOY
YR.	6	2	11	I2	LAST 2 DIGITS OF YR CO
DAY	8	3	DAYS	Z3	JULIAN DATE 1-365
TIME	11	4	LIKS	I4	GMT TIME OF OBS.
AIR T.	15	2	۰F	F2.0	AIR TEMP (°F)
l m SEA. IDm "	17	5	°C	F3.1 F3.1	SEA TEMP (°C) AT I.M. DEPT.
30 m "	20 23	w) ~) <) <)	4	F3.1	30
60 m "	26	3	4	F.3.1	60
Per "	29	(2) (2)	1	F3.1	100
Den "	32			F3.1	150
Wispo. N. Dir.	35	2 2	K	F2.0	WIND SED. (K) WIND DIRECTION (FROM TRUE)
LOG	37 40	33	DEG	F3. 0 F3. 0	ComPASS NOG. (° FROM TRUE N)
LINE T.	43	2	KG	F.2.0	MODR. LINE TENSION (KG)
BLANK	45	32	15	32X	BLAWK
1.0.	77	- 4	DIGITS	I4	10 NO.
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FILES 3,4,5 BUDYS 29,30 LOGICAL RECORD FORMAT DESCRIPTION

LD	POSITION	FIELD	ATTRIBUTES	USE and MEANING
NAME	from start	LENGTH		
	of record			
•	measured			
	in CLAR			· · ·
	(e.g.bits,			
(e.g.	bytes, char.,		-	Include datum (if used) and other
temp.)	col.)	1 1	(e.g. F4.1)	data processing techniques
ID.			A3	"SIO"
STA NO.	4	2 21417	II2	No. OF BUDY
IR	6	2	IZ2	LAST 2 DIGITS OF YR QQ
		ł		
DAY	8	3 DAVS	IJ3	JULIAN DATE 1-365
TIME		4 LIRS		GMT TIME OF OBS.
	11			
HIRT.	15	2 0F	F2.0	AIR TEMP (°F)
HDG	17	3 DEG	F3.0	Compass HOO (FROM TRUCK
	17			
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SCRIPPS INSTITUTION OF OCEANOGRAPHY 12 February 1975 POST OFFICE BOX 1529 LA JOLLA, CALIFORNIA 92037

Mr. Nelson Ross NODC Liaison Officer National Marine Fisheries Service P.O. Box 271 La Jolla, California 92037

Dear Nelson:

Enclosed is a tape of all data that we processed from our bumblebee buoy platforms. These data are contained on one 9 track, 1600 bpi magnetic tape. Included with the tape is a listing of the first record of each file and a complete set of documentation which provides detailed information as to the technical characteristics of the tape as well as logical record format. With this documentation and the copy of the tape, it should be possible for any reasonable computer programmer to read and understand these data.

I trust that you will send this on to the proper office at NODC for permanent retention as the national record of this scientific data from this series of platforms. If the people in Washington have any questions concerning the technical nature of this data set, please let them call me directly at 714/452-4495.

Thank you for your help on this matter.

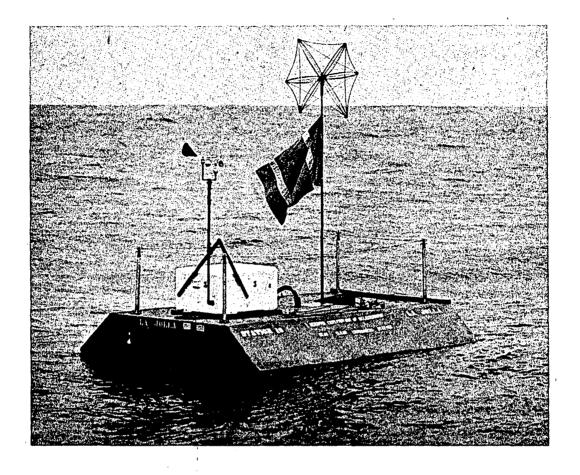
Sincerely yours,

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Richard T. Wert NORPAX Data Manager

- cc: Dr. James J. O'Brien Code 481 Office of Naval Research, Marlington, Virginia 22217
- cc: Dr. Curtis A. Collins IDOE - NSF, Washington DC 20550

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DEVELOPMENT AND TESTING OF TAUT-NYLON MOORED INSTRUMENT STATIONS

(WITH DETAILS OF DESIGN AND CONSTRUCTION)

Scripps Institution of Oceanography University of California at San Diego

SIO Reference 65-5

April 15, 1965

UNIVERSITY OF CALIFORNIA, SAN DIEGO SCRIPPS INSTITUTION OF OCEANOGRAPHY

DEVELOPMENT AND TESTING OF TAUT-NYLON MOORED INSTRUMENT STATIONS (WITH DETAILS OF DESIGN AND CONSTRUCTION)

John D. Isaacs, George B. Schick, Meredith H. Sessions and Richard A. Schwartzlose

This research has been supported by the Office of Naval Research, Bureau of Commercial Fisheries and Marine Life Research Program of The University of California.

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SIO Reference 65-5 April 15, 1965

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TABLE OF CONTENTS

Abstract \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots	1
Background of the problem	1
Background of mooring	2
Developmental testing	3
Results	8
Present and future plans	17
Conclusions	18
Acknowledgements	19
Appendix	29
Construction	29
Installation	35
Service instructions	41
Major service	43
Detailed drawings	44
Parts list for moored instrument station	83

LIST OF FIGURES

1.	October 1957 anomaly of sea surface temperature	2
2.	Taut-nylon deep-water mooring system	4
3.	Body of a shark found entangled in an instrumented mooring cable	
	170 feet below the surface on 23 August 1961 near Monterey Bay,	
	California	9
4.	Reproduction of a data frame	11
5.	Sample of computer plotted data	13
6.	Instrument panel	30 [.]
7.	Overhead view of instrument box	30
8.	Instrument line construction	31
9.	Thermistor boot assembly	32
10.	Instrument line and strength member termination	33
11a.	Load vs elongation for nylon	36
115.	Load vs elongation for nylon	37
12.	Arranging of equipment prior to launching float ••••••••••••••••••••••••••••••••••••	38
13.	Final assembly of mooring components	38
14.	Launching of the catamaran float	39
15.	Laying of the instrument cable	39
16.	Spooling out the nylon mooring line	40
17.	Launching anchor assembly	40
18.	Exchange of instrument box batteries	42
19.	Film exchange	42

DEVELOPMENT AND TESTING OF TAUT-NYLON MOORED INSTRUMENT STATIONS

John D. Isaacs, George B. Schick, Meredith H. Sessions, and Richard A. Schwartzlose

Abstract

One of the persistent problems of oceanography is to ascertain the nature and cause of large-scale shifts in the surface water masses of the oceans. The existence of such changes are readily apparent from vessel measurements. However, the nature of the motions involved cannot be documented by any feasible ship survey. It probably can best be documented by an array of continuous recording instrument stations.

For this and other purposes deep-moored instrument stations have been designed that record meteorological data and oceanographic data in the upper few hundred meters. Twenty installations of evolving designs of the taut-nylon mooring have been tested over a period of 3-1/2 years.

The approach has resulted in an increasing reliability and life of the installations and recent designs have a useful life of at least six months when moored in the deep open sea and much longer in deep sheltered areas. Developments and results of tests are discussed. Complete construction drawings with notes on construction, installation, and servicing are included.

Background of the Problem

The existence of large-scale shifts in the water masses of the oceans are well known. Perhaps the most celebrated of such shifts is the El Nino of the Peruvian coasts. Similarly abrupt shifts, however, appear to occur in all of the major boundary currents of the oceans and greatly affect the biota, fisheries, weather, underwater sound propagation, and other conditions. Shifts in the California Current System are well documented, and there appear to have been even greater shifts in the recent past in this system than observed in the last few decades. The existence of such anomalies is readily apparent from the data from coastal stations, survey vessels, and surface ships. See Figure 1, for example, where abnormally warm water (6° to 8° above normal) occurred in the Gulf of Alaska in the fall of 1957 (Mc Gary, 1960). Data from such discontinuous very shallow surface coverage, however, does not yield much insight into the nature of the exitation or water motion that gives rise to the anomalous distribution. For example, they cannot settle the question of whether these changes are progressive, wave-like instabilities of the boundary currents, floods of surface water from baroclinic transients, or the result of increases or decreases of mixing, transport or insolation.

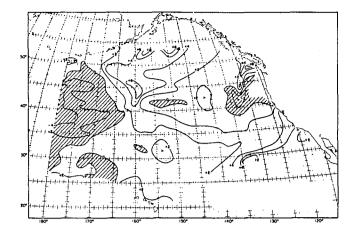


FIGURE 1. October 11-20, 1957. Anomaly of sea surface temperature (°F) from 30-year mean charts of H.O. 225. Hatched areas colder than average.

In addition there is the much more demanding problem of explaining teleconnection, that is, the apparent relationship of the changes that take place in widely separated parts of the Pacific Basin.

Insight into these and other questions of oceanography, meteorology, fisheries, and climatology require a spacial array of almost continuous long-term measurements of temperature through the mixed layers and associated other data (e.g., meteorological data) and extending well across the principal boundary currents of a current system and in the central water masses at a number of sections.

For the purpose of obtaining instrumentation to accomplish this, a deep-moored instrument system has been developed.

Background of Mooring

The development of deep moorings has continued at Scripps Institution of Oceanography since the early 1950's. Early work was with moorings of the taut-wire type, designed to gather surface data. This type of mooring consisted of a taut mooring wire supported by a subsurface float to which the surface float was attached by a slack pennant. The taut-wire mooring was successful for surviving sea surface conditions and for collecting surface data but many problems were encountered in attempts to use this type of mooring for measurements much below the surface. These problems included the fouling and cutting of slack buoyant pennants by ships, fish entanglement, uncertainty regarding the true depth of the measurements taken along the slack pennant, etc. Also theft and "helpful" recovery of the boat-type surface float and the instruments was a continuous problem (Isaacs, <u>et. al.</u>, 1963). The taut-nylon mooring concept was developed to overcome the disadvantages of the earlier moorings. Some considerations that went into the adoption of the taut-nylon mooring and platform were:

- 1. It allows the installation to be small and light enough to be installed from small ships without special equipment.
- 2. A taut vertical mooring line keeps station well in all but high currents, can be instrumented to any depth, can protect the surface float from theft, and eliminates the problem of surface pennants being fouled or cut by a ship's screw.
- 3. Nylon lines do not corrode and are elastic.
- 4. The float can be large enough to accommodate necessary instrumentation.
- 5. It is unattractive to thieves and theft resistant.
- 6. It is rugged and unsinkable.
- 7. It is large enough and is sufficiently stable to permit boarding for servicing at sea.

Developmental Testing

The first attempt at mooring a platform with a taut-nylon line was carried out on 27 June 1961 when a 16-foot Fiberglass skiff was anchored 13 miles from Point Loma. Mooring depth was 657 fathoms and line tension was 300 pounds as read by a dynamometer installed in the line. The skiff was last checked on 10 July 1961, but on 17 July 1961 it was missed on the routine check. The hatch cover for this skiff was found adrift 25 miles west of San Diego on 18 July 1961. Due to the large amount of shipping in this area, it was concluded that the skiff had been stolen or had been sunk by a large ship.

This mooring was designed to demonstrate the feasibility of using a taut-nylon mooring line from the anchor to the surface, and, although shortlived, was a departure from the mooring techniques that were then current. The length of the mooring line had been about 10 percent less than the depth to achieve 300 pounds of tension when installed.

The first taut-nylon catamaran mooring was installed on 13 October 1961 at 32° 54.8' N, 117° 21.8' W (6 miles west of Scripps Pier). This mooring was a result of considerable redesign of the platform and fittings. The instrumentation was housed in a box and mounted on the open deck of the catamaran-type float. The box was sealed and self-contained with only sensing input leads entering the box. Both the platform and instrument package represented a number of major improvements (Fig. 2).

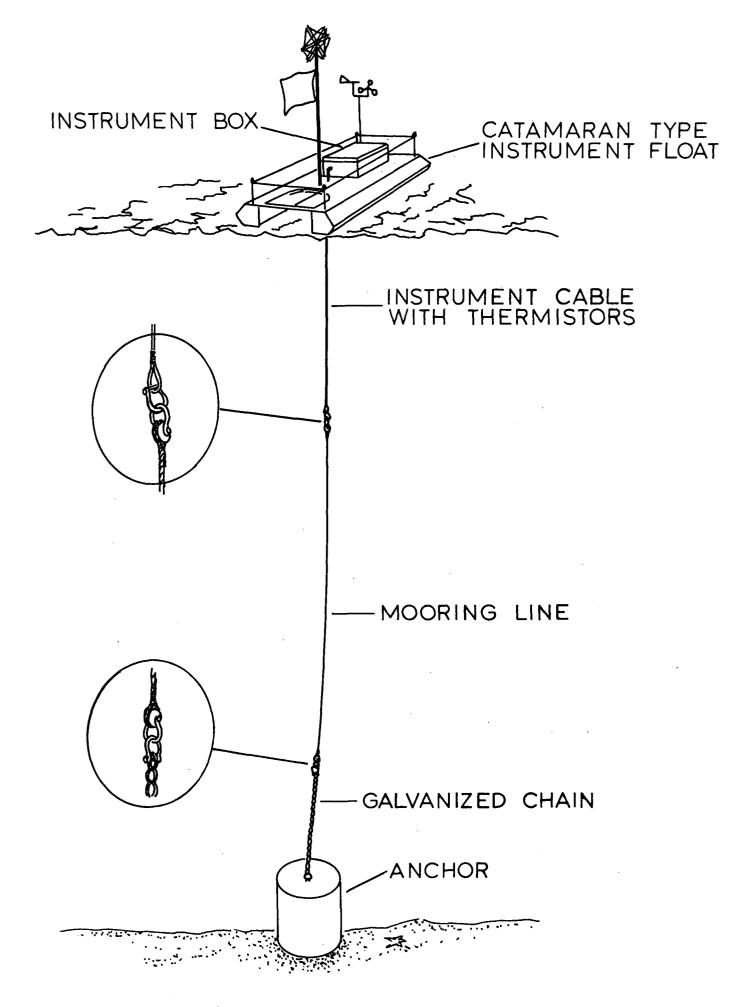


Figure 2. Taut-nylon catamaran mooring.

The installation operated well for almost 5 months until the recording control circuit malfunctioned. About the same time the instrument line failed, so the unit was left as a life test of the mooring components. After surviving 15 months, this mooring was eventually recovered intact as a test of recovery techniques and for component inspection and evaluation. 60

The installation of the second taut-nylon mooring with a catamaran float took place on 6 January 1962. This station was located near the first catamaran mooring. It was instrumented to measure wind speed and direction, 6 sea temperatures from the surface to 150 meters, depth of the bottom of the instrument line, and platform heading, all recorded photographically. This unit was installed to test the instrumentation of the taut-nylon mooring line. The instrument line was constructed by winding electrical conductors around a nylon strength member. With great difficulty a length of garden hose was pulled over the assembled line. The instrument line depended on the hose for its water-tight integrity; however, when installed, the nylon stretched, broke the hose and flooded the cable. After the instrument line failure, it was decided to attempt recovery of the entire mooring using a newly developed chain hook. This was attempted on 7 March 1962, but was not completely successful. However, the complete instrument line and bottom fitting containing the pressure transducer were recovered. The catamaran and instrument box were returned to the laboratory for repair and fitting out to be used again for another installation.

A third catamaran mooring with instrument box identical to the previouslydescribed unit except for minor modifications was constructed to test another type of instrument line. This line consisted of a 150-meter nylon strength member with amergraph hook-up wire spiralled around it in the form of a helix. Water-tight integrity was maintained at each individual conductor, the only covering being a tape to keep the conductors in place. This mooring took place 4 April 1962, in the area 6 miles off La Jolla, used in our previous tests.

One particular note of interest regarding this installation was the method used to attach the instrument line from the surface of the water to the instrument box. A large cable was made of the 15-conductors and a heavy-wall tygon tube was placed over the conductors. A large rubber stopper was drilled out and placed in the deck and the tygon cable was brought through the cork. A cannon MS series plug was attached to the conductors and was sealed in the end of the tygon which was placed in a large radius bend from the deck to the box in which it was plugged.

The instrument box from this station was brought back to the laboratory 19 July 1962 due to batteries leaking inside the box and expelling liquid. Checkout of the instrument line after removal showed all thermistor connections in good condition.

The surface float was exchanged 22 May 1963 to test the feasibility of such a transfer. The installation showed no sign of wear or chafing. The mooring is still intact at this time, 34 months after installation.

- 5

On 17 May 1962 catamaran station #4 was installed near the previous mooring off La Jolla. This installation used the instrument box and catamaran that were recovered and repaired from our station number #2.

The instrument line used on this station was of different design than any previous units. A 1/4-inch stainless steel cable was used as a strength member with amergraph hook-up wire taped to it. The primary purpose of this installation was to test a massive rigid instrument line in preparation to ordering a commercially manufactured unit from Marsh and Marine Manufacturing Company.

The only change was the use of Mecca Cable Company boots instead of vulcanized Joy connectors at the thermistor connections and an epoxy potted model #304 Bourns pressure transducer. When installed all instrumentation operated properly. On 20 July 1962 a check of the station revealed the pressure transducer reading was in error. A further check showed the surface instrumentation operating properly, so it was concluded that leakage of sea water may have occurred at the transducer connections.

This station broke loose and was recovered off Del Mar 21 August 1962 and later installed as station #7 off Point Sur.

Moorings #5 and #6 were to be the first rough-water test installations near Davidson Seamount and Point Sur respectively. They were also to test commercially manufactured instrument lines, fabricated by Marsh and Marine, and advances in instrumentation and packaging techniques. Station #5 was damaged during installation and never installed. Mooring #6 was installed 8 October 1962 in 2090 fathoms southwest of Davidson Seamount. Immediate check of the station after installation revealed numerous cable failures, evidently results of inadequacies in fabrication. It was serviced again on 14 October and appeared under high tension. It was not sighted on a return trip 3 November 1962 and was therefore given up as lost. A later Coast Guard sighting report indicates that it was still in position 26 April 1963 after 6-1/2 months.

Mooring #7 was installed off Point Sur 2 November 1962 in 660 fathoms to establish a winter mooring test. The mooring line and anchor had been prepared for mooring #5. The float and instrument line had been previously anchored as mooring #4 and had just broken loose. This station was serviced once in January 1963 and last sighted by passing vessel 30 April 1963 after 6 months.

Mooring #8 was a special mooring installed 30 March 1963 by the U. S. Coast Guard at ocean station November (30° N, 140° W) in 2260 fathoms. This float was anchored from a point at its center and had a 12-foot mast with a heavy radar reflector. It promptly capsized in heavy seas but was righted again by the Coast Guard. The float was exchanged for one with a shorter mast and a mooring point forward of the center. It performed well for 6-1/2 months, when it broke loose at a point 1285 feet below the surface.

Moorings #9 through #12 were the first standardized design of both moorings and instrumentation. This design represented many improvements in components and instrumentation. Commercially manufactured instrument cases were used for the first time as well as tautband, 250° meters. Many components previously constructed in-house were subcontracted out. These stations were anchored on 2 October 1963 along a line heading southwest from Point Conception. The purpose of these moorings was to establish a line of oceanographic stations in an area where previous data had frequently been collected by ship. Station #9 was found capsized on a routine service trip on 3 December 1963. The station was righted and the instrument box removed when it was found to have leaked slightly, presumably while capsized. Station #10 was not sighted on the same trip and assumed lost. Stations #11 and #12 were found to be in good working order. On subsequent service trips Station #11 was found capsized (9 January 1964 and 2 February 1964). Data recovered from Station #11 indicated that winds in excess of 50 knots occurred during December and January. The accompanying rough weather was concluded to be the cause of the floats capsizing. Station #9 was last seen on 18 December 1963. Station #11 was last sighted on 2 February 1964 and station #12 last sighted on 23 March 1964.

Due to the difficulty of maintaining frequent observations of stations very far from Scripps, it was decided to locate as many future test sites as possible, where they could be observed frequently and recovered if found adrift. We received approval to anchor stations at the Navy Picket Ship positions.

Station #13 was a reinstallation at the U. S. Coast Guard Weather Station November station. This mooring was to test a longer (450 meters) steel cable. The platform was anchored on 8 December 1963, but failed eight days later and was returned to Scripps.

An uninstrumented station #14 was established in cooperation with the U.³S. Coast Guard on 10 February 1964 at Ocean Station Victor (34° N, 164° E). This station capsized in very heavy seas on 12 February 1964 and was last sighted while still capsized on 15 February 1964.

Station #15 was the third mooring installed at U. S. Coast Guard Station November. This was an uninstrumented mooring with the nylon mooring line continuing to the surface. It was installed on 21 February 1964. The mooring was terminated on 12 March 1964 when the nylon line parted 60 feet below the surface.

Most observations indicate that the catamaran floats tend to capsize over the side. They apparently broach in heavy weather and overturn due to a combination of aerodynamic lift, a disorienting wave induced acceleration, and wind disorientation in the lee of an approaching comber because of the sheltering effect. This experience led to the addition of the ballast tanks to the catamaran float to prevent capsizing in heavy seas. The ballast tanks flood freely through small vents and capture a substantial volume of both air and water. This provides two beneficial effects. In a capsizal situation, as the float begins to lift one hull, the volume of water captured in the lifting hull increases the apparent weight of that hull and the moment arm of that hull as well, while the other hull sees an increase in apparent buoyancy and its moment arm due to the entrapped air. The overall effect of the ballast tanks then is to increase the capsizal resisting moment by more than a factor of three. Our recent recorded data in trade wind areas shows that the floats generally head into the wind, especially at higher wind velocities.

A new aluminum instrument box was designed with welded fittings to minimize possibility of water leakage into the box. Interchangeable plug-in mast assemblies were designed with electronic flash beacon lights. An all solid state electronic control system and commercially manufactured clock timers replaced the motor-drive cam assemblies. Internal modifications were made to the camera to improve reliability. The size of the nylon mooring line was increased from 3/8-inch to 7/16-inch diameter to provide a greater safety factor in case of chafing or animal attack on the mooring line. With these changes, 5 stations numbered #16 through #20 were installed in May 1964 and one in June (see Table 1 for details). It should be noted that, although these latter stations were under frequent surveillance care was exercised not to vitiate the conditions of a test of <u>unmanned</u> stations. No repairs were made.

<u>Results</u>

Over the last 3-1/2 years of the development of the taut-nylon moorings the life of installation and reliability of the instrument lines and instrumentation has greatly increased. The most recent tests have demonstrated that a sufficient number of moorings will survive approximately 6 months to make it possible to use moorings to document the shifts of water masses and boundary currents. The considerations that went into the mooring system appear to have been met. The moorings are small enough to be installed from a small ship without special equipment, yet large enough to accommodate the necessary instrumentation. They have proved theft resistant and stable under various sea and wind conditions.

The cause of some failures of the mooring lines is still unknown. All the moorings that were recovered after breaking loose failed by parting of the nylon line except no. #19. Several samples of the nylon line were sent to the manufacturer for analysis of the breaks. Their review showed no deterioration of the nylon but they could not determine the cause of the breaks. In three cases (#4, #13, #20) the nylon lines parted less than 50 feet below the bottom of the instrument line. In one event (#15) where there was no instrument line and the nylon extended from the surface to the anchor, the line broke at 60 feet below the surface. In another mooring (#8) the line parted 785 feet below the bottom of the instrument cable (1285 ft. from the surface). Essentially all the known line failures have occurred very near the upper end of the nylon mooring line. It is the area where a large discontinuity in mass and elasticity occurs between the steel cable instrument line and the nylon mooring line. It is thus possible that the vertical wave-induced oscillations of the lower end of the instrument line could produce large local strains in the upper end of the nylon mooring line where the discontinuity and reflection exists. If this were occurring the breaks would be expected in the upper end of the nylon as observed.

In the areas nearest the bottom end of the instrument line marine animal attacks would be expected to be more numerous than at greater depths. There is no evidence of the recent failures having been caused by marine animal attacks. In a mooring using the taut-wire subsurface float and pennant to the surface design, a shark became entangled in the pennant line (Fig. 3), and in earlier work a broken shark's tooth was imbedded near the end of a parted pennant. Woods Hole Oceanographic Institution, in their report on mooring performance, have evidence of cuts

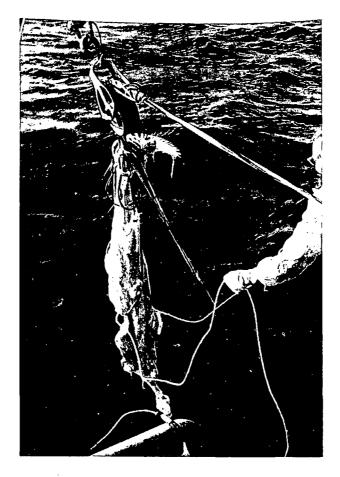


Figure 3. Shark which became entangled in an instrument line 170 feet below the surface.

in parted mooring lines that may be fish bites (Stimson, 1964). From only one of our recovered instrument lines (#18) is there clear evidence that it might have been attacked by marine animals. It had numerous razorlike slashes along its length to a depth of 200 feet. At the 200 foot mark there were several rips in the taped jacket and the electrical conductors. It is possible that a pelagic tuna long line could have caused this damage, but a marine animal attack is probable.

In order to protect the upper end of the nylon line from animal attack, and to secure condlusive evidence such as tooth imprints, a piece of polyethylene pipe 400 feet in length was placed over the nylon line of mooring #22. The pipe was attached just below the thimble at the upper end of the nylon, covering the area where most of the known failures have occurred. This mooring is still in place at the present time so that results of the test will have to await further development.

There has been only one known mechanical failure (#19). It occurred at the hydraulic shackle assembly. It appeared to be a problem of wear on the stainless stell threads and redesign of this piece may be necessary.

Performance of all taut-nylon catamaran moorings installed by Scripps is shown in Table 2. The "number of days moored" for each station is the minimum time each station remained installed. In cases where the mooring was not recovered it was assumed that the failure occurred on the day when the mooring was last sighted. It is evident that moorings located in sheltered areas may last for long periods of time but are not indicative of open-sea performance. The group of moorings numbers #16 through #22 were of later design with ballast tanks and larger diameter mooring line. This group shows a greater than 50-percent increase in mooring duration when compared to a similar open-sea group of earlier design. The moorings have withstood winds in excess of 50 knots and seas in excess of 25-foot.

Performance of the instrumentation on this latter group of moorings (#16 through #22) also was far superior to the preceeding stations. There were no failures in the instruments or cables for six months of installation. Shortly after the sixth month a number of indicator-battery failures were noted. This was somewhat sooner than expected but can easily be corrected.

There have been approximately 750 station days of data collected from the last 6 installations. Every station day of data contains 24 readings at hourly intervals, and each reading consisting of 12 parameters (Fig. 4). To date the readings total slightly less than one quarter of a million. This data film has been processed and is being punched on IBM cards as it is read. From the card form the data can be converted to IBM magnetic tape for computer analysis. A sample of the data obtained from a typical station, which has been computer-processed and plotted, is shown in Figure 5. From our experience it takes approximately 0.33 man hours per station day of data to read and punch these data on IBM cards.

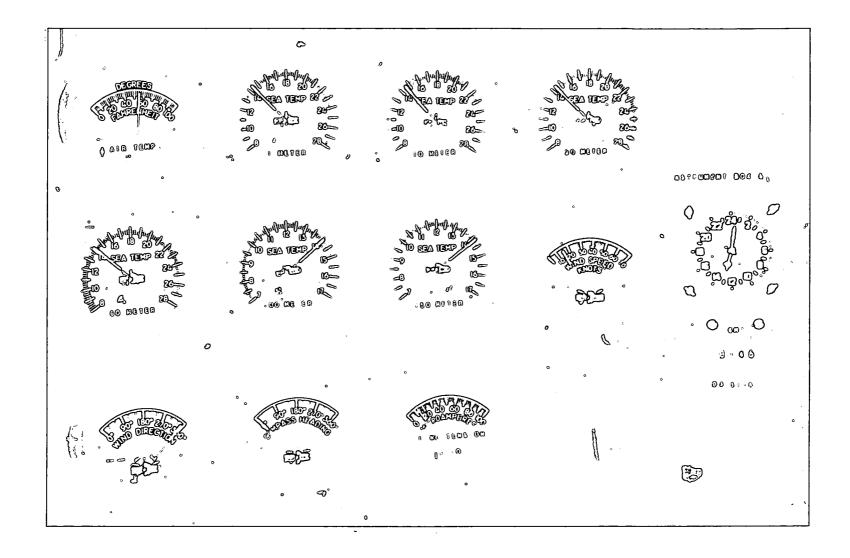


Figure 4. Reproduction of a data frame.

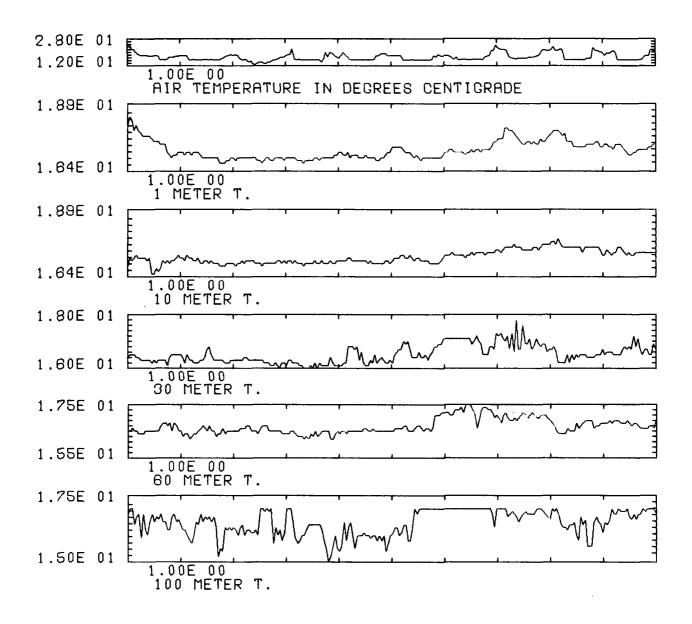


Figure 5. Sample of computer-plotted data for 10 days from Station 19. Data begins at 2157 GMT, 20 May, 1964. Spacing on the horizontal axis represents 1 day. There are 24 observations plotted each day. Temperature values are in centigrade at the depths indicated. The values on the vertical axis represent the scale (2.80E 01 means 28.0°C). Due to the programed method of plotting the areas of straight lines can result from off-scale instruments, missing data or no change in the values. This was a first attempt at computer plotting to learn the problems and to see the rough plotted data. (A continuous 3913-hour record has now been plotted from this station.)

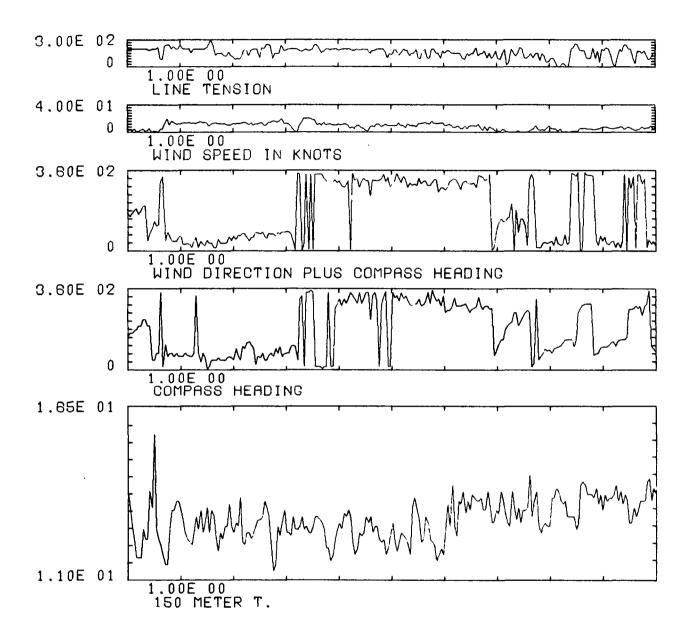


Figure 5 (cont.). Remainder of data from sample of computer plot from Station 19. Data begins at 2157 GMT, 20 May, 1964. Line tension values are in pounds (0-300 lbs.). Wind direction plus compass heading means true wind direction. Compass heading means the true heading of the platform.

The total cost of the mooring and instrumentation is approximately \$6,000. Operational cost of a station is low. Film and batteries are inexpensive and need replacement at intervals of 3 months if hourly records are made. The power requirements of the system are extremely low (12 milliwatts average power). The film magazine capacity of the camera is 50 feet. At the rate of one frame per hour the unattended endurance of the station is 83 days. By recording data every 2 hours or 4 hours the time between servicing can be double or quadrupled since it is the film storage rather than the power requirement that is the limiting factor.

Present and Future Plans

The present and future plans are centered around the instrumentation. A digital data gathering unit has been purchased from Berkeley Instruments. The data gathering unit consists of a group of sensors, the data conversion chassis and a paper tape punch. The unit is designed to sense 10 sea water temperatures (thermistors), air temperature, wind speed, wind direction (relative to magnetic north), and barometric pressure. In addition to these parameters a two digit identification number and time are recorded. The data unit is small (approximately 2.5 cubic feet) and light (25-30 lbs.) and consumes a small amount of electrical power (6 watts average during operating cycle). All electronic circuitry is solid state and operates from a 12 volt D.C. supply.

The analog signals sensed by the transducers are converted in the data unit to a standard five-level teletype code. In this form the data will be recorded on site by a paper tape punch. The output from the data unit will also key a relay for radio telemetry. The data recorded on paper tape can be converted to IBM cards and then to IBM magnetic tape for use on any computer.

The data unit is designed for use with radio telemetry of data in standard teletype format. A 500 and 700 cycles per second audio frequency will represent the mark and space respectively. These tones will be transmitted via single side band transmitter on the buoy.

This type of transmission is compatible with present facilities at radio station WWD and with future installations on Scripps' ships. The shipboard teletype installation will provide direct data output without conversion for survey work.

The data unit has been operating in the laboratory on a teletype wire loop for two months. The data unit has been packaged with the telemetry system in a military packing case similar to the photo recording buoys. This unit will be installed on the end of Scripps pier for initial tests of the radio link. The transmitter is low power (2 watts). The system will then be used offshore on a mooring. After considerable testing with the lower powered radio link, longer range will be tested by the addition of a linear amplifier to the transmitter to increase the output to 30-50 watts.

In addition to the capability of transmitting interrogated on line data it is desirable to be able to store data for later transmission. For this purpose a magnetic tape recorder is most suitable. This unit will be added at a later date when the present system has been sufficiently tested.

<u>Conclusions</u>

The development of the taut-nylon catamaran mooring has resulted in a unit that can be used to measure surface meteorological conditions and ocean temperatures in depth and which can be moored in any water depth to 3000 fathoms and undoubtedly deeper. Installations can be made by small ships without special equipment in a minimum of one to two hours.

The recording system is simplified in its design as compared to most other electronic data recording and storage devices. This system will allow any sensor with either digital or analog output to be visually displayed so that failures are obvious in an inspection.

The latest tests in deep water and in the open sea indicate that most of the moorings last at least 6 months before the mooring line fails and that the instruments will operate as long as the mooring is in place. In sheltered areas the moorings will last for years.

Thus it now is feasible to use these moorings in the open sea far from land to document large-scale shifts in the surface water masses of the oceans; to ascertain the nature of the time variation of a number of characteristics; to record internal waves; to gather data for inquiries that require many observations over long periods of time and from single or multiple locations, such as sea-air interaction; etc.

Acknowledgements

Research and development work on taut-nylon deep-moored instrument stations was undertaken at Scripps Institution of Oceanography, supported by the Office of Naval Research, Bureau of Commercial Fisheries and Marine Life Research Program of the University of California. Acknowledgement is made to the U. S. Coast Guard, Western Area and to the U. S. Navy Picket Squadron ONE for their assistance and participation on various test programs. Their observations and recovery of test moorings were of vital importance to the success of the test program. Acknowledgement is also made to Erich W. Duffrin, Phillip M. Marshall, Richard L. Shutts, Raymond Shuey, and John Martin for their assistance in carrying out this development and for their many contributions, and to Captain Frank Miller and the crew of the R/V Agassiz for their aid in mooring many of the test stations.

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TABLE 1

DATA FOR CATAMARAN MOORINGS

3 February, 1965

	Ø1	<i>₿2</i>	#3
DATE MOORED	October 13, 1961	January 6, 1962	April 4, 1962
LOCATION	32° 54.8'N, 117° 21.8'W	32° 54.8'N, 117° 21.8'W	32° 54.8'N, 117° 21.8'W
DEPTH	320 fathoms	320 fathoms	320 fathoms
TYPE OF MOORING LINE	3/8" nylon-white	3/8" nylon-white	3/8" nylon-white
<u>TYPE OF INSTRUMENT LINE</u>	None .	Hose instrument line 150 meters*. Nylon core with electrical conductors and garden hose covering.	Nylon instrument line with conductors spiraled around it and wrapped with tape.
INSTRUMENTATION	Hydraulic tension gauge.	6 sea temperatures, air temperature, wind speed and direction, depth of instrument line, camera recording.	6 sea temperature, air temperature, wind speed and direction, depth of instrument line (used Bourns gauge #734. Camera recording.
OORING SHIP	Baird	Paolina T	T-441
AST SIGHTED DATE	Removed November 28, 1962	Removed March 7, 1962	Still in service
ENGTH OF KNOWN TIME MOORED	406 days	61 days	
<u>HANGES AND REMARKS</u>	 Dec. 13, 1961. Added instrumentation: Data recorded on film: mooring line tension, wind speed and direction, mooring line angle, surface current measure- ment at 10 ft from sur- face, speed and direction. Transmitter put on to radio warning if tension was reduced substan- tially. Jan. 9, 1962. Replaced camera. Apr. 13, 1962. Removed instrumentation. Recording unit failed. 	 Instrument line failed on installation. Camera failed on in- stallation. January 9, 1962 re- placed camera. 	 Camera malfunction May 9, 1962 and camera re- placed. Removed instrument box July 19, 1962 (all sensors were working). Reinstalled instrument box July 24, 1962 (replaced several meters). Float was exchanged to test technique on May 22, 1963. Instrument box was not put on new float

* Ail instrument lines are 150 meters in length except as noted and the 6 sensors are at 1 m, 10 m, 30 m, 60 m, 100 m, and 150 m.

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DATA FOR CATAMARAN MOORINGS

3 February, 1965

	#4	#5	# 6
DATE MOORED	May 17, 1962		October 8, 1962
LOCATION	32° 54.8'N, 117° 21.8'W		35° 27'N, 123° 06.5'W
DEPTH	320 fathoms		2000+ fathoms
TYPE OF MOORING LINE	3/8" nylon-white		3/8" nylon-white
TYPE OF INSTRUMENT LINE	Stainless steel core (1/4″) conductors taped around core.		Marsh marine.
INSTRUMENTATION	6 sea temperature, air temperature, wind speed and direction, depth of instrument line. Current meter at sur- face. Camera recording.		6 sea temperature, air temperature, wind direction and speed, depth of instru- ment line, compass, hours per year counter. Camera recording.
MOORING SHIP	Paolina T		Agassiz
LAST_SIGHTED_DATE	Found adrift off Del Mar August 21, 1962.		April 26, 1963 reported by passing ship.
LENGTH OF KNOWN TIME MOORED	97 days		201 days
CHANGES AND REMARKS	 Remote reading compass in- stalled August 7, 1962. Moored near #3. Nylon broke 56 feet below instrument line. 	 Damaged October 7, 1962 during installation. 	 Retrieved film October 16, 1962. Was not seen by SIO ships after October 16, 1962.

	# 7	₽ 8	<i>4</i> 9
DATE MOORED	November 2, 1962	March 30, 1963	October 2, 1963
LOCATION	36° 05.9'N, 121° 55.2'W	30° N, 140° W	34° 19.4'N, 120° 48.2'W
DEPTH	660 fathoms	2260 fathoms	405 fathoms
TYPE OF MOORING LINE	3/8" nylon-white	3/8" nylon-gold line	3/8" nylon-gold line
TYPE OF INSTRUMENT LINE	Same line that was used on ∯4.	Stainless steel 1/4" strength member with Amerigraph hook-up wire taped to the cable, using Marsh Marine boots for thermister housing.	Same as ∉8.
<u>INSTRUMENTATION</u>	Same instrument box as used on #4. Installed Fenwale ruggedized meters. Same parameters measured.	6 sea temperatures, ten- sion recorder, sea temper- atures read on one meter with selector switch.	6 sea temperature, wind direction and speed, air temperature, compass, line tension, surface current aeromarine 270° meters, line depth. Camera recording.
MOORING SHIP	Smith	USCG Ponchartrain	Agassiz
LAST SIGHTED DATE	April 30, 1963 reported by passing ship.	Recovered October 18, 1963.	December 18, 1963
LENGTH OF KNOWN TIME MOORED	180 days	183 days	78 days
<u>CHANGES AND REMARKS</u>	 Serviced January 19, 1963. Changed film and batteries. All instruments working. 	 Ecco lens radar reflector on a 12-ft mast. Capsized April 13, 1963 and was righted by USCG vessel. Tension indicator failed (pressure pot failure). Float exchanged and mast shortened June 4, 1963. First float mooring eye was in the center. Second float mooring eye moved to original position, 1/3' aft from the bow. Nylon line parted 785 ft below the bottom end of the instrument line, October 18, 1963 	 Life boat radar reflectors on bamboo poles. Seen on November 7, 1963 from airplane. Observed November 15, 1963 from T-441 in good condi- tion. Found capsized December 3, 1963. Light and instru- ment box removed. Reinstalled instrument box without water temperature indicators. Also had modified electronic control system, December 18, 1963. Highest wind speed recorded on film was 27 knots. Searched for on January 8, 1964, but not found.

	# 10	#11	# 12
DATE MOORED	October 2, 1963	October 2, 1963	October 2, 1963
LOCATION	34° 05.5'N, 121° 14.6'W	33° 46.0'N, 121° 57'W	33° 24.4'N, 122° 36'W
DEPTH	1498 fathoms	2017 fathoms	2180 fathoms
TYPE OF MOORING LINE	3/8" nylon-gold line	3/8" nylon-gold line	3/8" nylon-gold line
TYPE OF INSTRUMENT LINE	Same as ∲8	Same as #8.	Same as #8.
INSTRUMENTATION	Same as #9 except no line tension and no current meter.	Same as ∲9 except no line depth.	Same as #9 except no line dept and no current meter.
		·	
MOORING SHIP	Agassiz	Agasoiz	Agasaiz
LAST SIGHTED DATE	October 4, 1963	February 2, 1964	March 23, 1964
LENGTH OF KNOWN TIME MOORED	3 days	124 days	174 days
CHANGES AND REMARKS	 Same as #9. Boarded October 4, 1963. All instruments operating. Not sighted during air search on November 7, 1963. Not found by December 3, 1963 	 Same as #9. Same as #9. Clock malfunctioning due to corrosion December 3, 1963. Highest wind speed recorded on film was 50+ knots. Replaced mechanical switch- ing with modified elec- tronic control system and Geodyne clock, December 18, 1963. Found capsized January 9, 1964. Righted and lens on camera replaced. Found capsized. Righted and camera removed February 2, 1964. Air search by Pacific Missile Range. Did not find on March 23, 1964. 	 Same as #9. Experimental electronic control system malfunc- tioned and was replaced by mechanical switching. Highest speed recorded on film was 32 knots. Mechanical switching had failed and was replaced by modified electronic control system, December 3, 1963 Serviced - changed bat- teries and film December 18, 1963. Removed instrument box due to camera malfunc- tioning January 9, 1964. At this time 60 meter, 150 meter, line tension not operating. Air and sea search by Pacific Missile Range

	#13	#14	#15
DATE MOORED	December 8, 1963	February 10, 1964	February 21, 1964
LOCATION	29° 58'N, 139° 56.7'W	34° 00'N, 164° 00'E	29° 58.5'N, 140° 0.5'W
DEPTH	2150 fathoms	3180 fathoms	2280 fathoms
TYPE OF MOORING LINE	3/8" nylon-gold line	3/8" nylon-gold line	3/8" nylon-gold line
TYPE OF INSTRUMENT LINE	1500 ft of 1/4" stainless steel.	1000 ft of 1/4" stainless steel.	None (nylon line to the surface).
INSTRUMENTATION	Hydraulic tension indicator.	Hydraulic tension indicator.	None.
MOORING SHIP	USCG Ponchartrain	USCG Bering Strait	USCG Minnetonka
LAST SIGHTED DATE	Recovered December 15, 1963.	February 15, 1964	Recovered March 12, 1964.
LENGTH OF KNOWN TIME MOORED	8 days	6 days	21 days
<u>CHANGES AND REMARKS</u>	 Nylon parted 40 ft below stainless steel wire. 	 Capsized in very heavy seas on February 12, 1964. Never righted. Weather - wind 35 knots, 15-foot seas when found capsized. Had drifted approx. 6 miles when last seen. 	l. Nylon parted 60 ft below sea surface.

3 February, 1965

	#16	#17	#18
DATE MOORED	May 17, 1964	May 18, 1964	May 19, 1964
LOCATION	33° 23'N, 128° 38'W	35° 30.4'N, 131° 46.1'W	32° 10'N, 132° 46.8'W
DEPTH	2355 fathoms	2735 fathoms	2545 fathoms
TYPE OF MOORING LINE	7/16" nylon-gold line	7/16" nylon-gold line	7/16" nylon-gold line
TYPE OF INSTRUMENT LINE	Same as #8.	Same as #8.	Same as #8.
INSTRUMENTATION	Same as #9 except no current meter or line depth. Zero aluminum box.	Same as #16 except used Accutron clocks.	Same as #16.
MOORING SHIP	Agassiz	Agassiz	Agassiz
LAST SIGHTED DATE	Still in service	Recovered 29 September, 1964	October 16, 1964
LENGTH OF KNOWN TIME MOORED		135 days	150-195 days
<u>CHANGES AND REMARKS</u>	 Triangular ballast tank on sides. Wooden thimbles between nylon line and chain. Radio beacons installed on June 11, 1964. 	 16-ft float. Wooden thimbles between between nylon line and chain. Various parts from instru- ment box stolen by unknown party June 30, 1964. Two Russian trawlers sighted near platform June 30, 1964. Mooring failed but line not recovered to break due to weather and time of recovery. 	 Semi-circular ballast tanks on sides. Wooden thimbles between nylon line and chain. Radio beacon installed on June 11, 1964. Not located on 7 November under poor search conditions Not located on 19 December 115 sq. mi. search area good position. S.S. Lurline reported sighting on 23 December, 1964 at 30°24'N, 134°31'W. Skiff adxift.

	#19	#20	#22	
DATE MOORED	May 20, 1964	June 13, 1964	June 25, 1964	
LOCATION	30° 51.5'N, 128° 37.8'W	29° 59.9'N, 140° 02.2'W	29° 58.8'N, 140° 1.0'W	
DEPTH	2355 fathoms	2250 fathoms	2100 fathoms	
TYPE OF MOORING LINE	7/16" nylon-gold line	7/16" nylon-gold line	7/16" nylon-gold line	
TYPE OF INSTRUMENT LINE	Same as #8.	Same as #8.	Same as 16	
• •				
<u>INSTRUMENTATION</u>	Same as ∦16 except used Accutron clocks.	Same as ∦16.	Same as 16	
MOORING SHIP	Agassiz	USCG Gresham	USCG Pontchartrain	
LAST SIGHTED DATE		Recovered June 29, 1964	Still in service	
LENGTH OF KNOWN TIME MOORED	194 days	17 days		
<u>CHANGES AND REMARKS</u>	 Semi-circular ballast tanks on on bottom of floats. Yarn knot in upper end of nylon. Parted at clevis, Mechanical failure 	 Triangular ballast tanks on sides. Nylon line parted one foot below instrument cable. 	 #20 reinstalled at OSN. 500 ft. polyethylene pipe over nylon extending down from bottom of instrument line. 	

#21 built for Oregon State University.

TABLE 2

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Mean Time Before Failure of Various Moorings as of January 27, 1965

Location	Mooring No.	Duration in Days	MTBF in days
Sheltered	1	406*	
area off	2	61*	
La Jolla	3	1000+	
	4	97	391
		1564	
Open sea areas	6	201	
	7	180	
	8	183	
	9	78	
	10	3	
	11	124	
	12	174	
	13	8	
	14	6	
	15	21	
		978	98
Improved design	16	250†	
open sea areas	17	135	
	18	150	
	19	194	
	20	17	
	22	220†	
		966	161
All open sea moorings to present			121
All moorings to present			175

* Purposely terminated

† Still installed

APPENDIX

Construction

Described below are the construction details of the mooring that have been tested by SIO. Variations in the number of thermistors, instrument line, instrument box are possible without compromising the reliability of the entire mooring system.

Description

The major components of the Scripps Deep-Moored Instrument Station consists of a modified catamaran-type surface float, instrument box, instrument line, nylon mooring line and anchor. The length of nylon line is cut slightly less than the depth of the water where the station will be anchored. This stretches the line tending to hold the station in a position over the anchor. The upper 150 meters of the mooring line is a steel wire to which the instrument cable is attached. There are 6 theristors spaced along the cable at various intervals. The cable is terminated at the surface with a steel wire strength member fastened to a tension transducer; the electrical conductors pass through the deck and plug into the instrument box.

Mounted on the deck of the float is the instrument box. It houses the instrumentation, recording equipment and acts as a support for the mast. The box has a hinged top which is fastened shut with link-lock latches. Several bulkhead-type connectors provide electrical connections with the main instrument cable and accessory sensors mounted on the float.

The instrument box contains a number of indicating meters which display all the various measurements simultaneously. These indicators are mounted on a curved panel and photographed at predetermined intervals (Fig. 6). A clock-driven switch initiates a pulse at the pre-selected interval which triggers an electronic control circuit. The control circuit generates a pulse to advance the pulse camera to the next frame, followed by a second pulse to turn on a bank of lights which photographs the panel of instruments. There is no shutter in the camera, so the length of time the lights are on determine the exposure for the photograph. The 6-volt dry-cell batteries which power the recording system and the flashing beacon are housed in wooden containers inside the instrument box.(Fig. 7).

Detailed Construction Notes

During the evolution of the taut mooring most of the components were hand made at Scripps. For the model described here, many components were manufactures to our specifications by outside vendors or the Research Support Shop on campus. Among the components manufactured outside were: sea temperature indicators, instrument box, remote reading compass, float, hydraulic clevis, jacket on stainless steel cable, thermistor boots, and tape-wrapping machine. (See parts list with vendor name and drawings.)

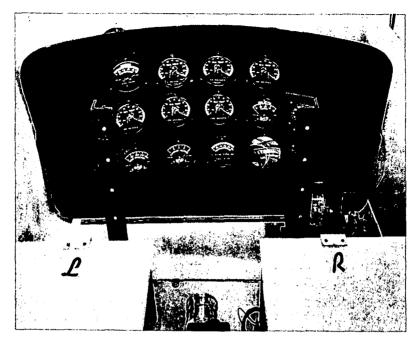


Figure 6. Instrument panel.

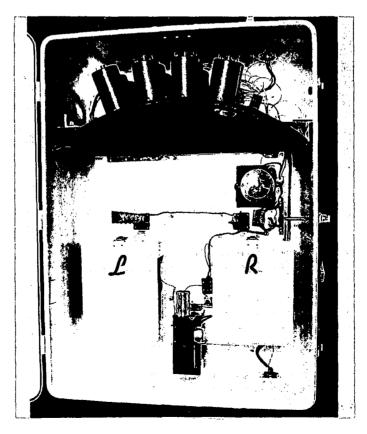


Figure 7. Overhead view of instrument box.

Generally the construction of the system is straight forward and can be carried on with reference to the drawings. There are, however, some points that need special consideration. These points resulted from test and experience with previous anchored stations.

Aluminum Parts

All exposed aluminum pieces should be of the 6061 T6 alloy and, after fabrication, they should be <u>hard anodized</u>, except for the stanchions (3002 alloy). This will greatly reduce the corrosion rate.

Instrument Line

The instrument line has been manufactured at Scripps with the aid of a tape-wrapping machine (see drawing no. 27). The procedure for this is to first have the 1/4" S.S. strength member jacketed (item #10 on first page of the parts list). After this has been done the necessary components (wire, tape, etc.) are taken to an area where the 150-meter length of cable can be stretched out. Once the strength member is stretched out, pairs of Amergraph hook-up wires are laid out to appropriate lengths from the top of the cable to give the desired thermistors' depths. 8 to 12 feet of electrical wire must be left above the top end of the strength member to allow the electrical cable to reach the instrument box (Fig. 8).

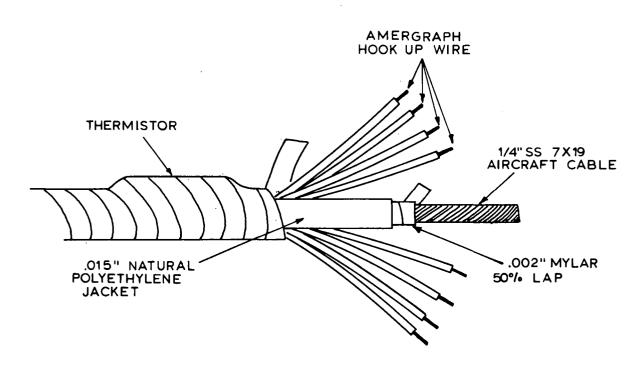


Figure 8. Instrument line construction.

When all the conductors are laid out the tape-wrapping machine can be slipped over the end of the cable and wrapping the cable assembly together can proceed. When conductor's end is approached about 2 feet of conductor should be pulled out for splicing the boot in at a later time. When a six-thermistor cable is made (12 conductors) all conductors (at the upper end) may not fit through the tape-wrapping machine. If this is the case the surface temperature thermistor can be hand taped to the assembly after the cable is wrapped. When the cable is wrapped with tape and the tape-winding machine removed, the thimbles can be nico-pressed in the ends.

The thermistors are spliced into the cable as follows: first, pull the rubber boot up one of the conductors. Strip the insulation from the ends of the conductor and slide the nylon tube over the thermistor. Then solder the thermistor to the conductors. (DO NOT USE TOO MUCH HEAT ON THE THERMISTOR.) Inject epoxy with a hypodermic syringe into the nylon tube and press the conductors up against the ends of the nylon tube so the wires will be imbedded in the epoxy. When the epoxy is cured, slide the boot over the nylon tube containing the thermistor (see Fig. 9). The conductors at the upper end of the instrument line are passed through a piece of tygon tubing and soldered to the appropriate pins of the electrical plug. The lower end of the tygon tube is taped to the strength member to secure the conductors at their take-off point (Fig. 10).

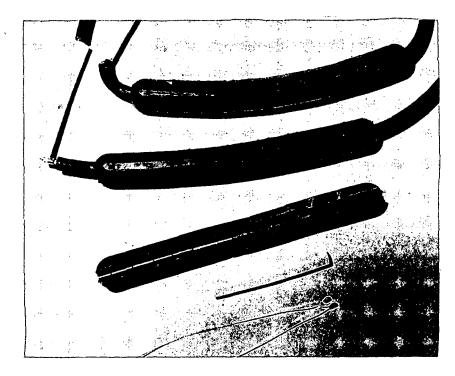


Figure 9. Thermistor boot assembly.

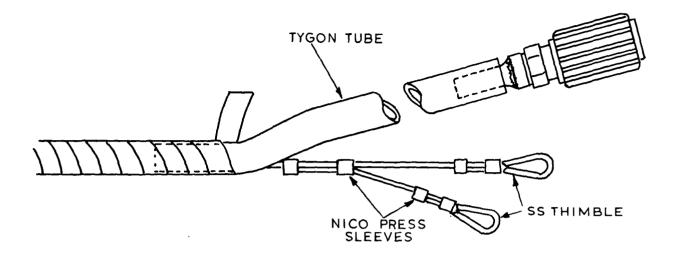


Figure 10. Instrument line and strength member termination.

Instrumentation

The instrument panel is fabricated from fiberglass cloth impregnated with epoxy resin. A suitable sphere (steel float) should be found with a radius of curvature of about 24 inches. This is coated with a suitable glass agent and used as a mold. Eight layers of a medium weight fibercured the panel can be trimmed to size, mounting holes drilled and the bottom piece glued on. The panel can then be degreased and painted flat

Several modifications should be incorporated in the instrumentation of any future units. Experience has shown that the batteries in the sea temperature indicators last for a period of approximately six months. A change in the batteries from the RM 502R models to the RM 12R would increase the time between battery changes by 50 percent with a very small increase in size. The three electronic circuit boards could be incorporated into one for easier servicing.

Some components used in the instrumentation portion of the mooring resulted in limited life or doubtful performance. The aerological sensors have shown numerous failures after six months of service. This has been due primarily to sea water leakage around the shafts causing corrosion and seizing of the shaft. Satisfactory seals were not included and it is suggested that a more reliable unit be found or the present units be modified to increase reliability. The strobe light beacon was originally designed for short service and life. A number have been used satisfactorily for periods of six months; however, there have been several failures after only two months of service.

Photographic equipment

After a number of photographic tests and consultation with Elgeet Optical Company, it was found that production lenses have the back focus adjusted for infinity. This resulted in the pictures taken with some lenses having parts of the picture out of focus while the remaining parts were in focus. Changing the focus setting did not solve this difficulty. Elgeet Optical Company then agreed to adjust the back-focus of the lenses to 24" at our request. Any future lenses purchased should have this adjustment made at the factory.

The camera used in this instrument station was secured from a surplus military weather data unit. It was necessary to modify some of the internal parts of the camera in the interest of reliability. There is some doubt as to the availability of this camera at the present time. A similar camera has been manufactured by Bell and Howell (Model 200p). The cost of the Bell and Howell unit has not been determined since SIO was able to obtain a large supply of the present cameras at a reasonable cost.

Nylon mooring line

The mooring line used in the more recent installations has been Goldline. This is a gold-colored nylon line chosen mainly for its color. It was felt that a more subdued color than the usual white nylon would be less attractive to marine animals. Two sizes of line have been used, 3/8-inch and 7/16-inch diameter, the latter size used in the most recent moorings (#16 through #22).

During the course of our mooring experience several line defects were noted. The obvious defects were improperly tied yarn knots and dropped yarns. In order to prevent this, the maximum length obtainable without yarn knots was ordered (approximately 5000 feet) and spliced together to give the desired total length.

Anchor

Several different types of anchors have been used successfully with the taut nylon mooring. The primary consideration is the cost and availability of the various materials used. Railroad rails have been used by cutting them into 3-foot lengths, laying them side by side and welding the assembly together. More recently, 1-1/4-inch anchor chain has been placed in 55-gallon drums and filled with concrete. Since large quantities of surplus chain are available, the chain and concrete anchors are the more economical of the two. A 20 to 30-pound danforth type anchor is attached by a 20-foot length of 3/8-inch chain to the 1200 to 1500-pound deadweight anchor to resist dragging by the mooring line.

Installation

In planning a mooring, first select a mooring site and from charts and soundings available determine the depth (use sound velocity correction tables). The slack length of the mooring line is 10 percent less than the actual depth so that when installed there is approximately 100 pounds tension in the line (see load vs elongation curves for nylon Figs. 11a, b). After the theoretical slack length has been determined the line must be measured under a known constant tension due to its elastic properties. The actual slack length must be determined by extrapolating back to zero load condition. The thimbles should be spliced into the line during the measuring operation when both ends will be available.

Before arriving on station the components should be laid out and the float completely assemble (Figs. 12, 13). A search in the area of the station for a flat area of the appropriate depth should be conducted. When a suitable area has been found the ship should run downwind a distance equal to the mooring depth plus 20 percent. At this point the float should be put in the water with the instrument line connected (Fig. 14). The ship can then pull slowly away from the float toward the drop area paying out instrument cable (Fig. 15). The instrument cable should be shackled to the nylon line before the float is put in the water. Once the instrument line is payed out the nylon can be payed out from its spool mounted on a reel stand (Fig. 16). Care should be exercised in paying out the instrument cable so it will not become fouled in the ship's screw. After several hundred yards of nylon have been spooled out the line will float on the surface and the fouling hazard will not be great. Stop the ship when there is one layer of nylon left on the spool. Pull some slack in the line and tie it off on a capstan. Unreel the remaining line and shackle the end of the line to the anchor chain. The ship should now be maneuvered into position over the previously selected area. Move the anchor in position to drop and then untie the mooring line from the capstan and let the line and anchor chain out. Move the ship to take the slack out of the mooring line and then drop the anchor (Fig. 17).

It will take some time for the anchor to fall, depending on the depth. When the anchor is on bottom the float can be boarded to make any final adjustments or additions and check out the system for proper operation. Installed tension should be observed and a depth reading taken near the float. From this information, line measuring accuracy can be checked.

Matthews, D. J., Tables for the velocity of sound in pure water and salt water for use in echo sounding and sound ranging. Hydrographic Department, Admiralty, London, 1939.

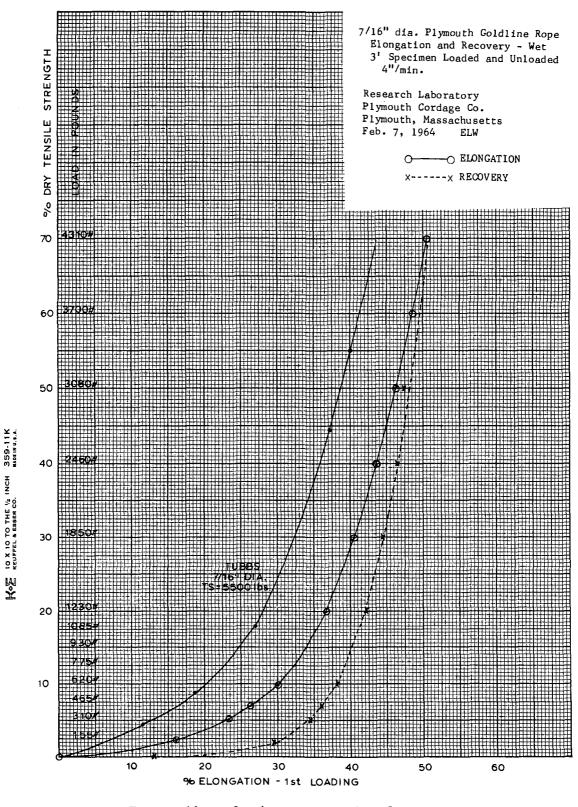


Figure 11a. Load vs elongation for nylon.

KOE 10 X 10 TO THE 1/2 INCH 359-11K REUFFEL & ESSER CO. RADE IN 0.5.4.

TS = 6160

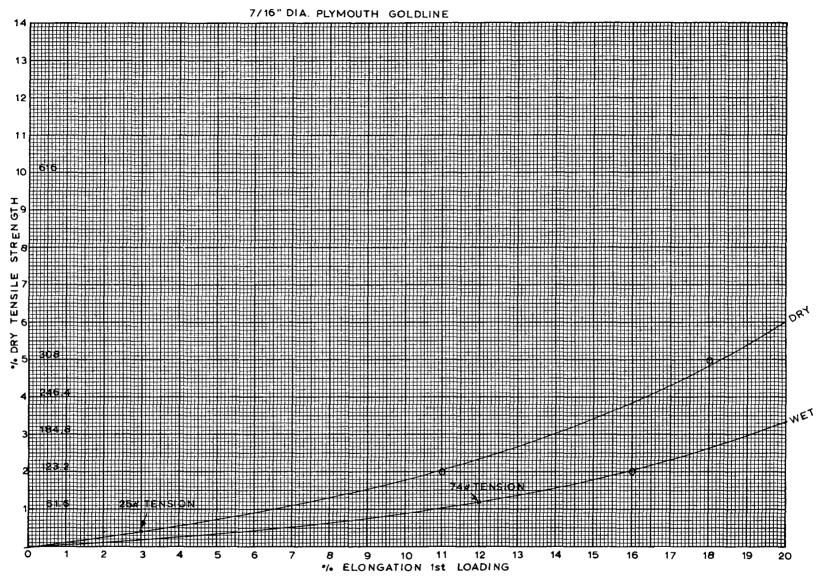


Figure 11b. Load vs elongation for nylon.



Figure 12. Arranging of equipment prior to launching float.



Figure 13. Final assembly of mooring components.

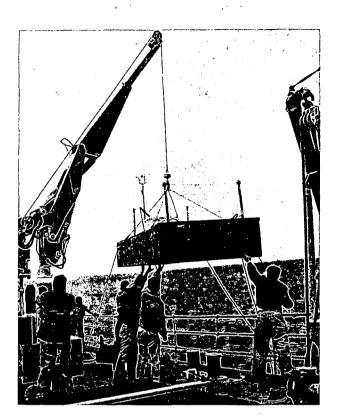


Figure 14. Launching of the catamaran float.



Figure 15. Laying of the instrument cable.



Figure 16. Spooling out the nylon mooring line.

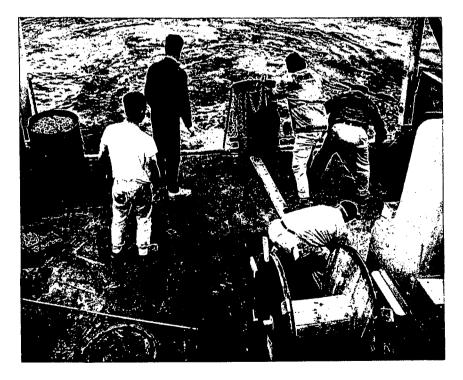


Figure 17. Launching anchor assembly.

Service Instructions

Service of the stations consists of changing batteries, film, flags, and radar reflectors.

1. <u>Batteries</u>

The power supply for the instrumentation is a pair of 6-volt dry cell batteries, wired in parallel, which is sufficient for three to four months operation. There are also a pair of the same batteries to power the strobe light beacon for three to four months. The batteries are standard ignition-Fence batteries, Mallory No. M 907, Burgess No. S 461, Everready No. 1461 or R.C.A. No. VSO 39.

The batteries are mounted in white wooden boxes with the box marked \underline{L} for beacon light and \underline{R} for power supply (Fig. 18). When it is necessary to replace the batteries the container should be opened, the wires disconnected and the new batteries installed. Reconnect the replacement batteries observing the polarity as mark on the cover of the battery case.

2. Film Exchange

The film should be replaced as often as possible in order to obtain the maximum amount of data in event of loss of the station. The 50-foot magazine has a maximum capacity of 83 days when hourly pictures are taken.

The film is supplied in moisture-tight foil containers and should not be opened until ready to load into the camera. Film that is stored under refrigeration should be allowed to reach ambient temperature before the foil bag is opened. Failure to observe this caution will result in jamming of the magazine. The camera is mounted on a hinged platform with a linklock latch (similar to exterior latches) securing the platform in place. Reach under the camera platform and release the latch. This will allow the camera and platform to swing forward (see Fig. 19). Squeeze the two catch releases in the rear of the camera, together opening the magazine compartment of the camera. The magazine can be extracted and the new one inserted, making sure that the hole in the front of the magazine faces toward the lens. Closing the rear of the camera and latching the platform in place completes this operation.

3. Radar Reflector and Flag

Each float is equipped with a surplus life boat radar reflector and a flag attached to a fiberglass pole on the float. It will be necessary to replace these units occasionally. Directions for rigging the radar reflector are included as part of the reflector package.

4. <u>Vent Valve on Instrument Box</u>

It may be necessary to open the vent value on the side of the instrument box before the lid will open due to a possible vaccum inside the box. If the value is opened, be sure it is closed after the lid has been opened.

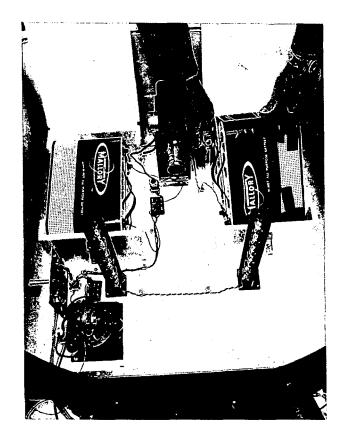


Figure 18. Exchange of instrument box batteries.



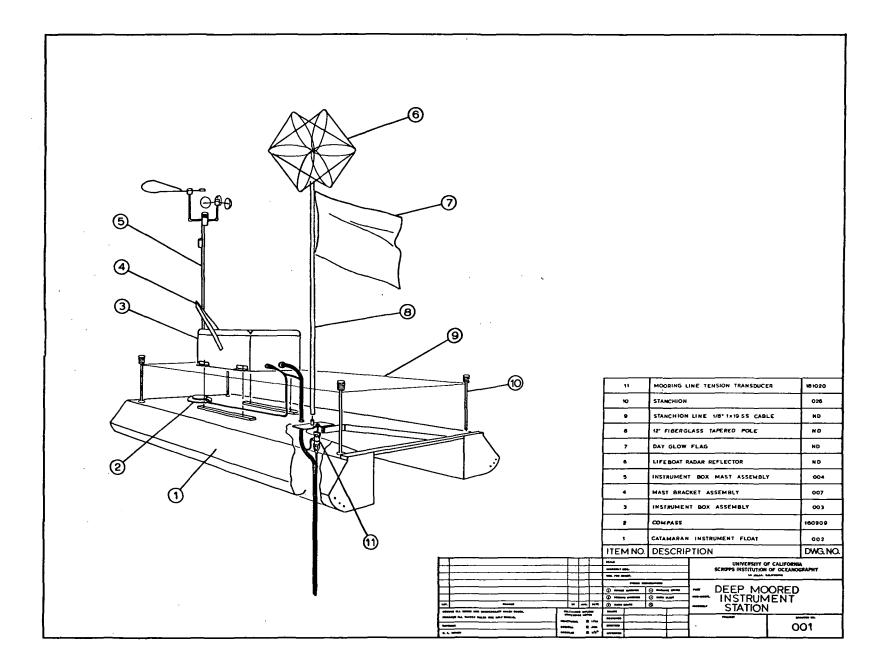
Figure 19. Film exchange.

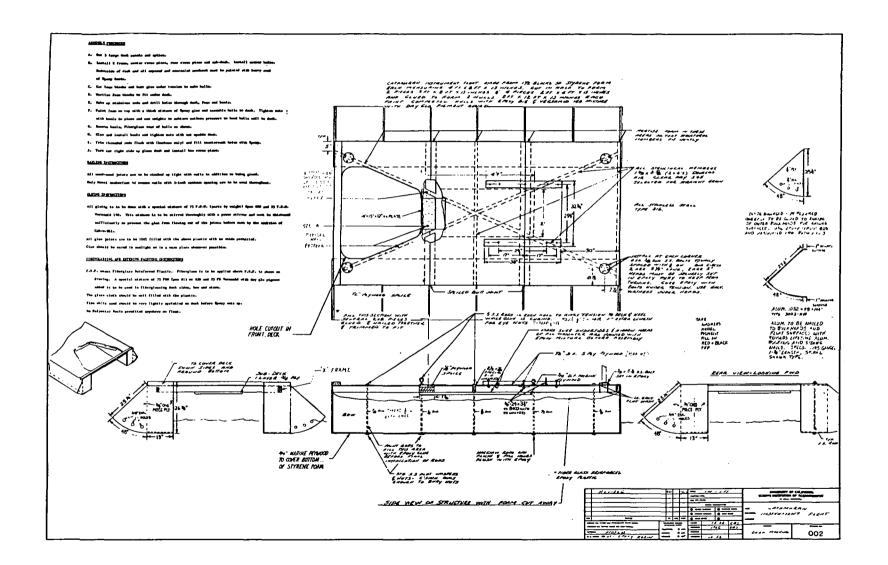
Major Service

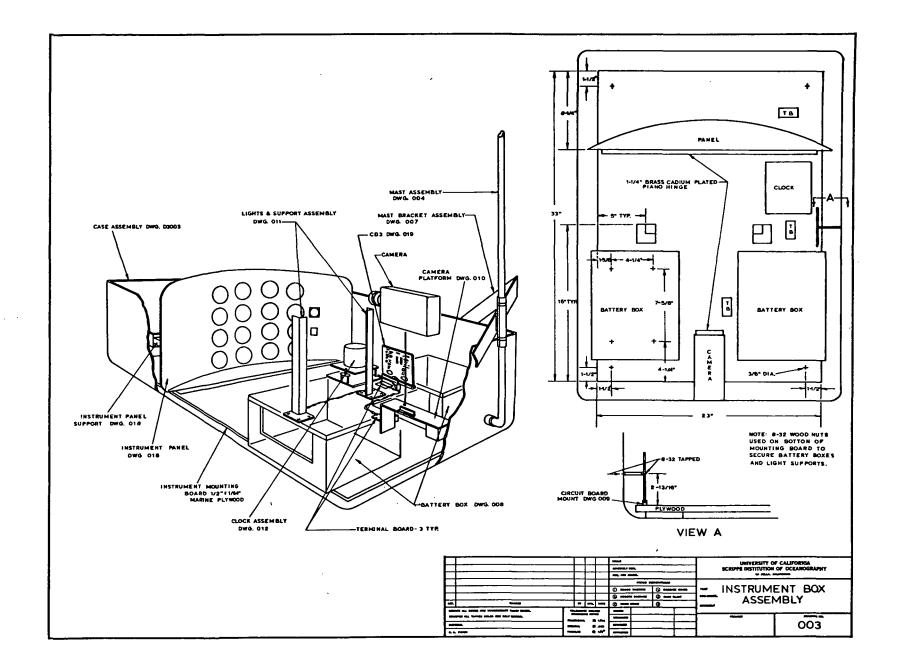
At intervals of approximately six months it will be necessary to replace instrument batteries and check calibration of the various instruments. The best procedure for this is to replace the instrument box assembly with another one in good operating condition and return the used one to the laboratory. In the laboratory all meter assemblies should be disassembled, batteries replaced and the units checked for wear or corrosion. The internal parts of the camera should be checked for wear and a test magazine run in the camera to assure proper film advance. The clock and control circuit assembly should be checked for proper operation. The station should then be reassembled and calibrating resistors connected across the thermistor inputs. At least five points should be chekced on the sea temperature scales for linearity. After the instrument box assembly has been assembled and calibrated it should be run in the laboratory for several days to verify its operation.

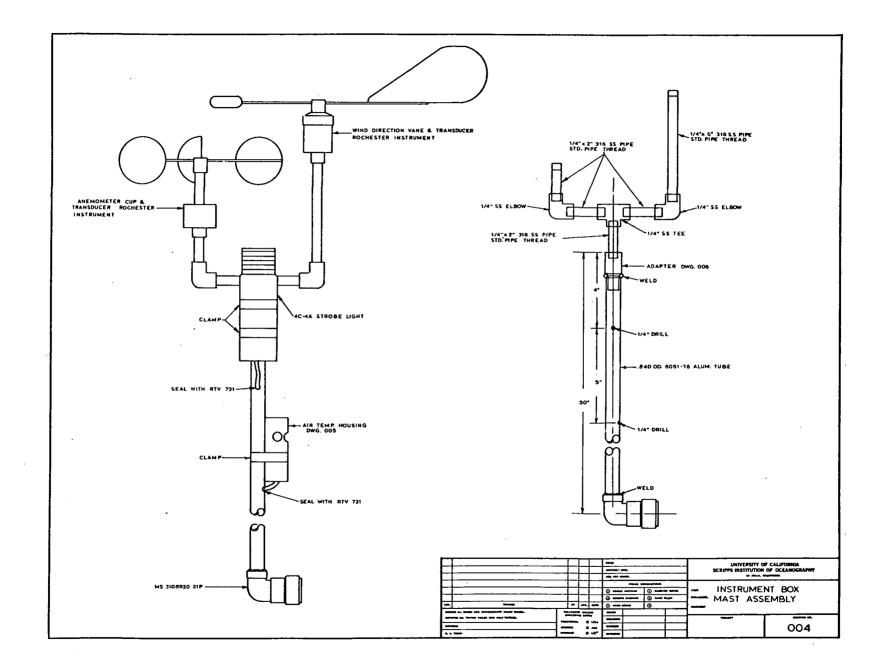
r		
Compass	180909	
Stanchion Assembly		026
Indicator Circuits		025
7°-17°C & 8°-28°C Pyron	neter Sea Temperature	024
Air Temp Circuit		023
Instrument Panel & Exte	ernal Sensor Wiring	022
Geodyne Clock Timer-Acc	cutron Clock Counter Driver	021
Photographic Control Sy	ystem Wiring	020
CB-3 Electronic Circuit	for Photographic System	019
Instrument Panel Suppor	•t	018
Instrument Panel Faster	ner Plate	017
Instrument Panel		016
Clock Shockmount Plate		015
Clock Platform Assembly	,	014
Clock Enclosure		013
Clock & Mounting Assemb	bly	012
Lights & Support Assembly		011
Camera Platform		010
Circuit Board Mount		009
Battery Box		008
Mast Bracket Assembly		007
Weather Transducer to M	last Adapter	006
Air Temperature Housing		005
Instrument Box Mast Assembly		004
Instrument Box Assembly		003
Catamaran Instrument Float		002
Deep Moored Instrument Station		.001
DESCRIPTION	DWG, NO.	
SCALE	UNIVERSITY OF CALIFORNIA	MATERIAL
DRAWN	SCRIPPS INSTITUTION OF OCEANOGRAPHY	FINISH
DTSIGNED CHECKED	DRAWING LIST FOR DEEP WATER MOORING STATION	DRAWING NO. SHEET 10F2
APPROVED	L	I

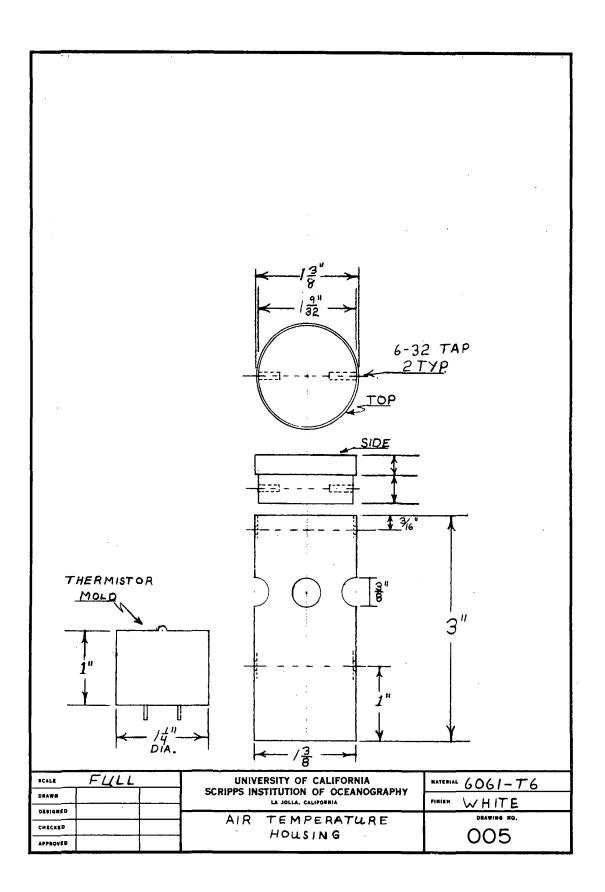
PVC Thimble		029
Thermistor Assembly		028
Tape Wrapping Machine		027
Angle Plate		Dwg. D3003 Item 27 of
Hat Section Assembly		D3003C1
Hat Section Assembly		D3003C2
Latch & Hat Section Ass	sembly	D3003C3
Case Assembly		D3003
Mooring Line Tension Tr DESCRIPTION	ansaucer	DWG NO.
JCALE	UNIVERSITY OF CALIFORNIA SCRIPPS INSTITUTION OF OCEANOGRAPHY	MATERIAL
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	DRAWING LIST FOR DEEP WATER MOORING STATION	DRAWING NO. SHEET 2 OF 2
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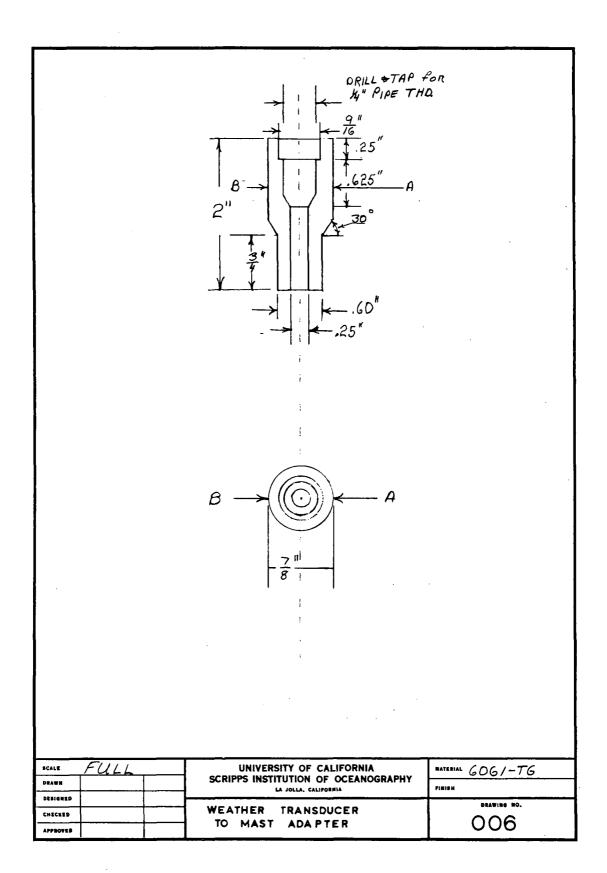


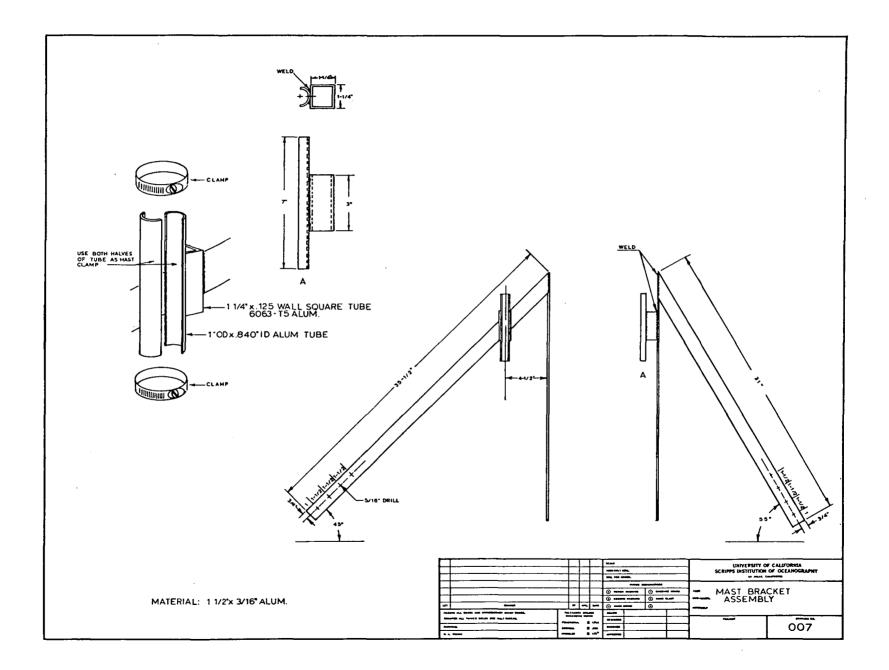


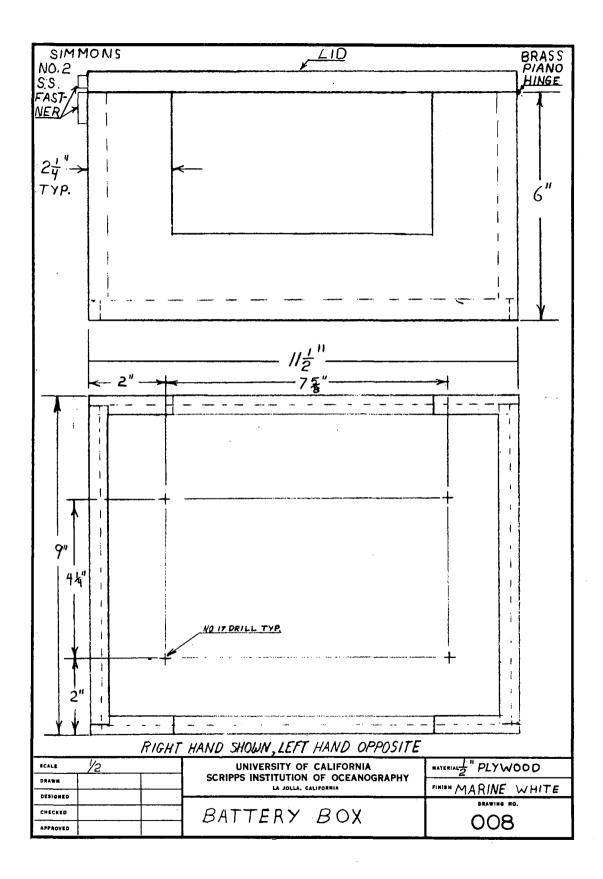


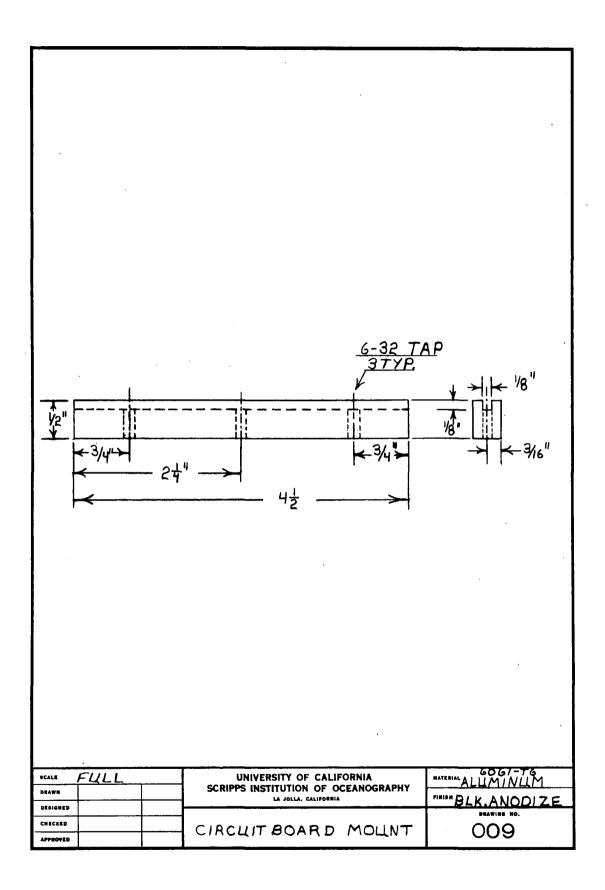


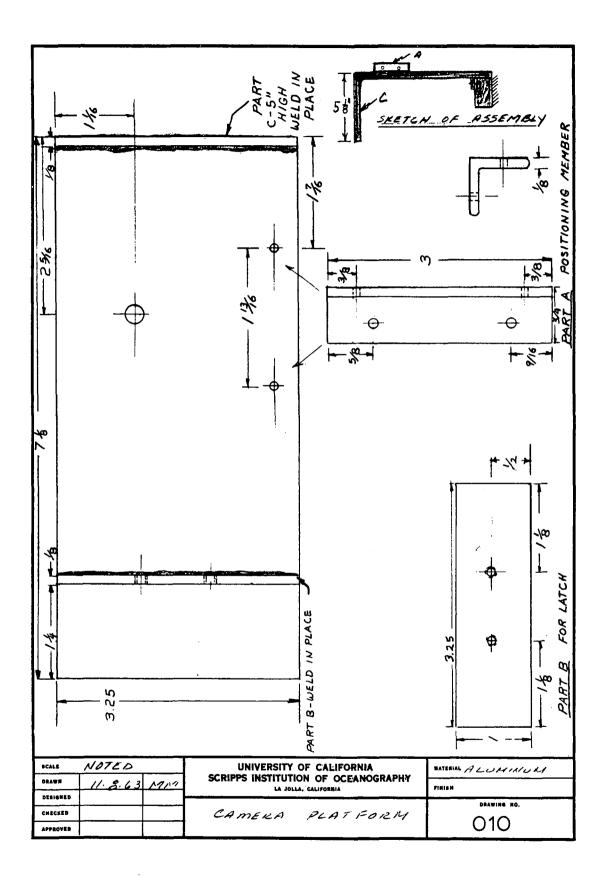


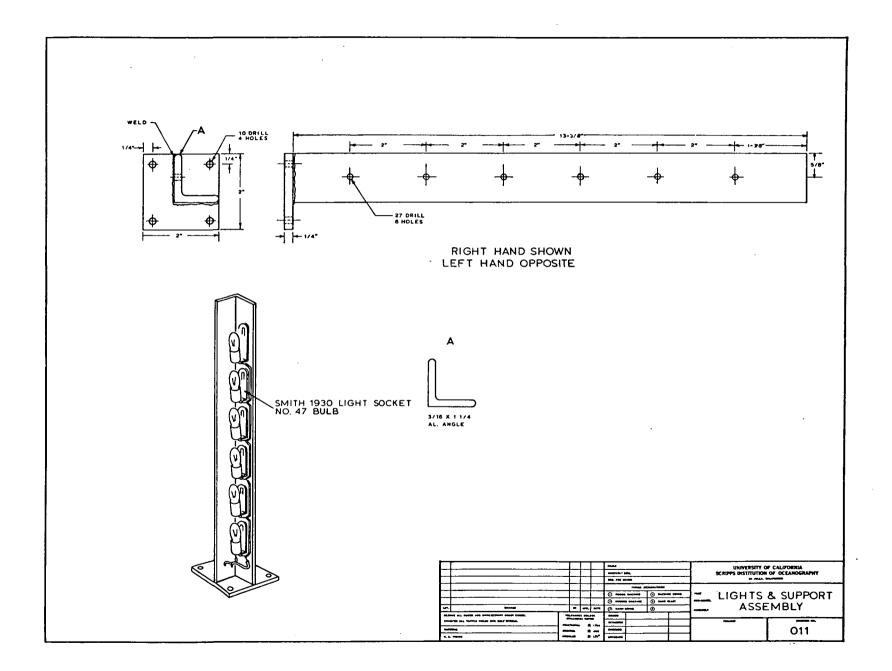


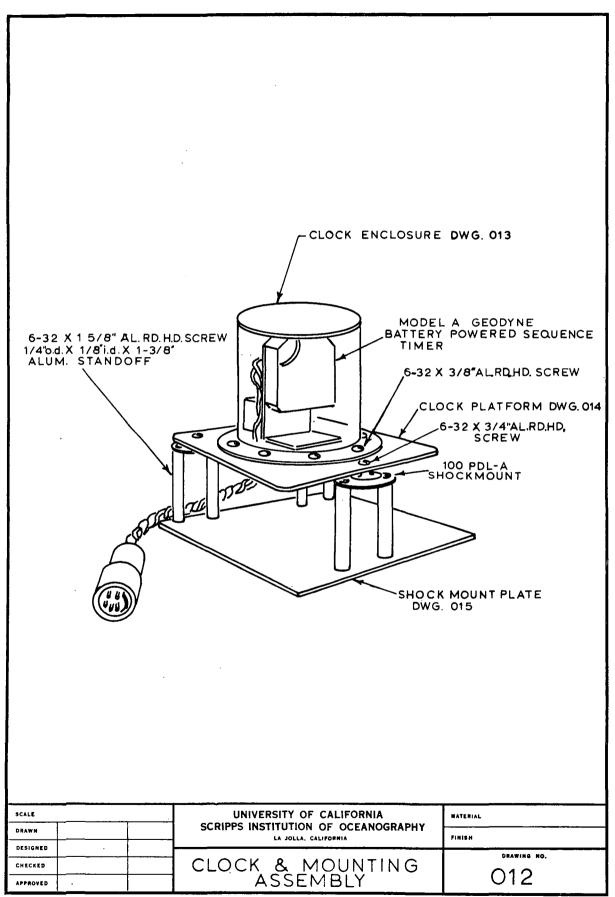


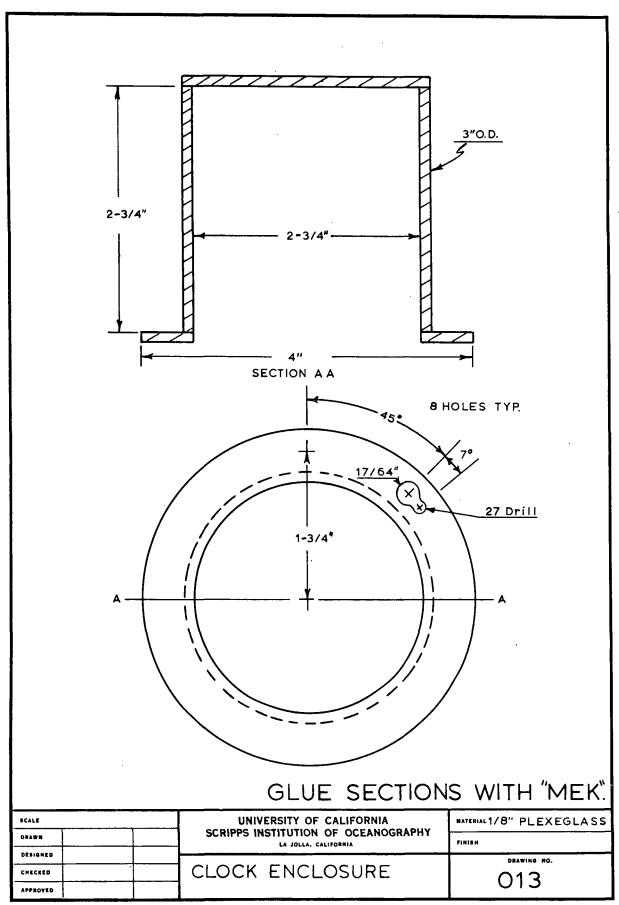


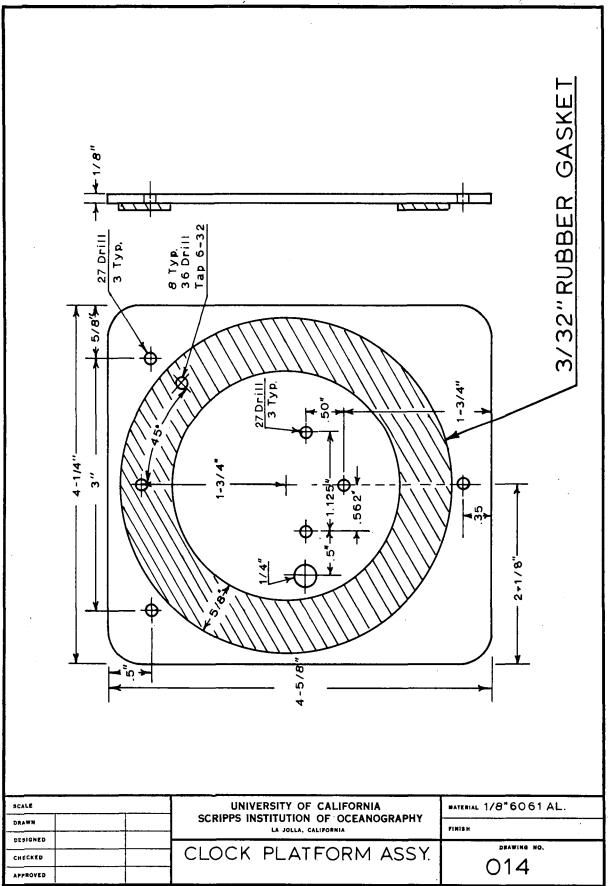


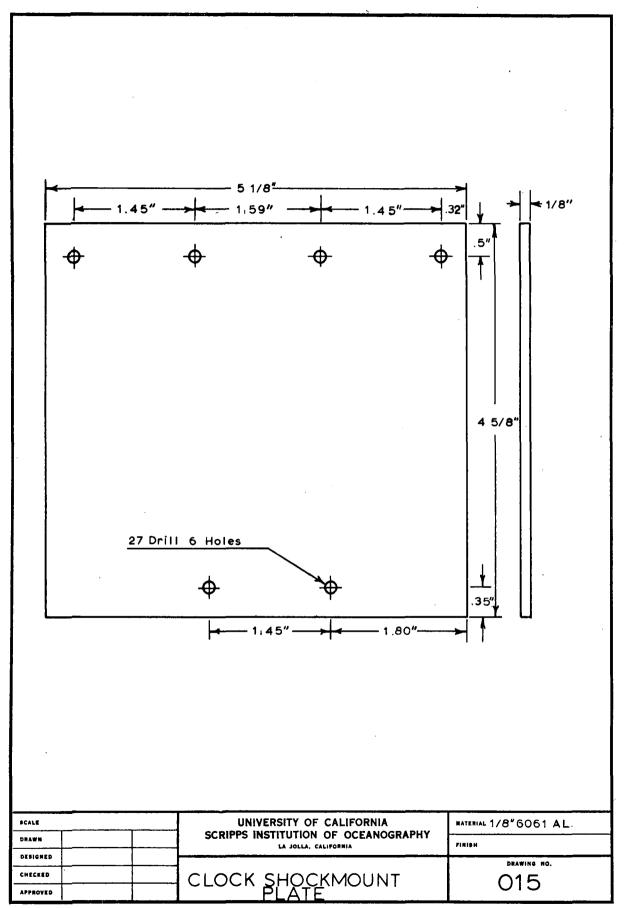


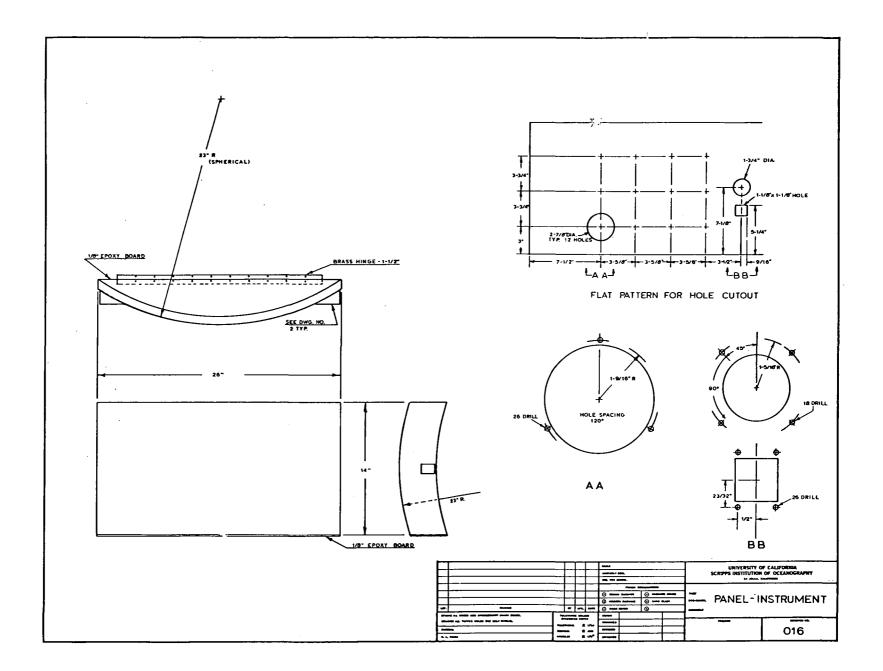


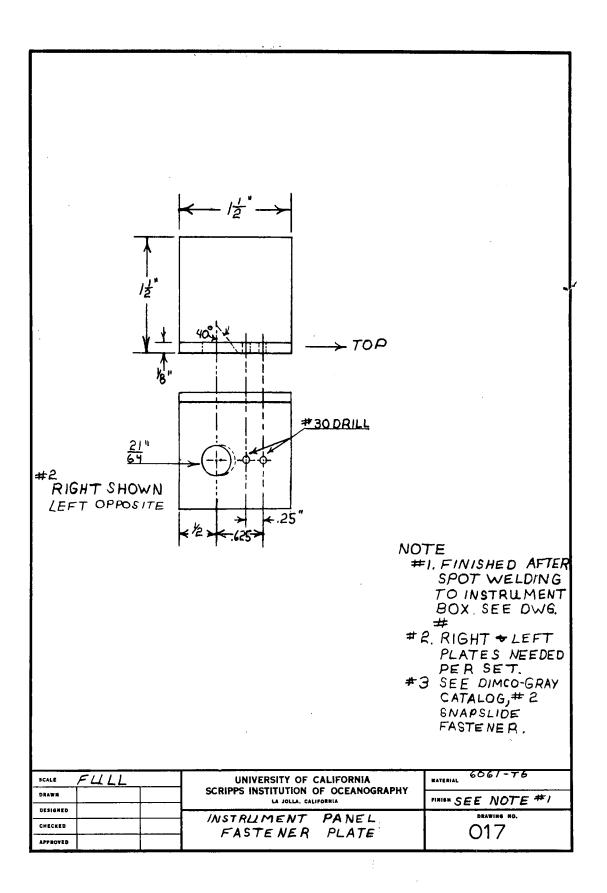


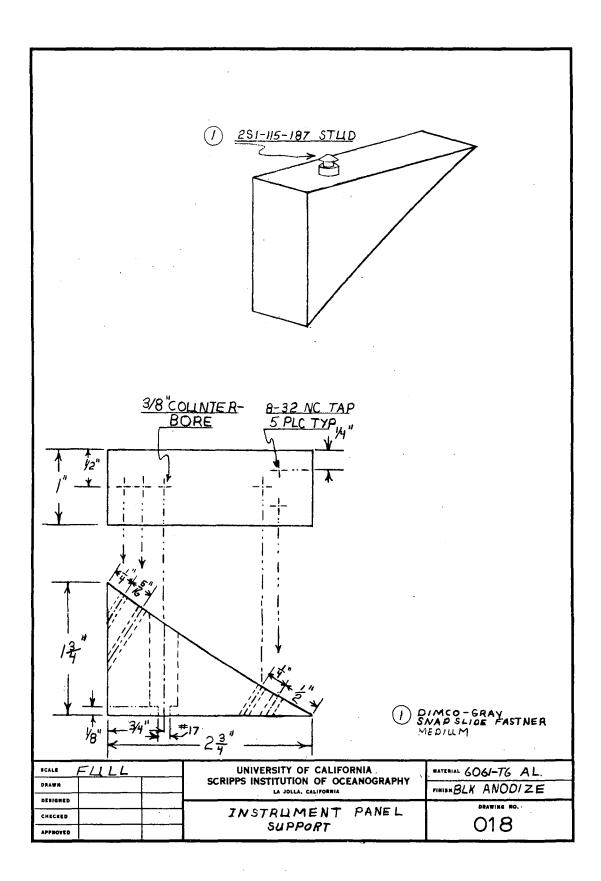


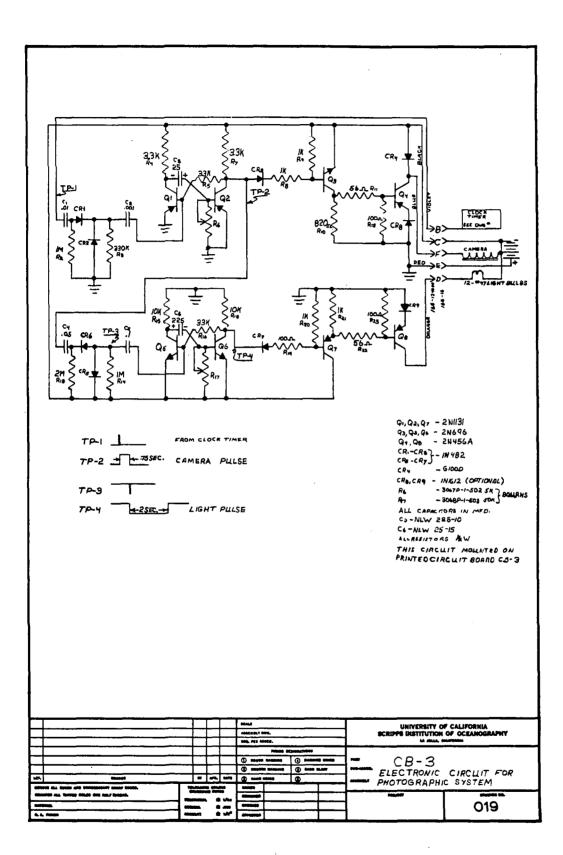


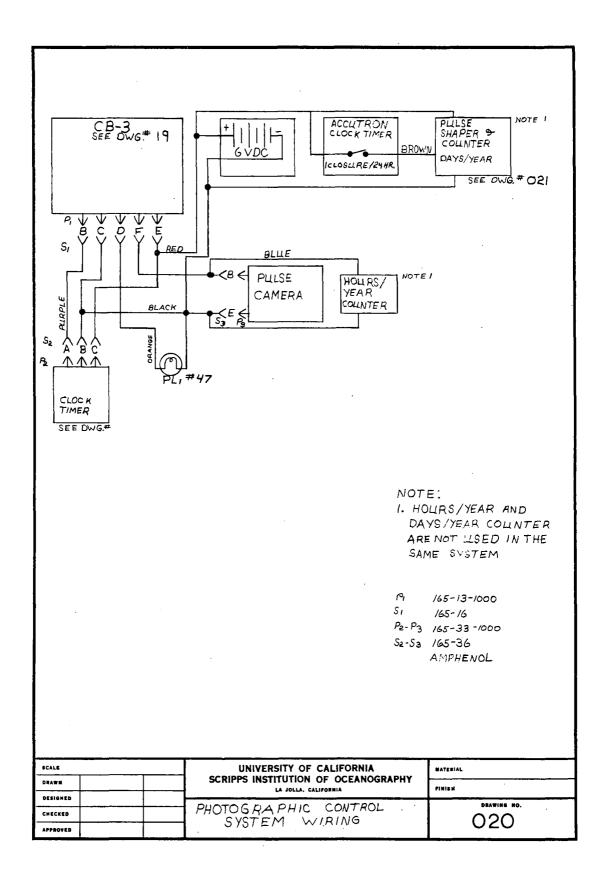


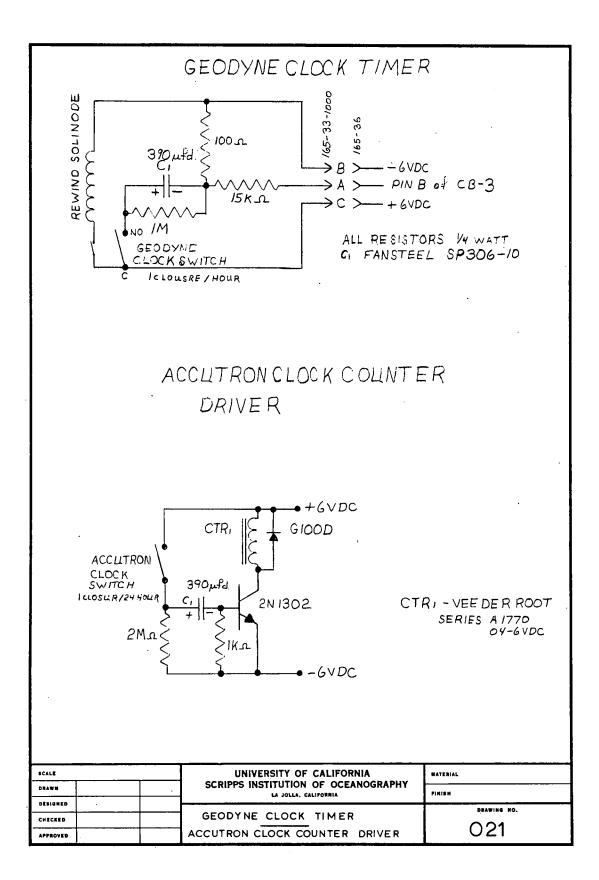


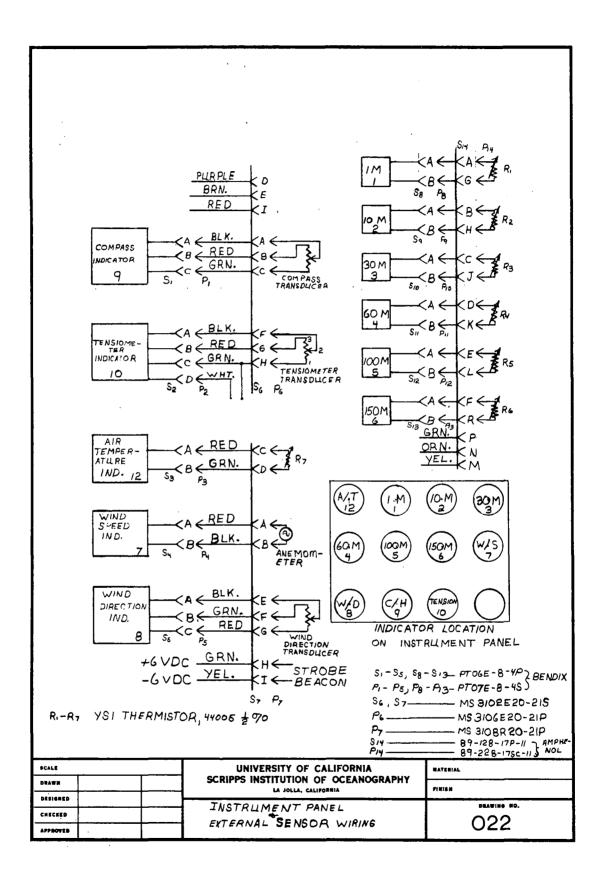




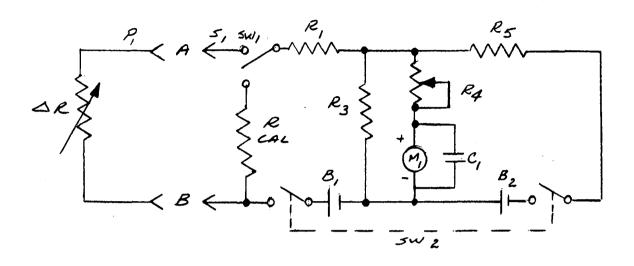








AIR TEMPERATURE



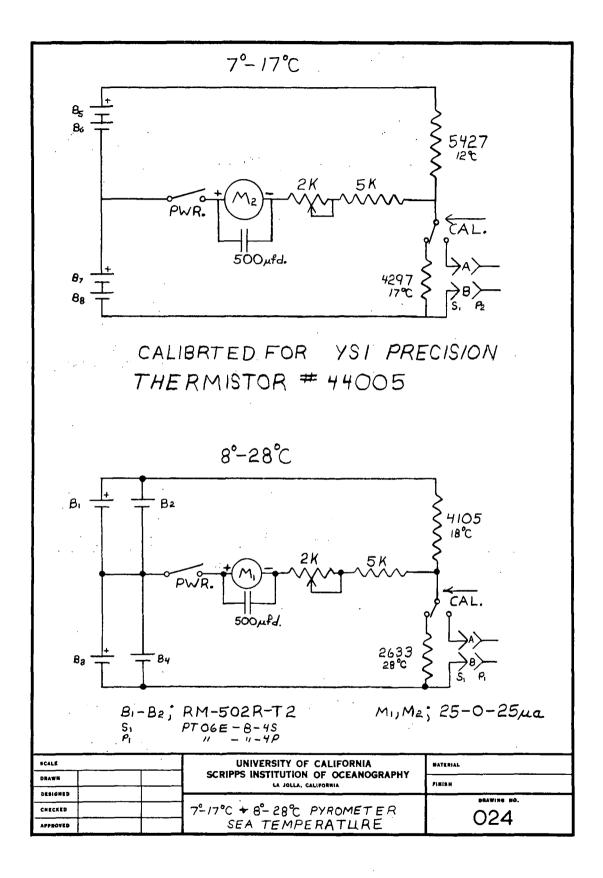
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	100 ufd
Μ,	0-100µa
R,	2.8k
R'Cal.	1.77K calibrate
R 3	4.77k
R ,	5k trimpot
R 4 R 5-	27.7 k
SW/	SpDT cal
SW,	DPDT power
2	1

 $\triangle R_{,}@0°F = 24.24 k.$ $<math>\triangle R_{,}@50°F = 5.86 k.$ $\triangle R_{,}@100°F = 1.77k.$

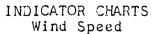
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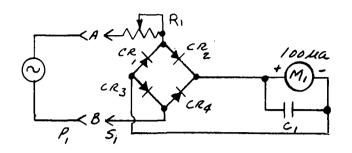
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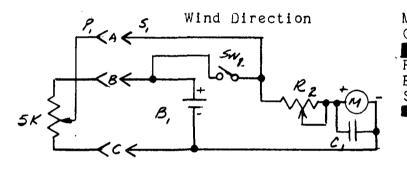


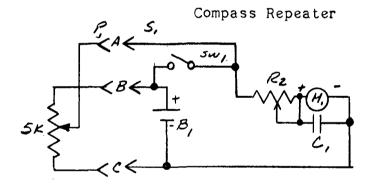
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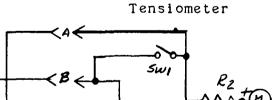




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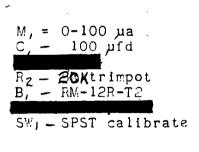


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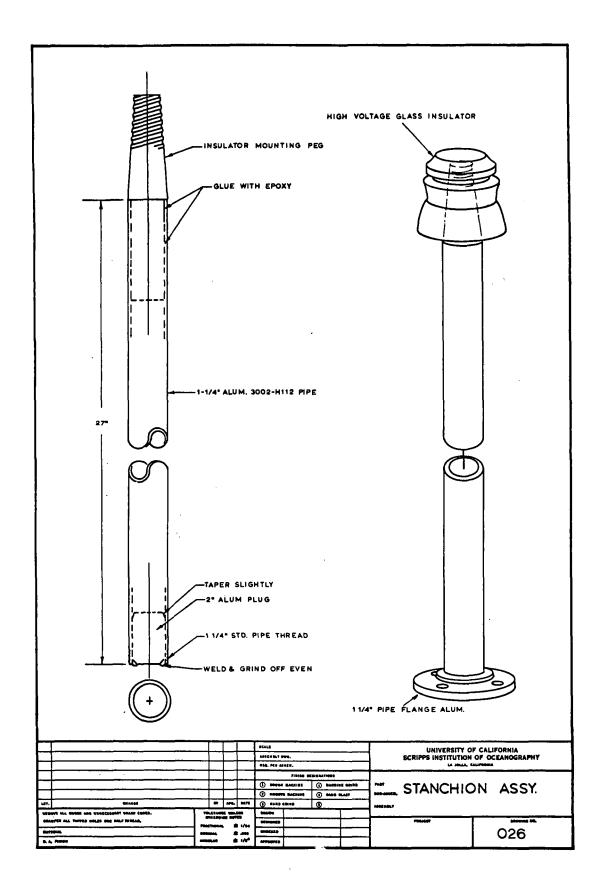
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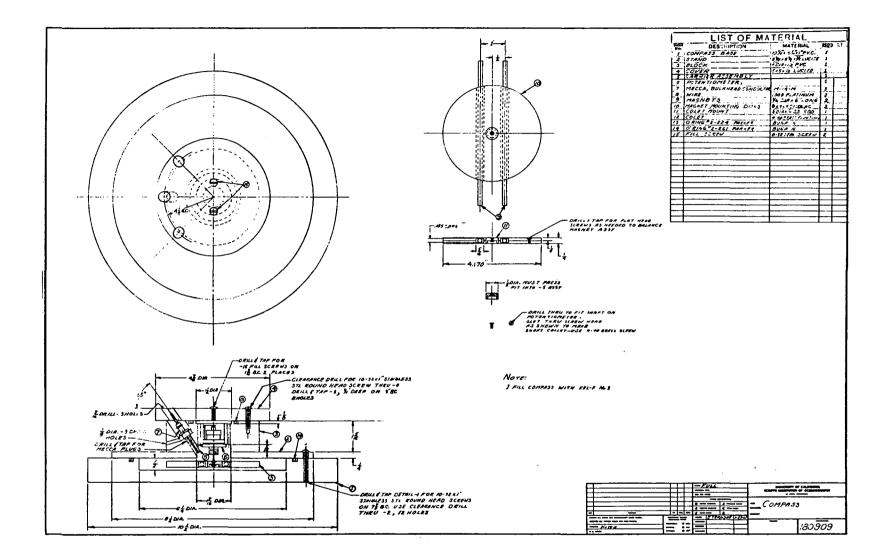
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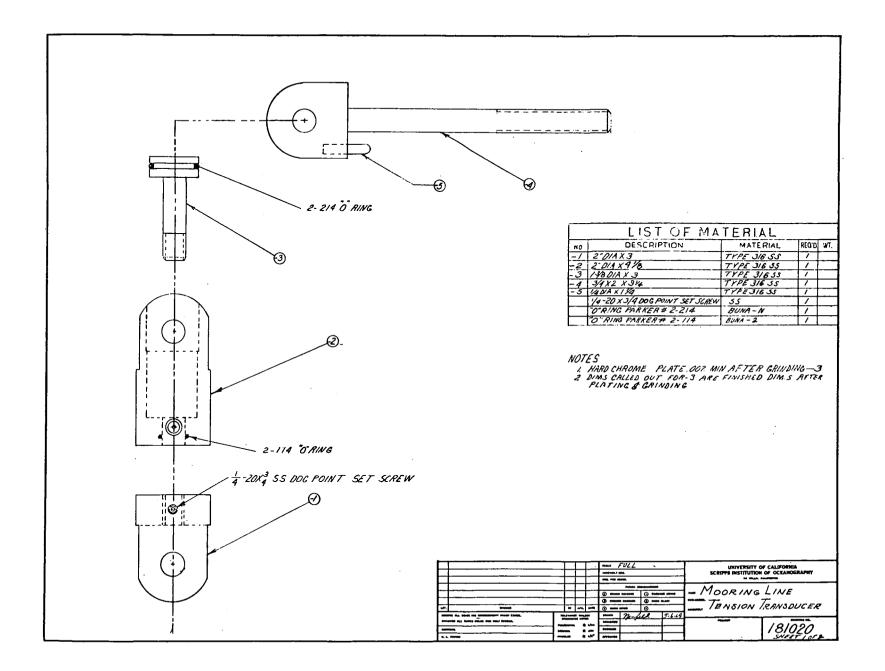


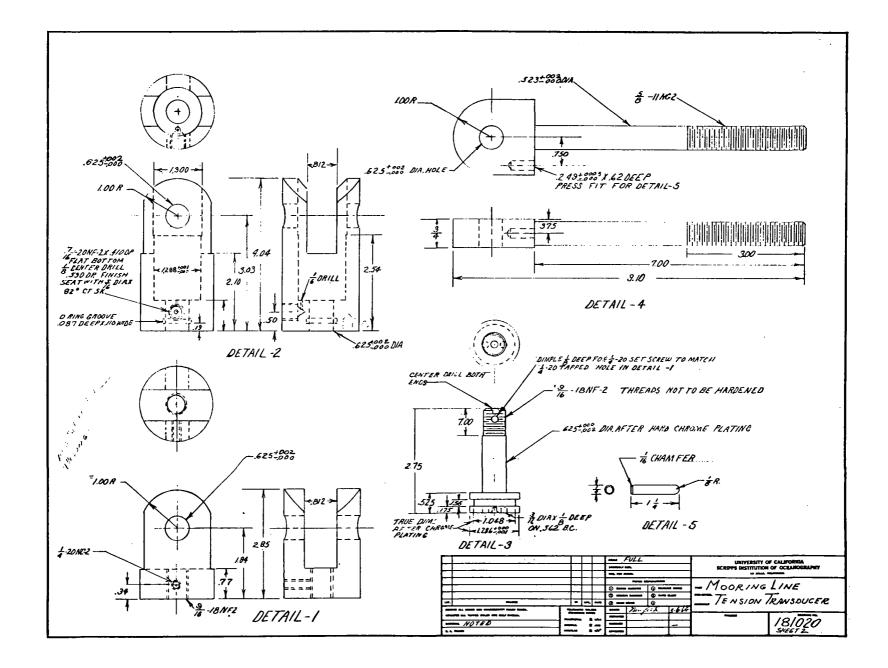
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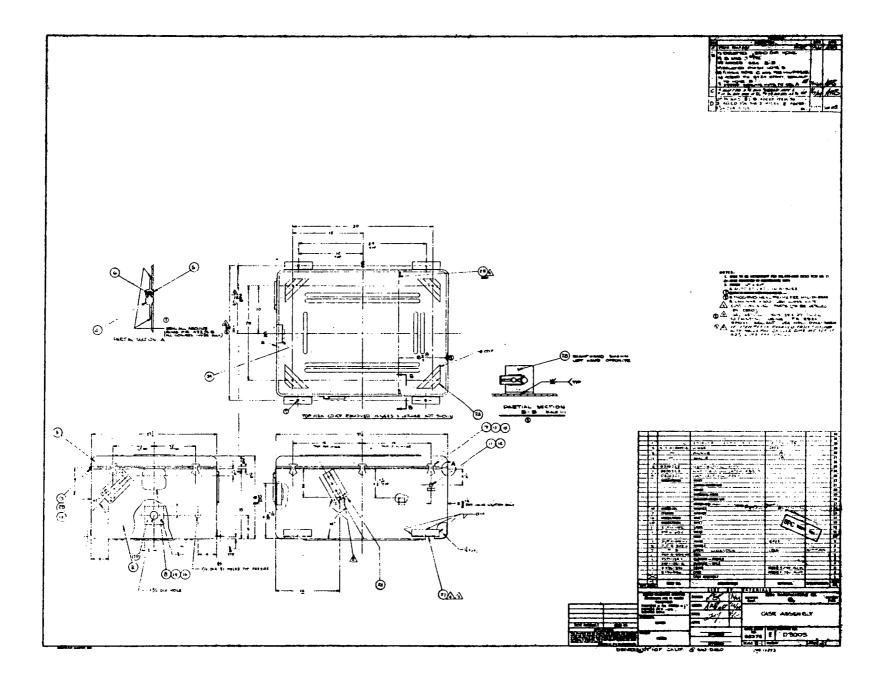
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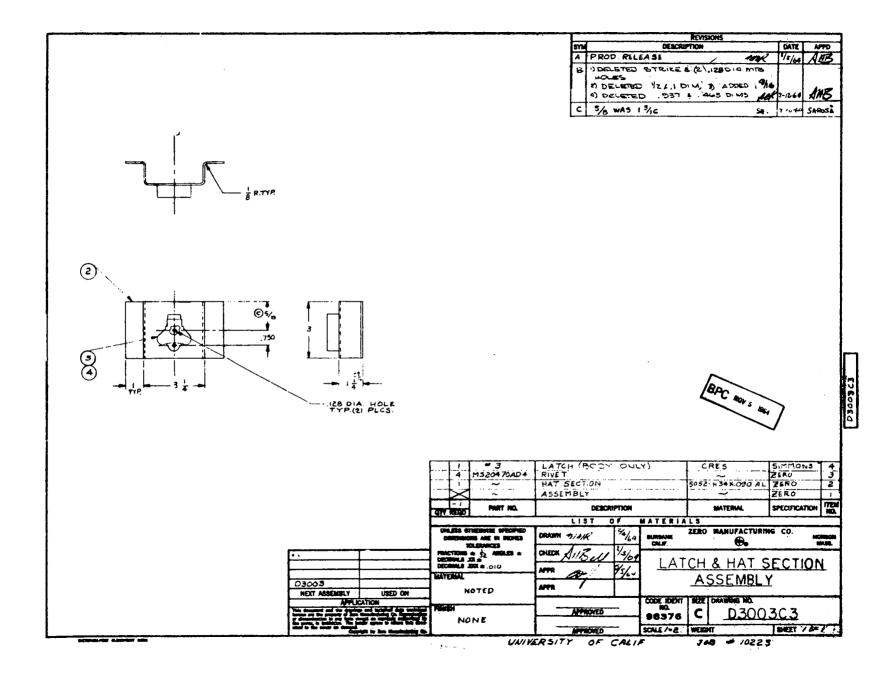


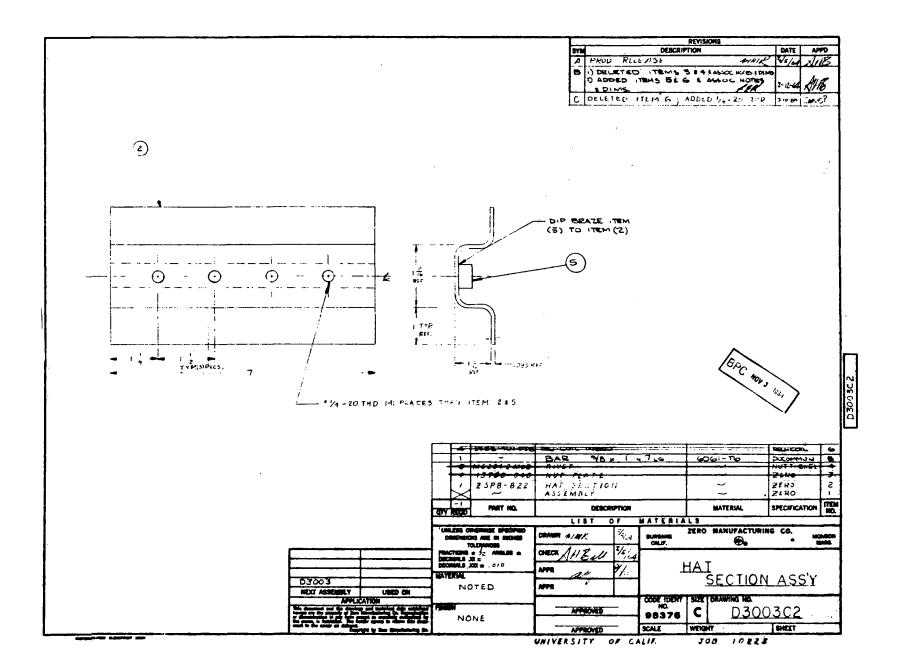




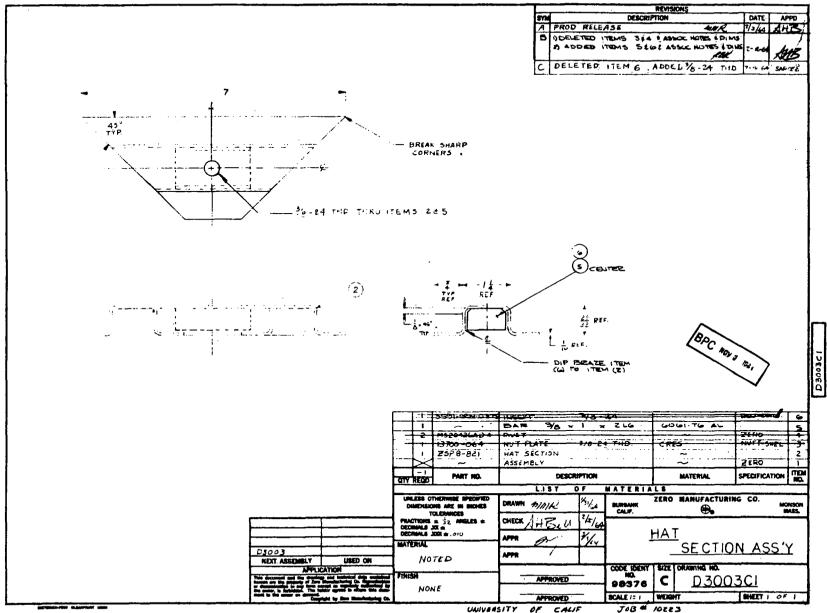




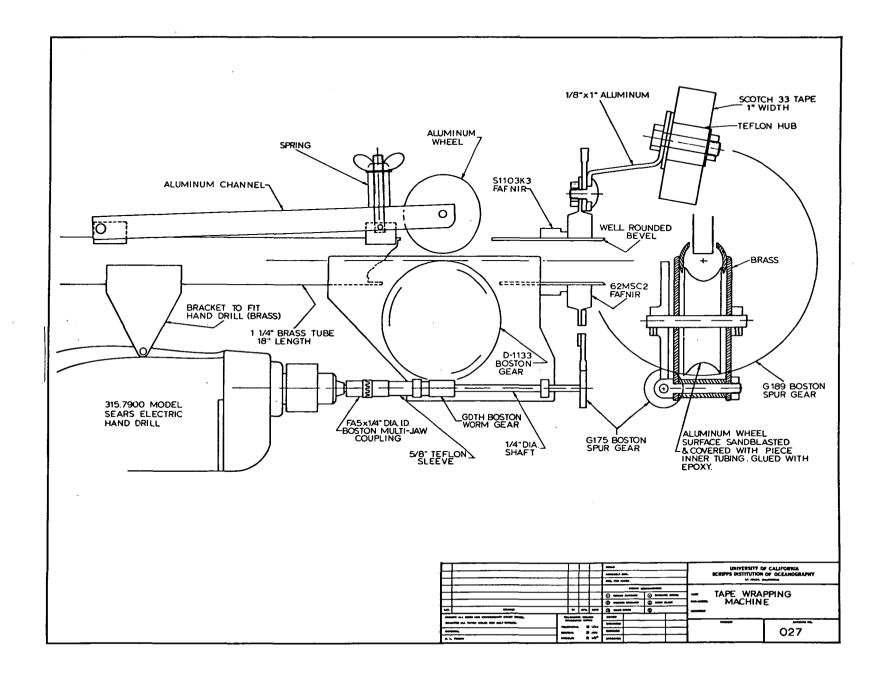


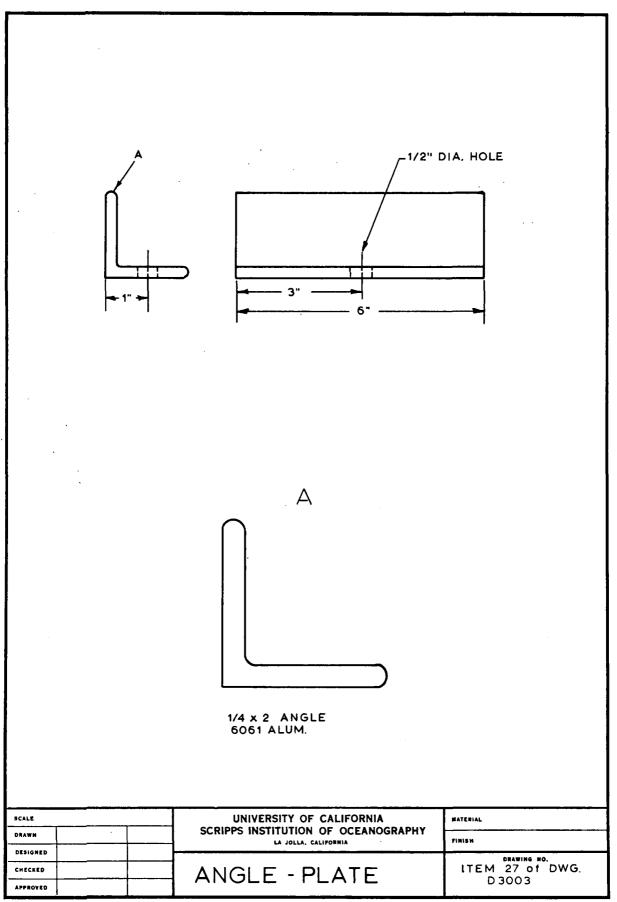


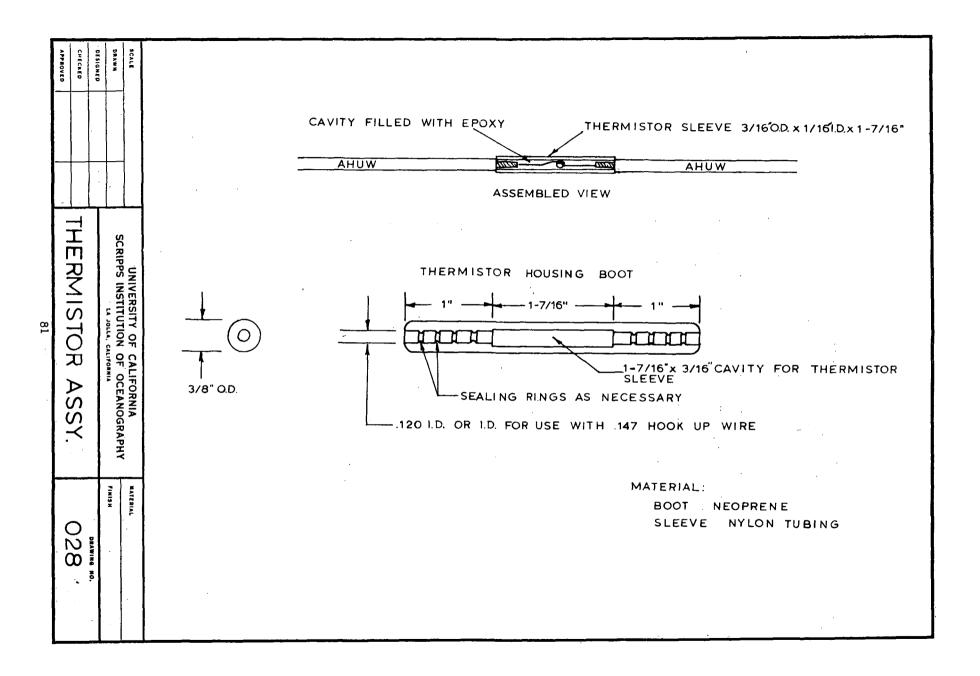
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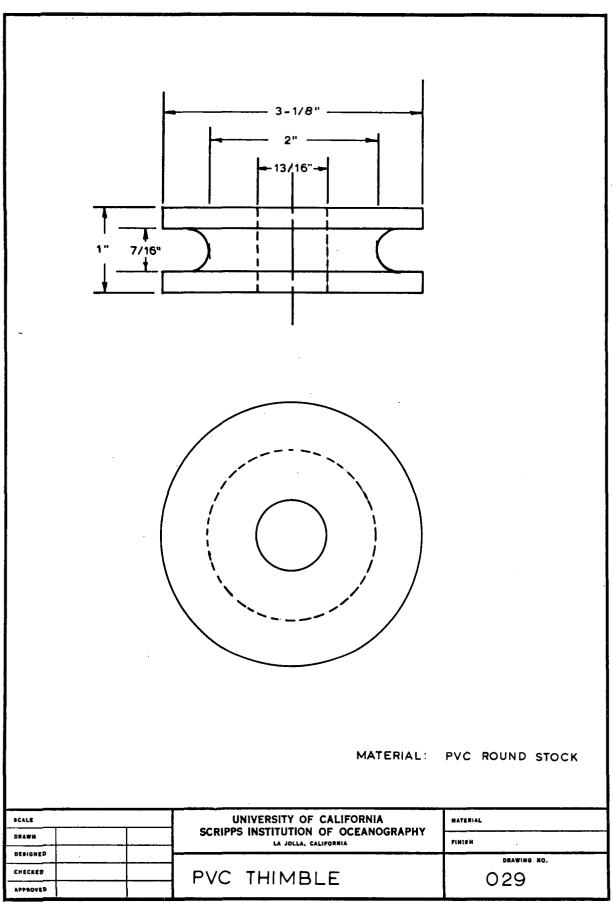












Quantity	Description	Vendor	Reference Drawing No.	Approx.
	A. Float, Associated Hardware	· · · · · · · · · · · · · · · · · · ·		
* 1	Catamaran Instrument Float	Mauricio and Sons Marine 2420 Byron Street San Diego, California	002	\$570
1	Stanchion		026	25
1	12 ft. tapered Fiberglas pole		001	8
		Sub total		\$603.00
	B. Mooring Line and Hardware			
L	1100 1b. anchor 55 gallon drum chain and cement	Note: Free anchor chain was used	Fig. 2	30
2	PVC thimbles		029	10
2	Stainless steel 3/8" Thimble		Fig. 2	2
* 100 ft.	3/8 Galvanized chain	Kettenburg Boat Works 2810 Carlton San Diego	Fig. 2	56
2	5/8" Screw Pin Anchor shackle, 18-8 stainless steel	Schnitzer Alloy Prod. 325 Pine St. Elizabeth, New Jersey	Fig. 2	22
* 500 ft.	7 x 19-1/4" stainless steel aircraft cable	Pacific Wire Rope Co. 1840 East 15th Street Los Angeles, Calif.	Fig. 2	143
* 1	Jacketing SS Cable .002 Mylar 50% lap .015 Natural polyethylene Jacket	Gavit Wire and Cable Co. Escondido, Calif.	Fig. 2	45
l length (depends on depth of mooring)	7/16" Goldline Nylon	Tubbs Great Western Cordage 501 W. Palm Avenue Orange, Calif.	e Fig. 2	\$.052/ft. a 2000 fathom mooring would cost \$624
2300 ft.	Amergraph Hook-up wire 3/64" 7x19 Tinned cadium bronze Neoprene jacket	Columbia-Geneva Steel Box 3040 Terminal Annex Los Angeles 54, California		113
3	Galvanized shackle 5/8"	· - · · · ·		5
		Sub total		\$1,050.00

* Cost based on 5 units

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<u>Quantity</u>	<u>Description</u>	Vendor	Reference <u>Drawing No</u> .	Approx. Cost
1	C. <u>External Instrumentation</u> Hydraulic clevis Model 3000 B.Pressure Transducer 0-1000 PSI 5000 ohm	Computer Instrument Corp. 420 Madison Avenue Hempstead,Long Island NY	181020 181020	\$237 120
1	Remote Compass		180909	117
1	Microtorque Potentiometer Type 9, Model 85111	G.M.Giannini and Co. Inc. 1600 Mountain Avenue Duarte, Calif. 91010	180909	56
6	Precision thermistor 3000 ohms 25°C selected to 0.1°C over a range of 0°-30°C	Yellow Springs Instr. Co. P. O. Box 106 Yellow Springs, Ohio	-	30
6	Thermistor Housing Boats	Marsh and Marine Mfg. Co. Houston 36, Texas	028	9
12 rolls	No. 22 Scotch Electrical Tape 1"x36 yds.	Sunlight Electric Supply 205 Market St. San Diego, Calif.	Со.	24
1	Amphenol plug assembly 89-128-17p-11 (instrument line plug) Amphenol socket assembly 89-228-175(c)	Amphenol Connector Div. 9201 Independence Avenue Chatsworth, California	022	28
12 ft.	(instrument box mounted) Tygon tubing 1-1/4" OD	:	001	12
_			007	25
1	Mast Bracket Assembly Mast Assembly		007	150
l ea.	Aniometer-wind direction assembly, resistance of W/D potentiometer is 5000 ohms, units sealed against submersion in sea water	Rochester Instrument Co. 325 Military Dr. Colurd Alene, Idaho	004	85
1	4C4-A strobe light 15 FPM, 6 VDC, Daylight Control	ACR Electronics 551 West 22nd Street New York 11, N.Y.	004	90
6 hrs.	Assembly of Instrument line at \$10.00/hr.			60
		Sub	total	\$1,043

Quantity	Descriptio	<u>on</u>	Vendor	Reference Drawing No.	Approx. <u>Cost</u>
	D. <u>Record</u>	ing System			
11		ent mounting board 3"x33" Plywood or		003	6
1	Instrum	nent Box	Zero Manufacturing Co. 1121 Chestnut Street Burbank, California	 4 03003 03003C1 03003C2 03003C3 	700
l set	Battery	/ Box		008	30
1	Light a	and support assembly		011	15
1		nent Panel .ass assembly		016 017-18	50
• 3 ft.		Brass, cadium piano hinge		003	2
1	Camera	Platform		010	15
1		ry version of the nd Howell 200 P	Possibly no longer available	003	500
1	Elgeet angle I	12 mm 1.2 wide ens	Nelson Photo Supply 1917 India Street San Diego 1, California	003	103
1	Electri circuit	c control : CB-3		019	75
l ea.	circuit	aneous electronic (future circuits be incorporated 3)		021	15
1	TE-13-1 a) 24 t b) SPST ever c) Epox	on Industrial timer .0 hour dial Switch closure cy 24 hrs.at 2400 hrs sy sealed face setting	Bulova Watch Co. Bulova Park Flushing 20, N.Y.	016 021	290
1		04-6VDC magnetic manual reset	Veeder Root Inc. P. O. Box 128 Montrose, Calif.	016 003	20
* 6		ing pyrometers 7-17°C	Aero-Marine Electronics 3045 Moore San Diego, Calif.	024	72.40

* Baxed on quantities of 30 units

Quantity	Description	Vendor	Reference Drawing N o .	Approx. <u>Cost</u>
	(<u>D. Recording System Cont'd</u>)			
* 6	25-0-25 microamp tautband meter - Model 46H-250R; scales identical to UCSD P.O. 74899 (12-18-63)	Hickok Electrial Instrument Co. 595 N. Lake Avenue Pasadena, Calif.	024	\$360
* 5	0-100 micro-amp tauntband meter - Model 46HR;scales idential to UCSD - PO 74899 (dated 12-18-63)	same as above	023	130
1	Wind speed indicator circuit		025	40
3	Wind direction, compass repeater, tensiometer circuits		025	120
1	Air temperature circuit		023	50
11	Bendix Pigmy plug PT-6E-4P	Aero-Marine Electronics 3045 Moore Street San Diego, Calif.	022	62.26
11	Bendix Pigmy socket PT-7A-4S	same as above	022	69.08
5	Aluminum case extensions	same as above		31.40
12	Miscellaneous electrical plugs and connectors		020 022	31.29
4	M907 Mallory carbon batteries		020	19.92
50 (minimum order)	16 MM Universal Magazine 50 feet of Recordak Fine Grain Fil, Type 7456 with opaque backing	Recordak Corporation 343 State Street Rochester 4, N.Y.		250.
32 hrs.	System assembly of Instrument float at \$10/hr.			320.
		Sub	total -	\$3,377.35
	TOTAL SYSTEM COST			<u>\$6,073.35</u>

* Based on quantities of 30 units

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Scripps Institution of Oceanography		2 b. GROUP	Unclassified
La Jolla, California 92038			
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(with details of	design and cor	structi	on)
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Summary through April 5, 1965			
5. AUTHOR(S) (Last name, first name, initial)			
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10 AVAILABILITY/LIMITATION NOTICES	G. B. Schlok	м. н	Sessions, R. A.
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13 ABSTRACT One of the persistent problem	L of oceanogram	hv is t	o escertain the nature
and cause of large-scale shifts in the s	urface water ma	isses of	the oceans. The ex-
istence of such changes are readily appa	rent from vesse	el measu	rements. However, the
nature of the motions involved cannot be	documented by	anv fea	sible ship survey. It
probably can best be documented by an ar	ray of continuo	ous reco	rding instrument sta-
tions.			
For this and other purposes deep-mo	ored instrument	: statio	ns have been designed
that record meteorological data and ocea	nographic data	in the	upper few hundred meter
Twenty installations of evolving designs	of the taut-ny	lon moo	ring have been tested
over a period of 3-1/2 years.			
The approach has resulted in an increasing reliability and life of the instal-			
lations and recent designs have a useful life of at least six months when moored in			
the deep open sea and much longer in deep sheltered areas. Developments and results			
of tests are discussed. Complete construction drawings with notes on construction,			
installation, and servicing are included.			
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DEEP-MOORED INSTRUMENT STATION DESIGN AND PERFORMANCE

1967 - 1970

R.M. Born, D.M. Brown, J.D. Isaacs, R.A. Schwartzlose, and M.H. Sessions

University of California Scripps Institution of Oceanography 11 May, 1970

UNIVERSITY OF CALIFORNIA, SAN DIEGO Scripps Institution of Oceanography

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TABLE OF CONTENTS

1	Page
LIST OF TABLES	iii
LIST OF FIGURES	iv
ABSTRACT	v
INTRODUCTION	1
BUOY HULL	2
INSTRUMENTATION	7
SENSOR CABLE ASSEMBLY	10
MOORING SYSTEM	12
RESULTS	14
FUTURE PLANS	25
ACKNOWLEDGEMENTS	27
REFERENCES	28

· ·

LIST OF TABLES

Table	Page
1. Bumblebee catamaran mooring summary	15
2. Data for Bumblebee moorings	29
3. Thermistors operating for the duration of the	
installation and cause of failures	19
4. Number of days of acceptable data for North	
Pacific Study buoys processed through December,	
1969	21

LIST OF FIGURES .

Figure		Page
1.	Test "Bumblebee" buoy at 34° N, 164° E, wind 45 knots (23 m/sec) and 20 ft (6 m) sea and swell	4
2.	SIO "Bumblebee" buoy - moored	6
3.	SIO "Bumblee" buoy - cutaway diagram	6
4.	Interior of the instrument box	8
5.	Interior of the instrument box	8
6.	Close-up of the instrument box	9
7.	Instrument cable - cutaway diagram	11
8.	Taut-nylon Bumblee mooring	13
9.	Damaged buoy - instruments had been stolen	17
10.	Station 40 (42° 27.7' N, 158° 2.0' W) November,	
	1968	23
11.	Station 40 (42° 27.7' N, 158° 2.0' W) October,	
	November, 1968	24

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DEEP-MOORED INSTRUMENT STATION DESIGN AND PERFORMANCE

1967 - 1970

Abstract:

Deep-moored instrument stations that record oceanographic and meteorological data for long periods of time have been in use at Scripps Institution of Oceanography for a number of years. Recently the ability of these stations to survive very heavy sea conditions has been greatly improved and the data-recording capability enhanced and increased. Test moorings and operational deployments have shown that many stations will survive for periods of one year or more in the central North Pacific Ocean including the winter storm season. The designs are described, as well as results from extensive sea tests and actual operational deployment in the central North Pacific Ocean.

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INTRODUCTION

Low-cost anchored instrument stations that record a number of parameters offer a very attractive method of gathering long time-series data from many locations simultaneously. Toward this end we have continued the development of deep-moored instrument stations. The first design started in the early 1950's using taut wire to a sub-surface float, a slack buoyant mooring pennant to the surface, and a small boat-shaped hull. (1,2) In the early 1960's we changed to the taut nylon mooring line attached directly to the surface catamaran hull.

Experience from these moorings indicated that a number of improvements were necessary. In particular, the flat catamaran float was ultimately susceptible to capsizal in heavy seas. The addition of ballast tanks improved the survival but did not prevent capsizal under extreme conditions. Also the sensor cables were manufactured at Scripps Institution of Oceanography using materials and techniques suitable for hand construction. While these cables performed well for 3-6 months, increased endurance was needed. It also became necessary to increase the number of parameters recorded and improve some of the sensors in accuracy, reliability, and life.

This latter development resulted in a design that is now used to collect data in the eastern North Pacific Ocean. $^{(3,4)}$

BUOY HULL

The present design of the deep-moored instrument station is a result of experience gained over the past 18 years. The flat catamaran described in Reference 3 performed very well under all but the most severe sea conditions but, because of occasional capsizal in heavy weather, a float was designed with the property of righting from a completely inverted position.

The principal design requirements were:

- A hull with the property of self-righting from a completely inverted position.
- A mooring point located near the center of motion to reduce electrical conductor and mechanical termination failure.
- A weight of less than 2,000 lbs (909 kilo) fully instrumented.
- 4. A beam of less than an 8-ft (2.33 m), for ease of highway transportation.
- 5. A hull suitable for boarding and service in moderately rough seas.
- 6. A system with an operational life of at least one year.
- 7. A hull easily constructed and repaired.
- 8. A system of low cost.
- 9. A hull that is unsinkable.
- 10. A hull with an undesirable and useless appearance.

The major concept change from the previous platform was the righting characteristic. The ballasted open catamaran was entirely satisfactory except in extreme weather. It was clear that the desirable high stability of such a water-plane shape as the catamaran could be incorporated with a self-righting superstructure, and the present design is a result of this marriage.

The cylindrical superstructure of the buoy makes a nonballasted catamaran truly self-righting, and provides shelter for instruments and servicing personnel. The merits of this design were tested with a number of scaled models of existing buoy designs, some proposed designs, and the new covered catamaran configuration, which were constructed and anchored in the surf. The relative performance of these buoys operating simultaneously in breakers of catatrophic scale made it readily apparent that the new catamaran design was a remarkable performer under these extreme conditions.

A full-size [12 ft (3.66 m) in length] prototype buoy was then anchored in 3230 fathoms (5907 m) at Ocean Weather Station Victor (34° N, 164° E) to test the buoy hull and mooring system under adverse sea conditions (Fig. 1).* The buoy successfully withstood winds of over 90 knots (47 m/sec) simultaneous surface currents of 3 knots (1.5 m/sec), and seas of at least 40 ft (12 m) during a typhoon. It remained anchored for 7.5 months until it was inadvertently torn loose by a Japanese fishing trawler. Line tension

^{*} A short motion picture of the buoy taken from the U. S. Coast Guard Cutter WACHUSETT at Ocean Station Victor during a gale is available.

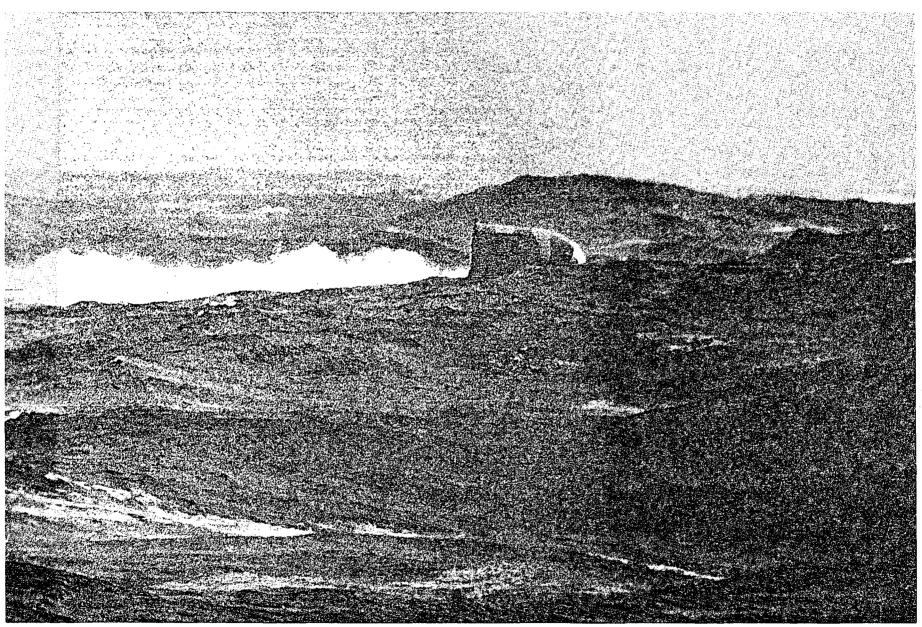


Figure 1. Test "Bumblebee" buoy at 34° N - 164° E, wind 45 knots (23 m/sec) and 20 ft (6 m) sea and swell. Photo from USCGC WACHUSETT.

records from this buoy affirmed that the principal stress on the mooring is caused by current drag on the mooring line. Also records of pitch and roll indicate that the buoy approximately follows the surface of the sea.

Two other buoys [14 ft (4.27 m) in length] were anchored 10 miles (16.1 km) off Monterey, California, in 1110 fathoms (1847 m) to test a boarding platform, instrumentation changes, and new instrument cable designs. One instrument cable parted due to fatigue failure of the strength member just below the float attachment point during a storm about one month after deployment and the buoy came ashore through the high surf landing unscathed on the beach. The other buoy was removed after 11.5 months for engineering analysis.

From these tests an operational float was designed with catamaran hulls [16 ft length (4.88 m)] including a 4-ft (1.2 m) boarding platform and covered over as shown in Figures 2 and 3. The covered portion provides excellent shelter for the instrumentation and the personnel servicing the buoy. Buoys of the present design are constructed of plywood, polyurethane foam, and fiberglass; are 16 ft (4.88 m) long; have an 8-ft (2.44 m) diameter; and displace 1800 lbs (816 kilo) fully instrumented. They soon became known as the "Bumblebee Buoys" due to their shape and colorful striped paint.

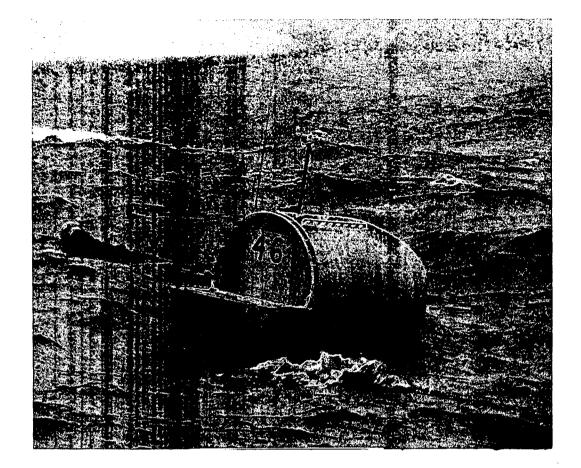


Figure 2. SIO "Bumblebee" buoy - moored.

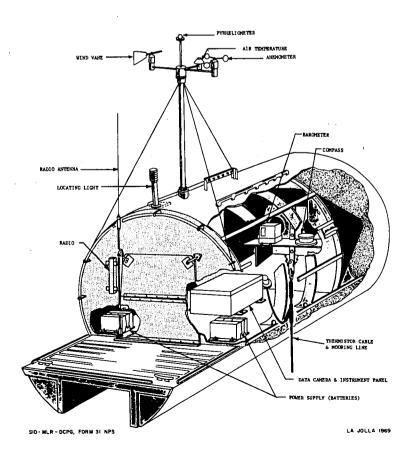


Figure **3**. SIO "Bumblebee" buoy - cutaway diagram.

INSTRUMENTATION

Recording data by photographing meters has been used in our buoys with good results for a number of years.⁽³⁾ This technique is simple, low cost, and reliable. While other techniques appear attractive it was decided to continue this proven technique until we had solved a number of the other more pressing problems such as extended survival of the float, sensor cable, and mooring line.

Our data requirements made it necessary to increase the number of data channels to twenty and the capacity of the film magazine to six months at a rate of one frame per hour. This was accomplished by utilizing a simple 35 mm electrically-driven camera with a capacity for 200 ft (61 m) film spools. By using four mil thick Estar-based film, 250 ft (76 m) could be loaded onto a standard 200-ft (61 m) spool. Also, by using smaller diameter instrument meters [2.5-inch (64 mm)], a format of 20 dials was layed out which allowed 4300 data frames to be taken per 250 ft (76 m) roll of film.

The recording system was housed in a water-tight aluminum case along with all signal conditioning and control systems. As shown in Figures 4 and 5, the data camera at one end of the housing faces a spherical section panel containing display meters and counters. On receipt of a contact closure from the panel-mounted Accutron clock, a picture-taking sequence is initiated. This begins by turning on power to all instruments for 10 seconds to allow the heavily-dampled instrument meters to reach equilibrium. At the end of the 10-second period, a group of incandescent lamps are turned on for two seconds exposing the film. (For simplicity, no shutter is used in the camera.)

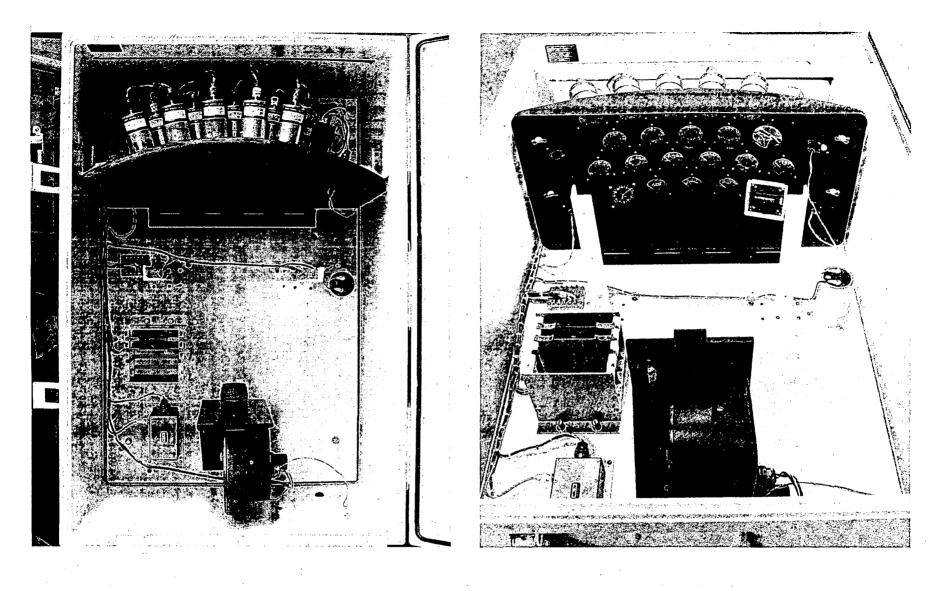


Figure 4. Interior of the instrument box.

Figure 5. Interior of the instrument box.

As soon as the lamps turn off the film is advanced to the next frame; then the entire system is turned off until another initiative pulse is received from the clock. This method uses a minimal amount of power (approximately 180 mw average). A typical data photograph is shown in Figure 6.

The signal-conditioning circuitry for each meter is mounted in a sealed cylinder attached to the rear of the meter to form a self-contained package. Only power and sensor connections are required to each unit for proper function.

The present design records 9 sea-water temperatures to 300 m depth, pressure measurements at 150 m and 300 m, air temperature, wind speed and direction, wind transport, insolation, barometric pressure, buoy heading, line tension, battery voltage, and date-time (GMT).

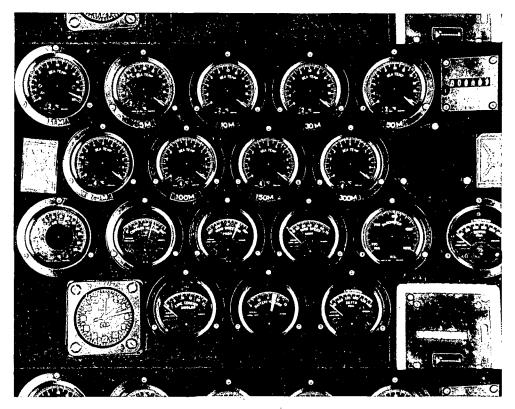


Figure 6. Close-up of the instrument box.

SENSOR CABLE ASSEMBLY

The sensor cable was initially identified as one of the critical problem areas. Past cables were handmade at Scripps using neoprene and rubber-covered cadmium bronze conductors. This wire has been a standard single-conductor wire used by many underwater plug manufacturers for a number of years. In field experience most of these cables failed within six months. Examination of these failures showed that water had penetrated the insulation at a number of points and corroded through the conductor causing an open circuit to the sensor. One attempt to correct this was to jacket the wire again with a polypropylene jacket. This was not considered a satisfactory solution because the wire became too stiff, bulky, and the overall diameter of the cable was increased.

The sensor cable that is now used was designed to take advantage of modern thermoplastic materials and manufacturing. Thermistor breakouts were completely eliminated by placing the snesors inside the cable and extruding a tough polyurethane jacket over the terminated sensor. This is feasible because the thermistors are small and can be placed inside the cable assembly prior to jacketing with no increase in cable diameter (Fig. 7). The sensors are potted onto their respective conductor wires and the entire assembly, as well as each component is water blocked with a deploymerized rubber compound. The water-tight integrity of all electrical wiring is thus double protected and not dependent entirely on the outer jacket, which is primarily a mechanical protection for the conductors. The cable is also tapered 40 - 50% in diameter as fewer conductors continue down

the entire cable length. Considerable reduction in weight and drag result from using this technique, as well as substantial reduction in average diameter particularly when large numbers of temperature sensors are located at shallow depths. The present cable length is 300 meters and in most thermistors are located 1, 5, 10, 30, 50, 75, 100, 150, and 300 meters below the surface. The time constant for each thermistor is approximately two minutes. There are two breakouts for pressure transducers on the cable at 150 meters and at 300 meters depth.

This basic cable design has been in use since February, 1967 and has proven very dependable and long lasting. Several cables have been in use since October, 1968, to the present (April, 1970) with all but one or two thermistors still functioning.

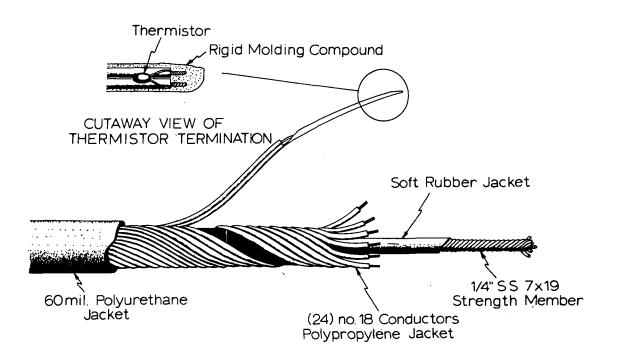


Figure 7. Instrument cable - cutaway diagram.

MOORING SYSTEM

The sensor cable extends down from the surface float to a depth of 300 meters. Below the sensor cable to the anchor on the ocean floor, nylon line serves as the mooring component. This is shown schematically in Figure 8. The mooring line is standard 3-strand gold nylon of 9/16" (14.5 mm) diameter. This construction can be used because tension is always maintained on the mooring line and the surface float is directionally oriented thus preventing spinning. A 1262 ft (385 m) portion of the nylon line just below the sensor cable is jacketed with polyurethane to help resist fishbite. Evidence collected from earlier tests suggested that a tough plastic jacket placed over the nylon would greatly reduce failures due to fishbite. ⁽⁴⁾

The mooring is installed with a static tension by employing a mooring line that is 10 percent shorter than the corrected measured depth. This tends to keep the surface buoy in a small diameter circle, and reduces dynamic forces due to slackening of the line, and provides other desirable characteristics. The static tension measured from a number of buoys has averaged about 500-700 lbs (227-308 kilos) including sensor cable weight of 300 lbs (136 kilos). Tension is very sensitive to current speed. In fact, semidiurnal and inertial period oscillations have frequently been measured by the line tension.

The ground tackle consists of a dead weight anchor and a drag anchor. The large anchors are usually 55 gal (209 liters) oil drums filled with used anchor chain and concrete to yield a weight of 1000 lbs (454 kilos) or more in sea water. This type of anchor is very inexpensive and has proven satisfactory in a large number of moorings. The drag anchor is a 25-lb (11.3 kilo) Danforth type attached to the main anchor by 20 ft (6 m) of 3/8" (10 mm) galvanized chain.

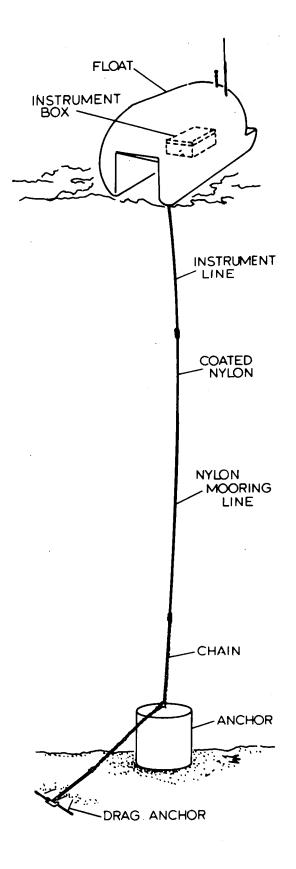


Figure 8. Taut-nylon Bumblebee mooring.

RESULTS

The results of the latest-designed deep-moored instrument station have demonstrated that it is feasible to collect year-long time series of both meteorologic and oceanographic data in open stormy seas.

Table 1 is a summary of all the bumblebee catamaran moorings that we have anchored to date. This table shows that out of 19 moorings 9 are still anchored or were removed after their term of usefulness expired. Of the 10 moorings that ultimately failed:

> one had its mooring line cut by a Japanese fishing vessel (#31), one had a construction defect in the instrument line (#34), one had a broken mooring plate in the buoy due to vibration fatigue (#42),

one had the mooring eye on the float come loose because the cotter key was not inserted to lock the nut in place (#32), and

six were lost through unknown causes.

Seven moorings remained anchored for more than 11.5 months, two of these for 18 months. Table 2 contains details for each mooring location, mooring depth, dates, type of mooring line and instrumentation. (Table 2 is located at the end of this report.)

The floats and mooring system have survived a wide variety of sea and weather conditions. One catamaran float has survived typhoon winds and seas in the western North Pacific, and another stayed anchored through the 1968-69 winter after nearly total distruction

Buoy number	Known moo		Remarks
31	7.5 m	onths	Mooring line cut by Japanese trawler
32	0	11	Mooring failed on the day after it was anchored
33	3	£1	Adrift
34	1	u	Cable fatigue failure near attachment point
35	11.5	11	Removed
36	2		Removed
38	18		Removed
39	12	11	Not found in December, 1969 ^{1,2}
40	14	u ·	Not found in April, 1970
41	8	ff .	Removed ^{1,2}
42	12	11	Found adrift near Kodiak Island ²
43	3	н	Adrift ²
44	0	*1	Never sighted or reported after mooring day^3
45	13	11	Removed ²
46	12	11	Still moored
47	0	н	Never sighted or reported after mooring day
X47	4	н	Removed
48	0	11	Not visited since moored in April, 1970
49	0	u	Not visited since moored in April, 1970

¹ All instruments stolen.

 $^{\rm 2}$ Damaged by a ship other than servicing ship.

 3 May have been carried away by the dragging BRAVO buoy. Note: There was no #37 bumblebee mooring. of the upper shell (Fig. 9). Six moorings remained anchored during the 1968-69 winter and two moorings were operating after two central North Pacific winters. One float remained anchored two months, before it was removed, in the Gulf Stream off Florida and experienced 3- to 4-knot (150-200 cm/sec) currents and 80-knot winds from the south (this was not an SIO mooring but was our hull design).

The floats that remained anchored from 14 to 18 months and which had not been damaged by ships or people are in excellent condition. There are large numbers of barnacles covering the hulls but otherwise the fiberglass, plywood, and foam show little sign of deterioration.

One of the ma or problems, which most likely has contributed to losses, is from ships and people other than our own. Five moorings out of nine anchored at least a year ago in the central North Pacific are known to have been boarded and extensively damaged; two had their instruments stolen. In some cases it appears that personnel aboard a ship have attempted unsuccessfully to retrieve the float with all its instruments without cutting the anchor line. The North Pacific Study Cruise 3 Report details two incidents where the buoys have been extensively damaged. Figure 9 is a picture of the remains of a catamaran float found on Cruise 2 where all the instruments had been stolen and an attempt was probably made to retrieve the float. Buoy #39 is reported as follows:

"On approaching the buoy, rather extensive damage was observed. There was a large gash in the starboard bow, a large hole in the overhead, and deep scuffs along the whole starboard side. On

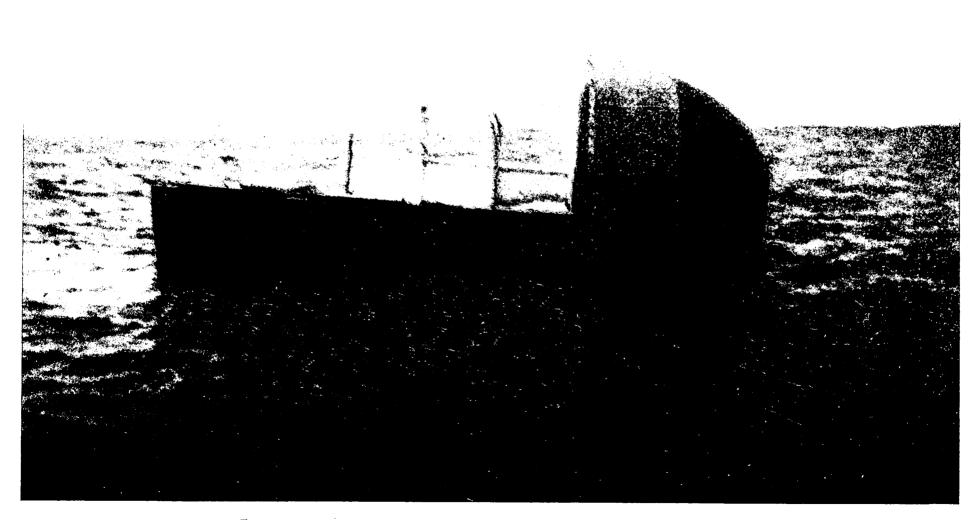


Figure 9. Damaged buoy - instruments had been stolen.

boarding it was found that all instrumentation had been stolen The crushed radar reflector was found inside the buoy. The reflector had been driven through the buoy skin leaving a large hole."

We have tried to reduce the pilfering by leaving a supply of complete drawings concerning the system with an invitation to take a set of drawings rather than the instruments.

The instrument cables have operated remarkably well. Table 3 lists the number of thermistors operating at the end of the mooring or when it was last visited.

Analysis of the test cable (#35) after 11.5 months at sea showed that the cause of open circuits was due to the sealing compound at the thermistors. This was not strong enough to provide adequate mechanical support for the very fine wires that attach to the thermistor head. The moorings #38 through #46 employed this type of sealing compound at the thermistors. In all cables after mooring #46 a higher strength potting compound has been used, but no data are yet available on this most recent cable design. Most of the five short circuits in one cable occurred simultaneously as determined from data analysis. This cable was not recovered, and the cause remains unknown. It is possible that a fish bite could have caused a water leak. The recently recovered mooring #38 shows evidence of fish bites on the instrument cable but these do not penetrate to the conductor wires.

All but one of the pressure-measuring devices at 150 m and 300 m failed in less than 100 days (Table 4). The cause is not known. When

Buoy	Number of operating thermistors	Number and cause of failures	Period of mooring
#35*	6	3 open circuit	11.5 months
#38	2	7 open circuit	14
#39	. 7	2 open circuit	2 "
#40	8	l open circuit	14 "
∦42	2	5 short circuit 2 open circuit	12 "
#45	7	2 open circuit	18 "
#46	9	0	ι2 "
7	41	22	83.5

Table 3.	Thermistors operating f	for the	duration of	the	installation
	and cause of failures.				

* Original test cable.

mooring cable #38 is returned it is hoped that an analysis will shed some information on these failures.

The five meteorological sensors have produced some interesting results and have operated very well except for the wind speed and barometer. The anemometer has repeatedly failed very quickly after being installed during each servicing cruise. The barometers all failed, primarily due to vibration.

The electronics and the indicator meters inside the instrument box have operated with almost no failures. The greatest loss of data was caused by camera failures due to a faulty mechanical method for turning off the camera when it advanced a frame. This has been corrected and subsequent tests have shown the camera can cycle 50,000 times without a failure.

The processed data from all our moored buoys have shown many interesting features such as large, long-term temperature inversions, inertial oscillations, very large temperature changes occurring in periods of a week to three weeks, the usual semidiurnal internal waves, and the nature of seasonal heating and cooling. The processed data have been distributed in two volumes with a third volume in preparation. ^(4,5)

Table 4 tabulates the number of days of acceptable data for each parameter taken by the North Pacific Study buoys. It also shows the cause of each failure. With the problem corrected in the camera and the change in design of the thermistor attachment, future loss of data from instrument failure should be minimal.

Two examples of the processed data are shown in Figures 10 and 11. Calibration studies of most sensors have been carried out on each

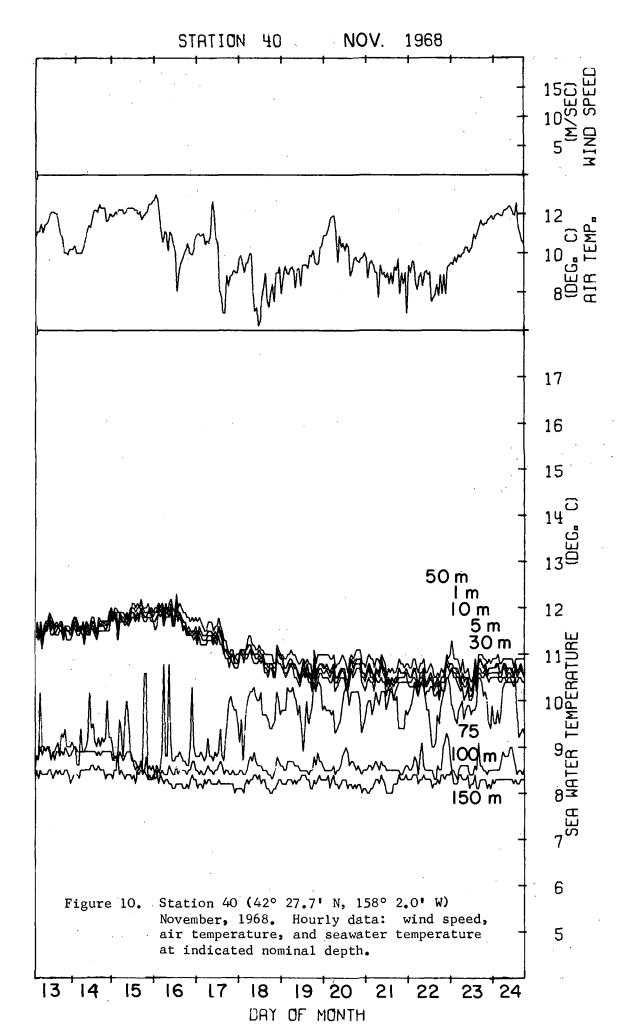
Buoy ni	umber		38	39	40	42	45	46
Wind d:	irection		269 ¹	57 ¹	1551,5	135 ¹ , ²	2302	. 80 ¹
Wind s	peed		204 ¹ , ²	12 ²	65 ^{1,2,5}	128 ¹ , ²	73 ²	· 17 ²
Wind t	ransport		162 ²	12 ²	65 ¹ , ² , ⁵	128 ¹ , ²	253,4	· 0 ⁴
Air te	mperature		269 ¹	57 ¹	155 ^{1,5}	205 ¹ , ²	107 ^{2,6}	80 ¹
Buoy h	eading		269 ¹	57 ¹	155 ^{1,5}	296 ¹	321 ¹	80 ¹
Barome	ter		207 ¹ , ² , ³	57 ¹	25 ^{1,2,3,5}	107 ^{2,3}	1082,3	0 ⁷
Py rhe i	iometer		229 ¹ , ³	57 ¹	155 ^{1,5}	105 ^{2,3}	1192	80 ¹
	re at 150 le length		165 ^{1,2}	7 ²	101 ¹ ,2,5	30 ²	46 ²	24 ¹ , ²
	re at 300 e length	m	165 ¹ , ²	۱7 ²	95 ¹ , ²	30 ²	34 ²	24 ¹ , ²
Line to	ension		0 ²	0 ²	19 ^{1,2}	194 ^{1,2}	21 ²	37 ¹ , ²
Water	temperatu	re l m	36 ¹ , ² , ⁴	57 ¹	1551,5	194 ¹ , ²	2421,6	80 ¹
н	11	5 m	165 ¹ , ²	13 ²	1551,5	296 ¹	321 ¹	42 ^{1,4}
0	บ	10 m	165 ¹ , ²	18 ²	155 ^{1,5}	o ²	47 ³	80 ¹
11	0	30 m	207 ¹ , ²	o ⁴	155 ^{1,5}	89 ²	3211	80 ¹
11	u	50 m	269 ¹	57 ¹	155 ^{1,5}	30 ²	218 ¹ , ³	80 ¹
11	11	75 m	269 ¹	57, ¹	1551,5	30 ²	321 ¹	80 ¹
	11	100 m	207 ^{1,2}	57 ¹	155 ¹ ,5	30 ²	1243	80 ¹
	11	150 m	170 ^{1,2}	57 ¹	155 ^{1,5}	296 ¹	79 ² , ³	80 ¹
н	н	300 m	137 ²	57 ¹	2^2	1412	0 ²	80 ¹
l m lag	g tempera	ture						81 , 4
5 m lag	g tempera	ture						80 ¹
fotal a	available	data days	422	61	428	374	416	208

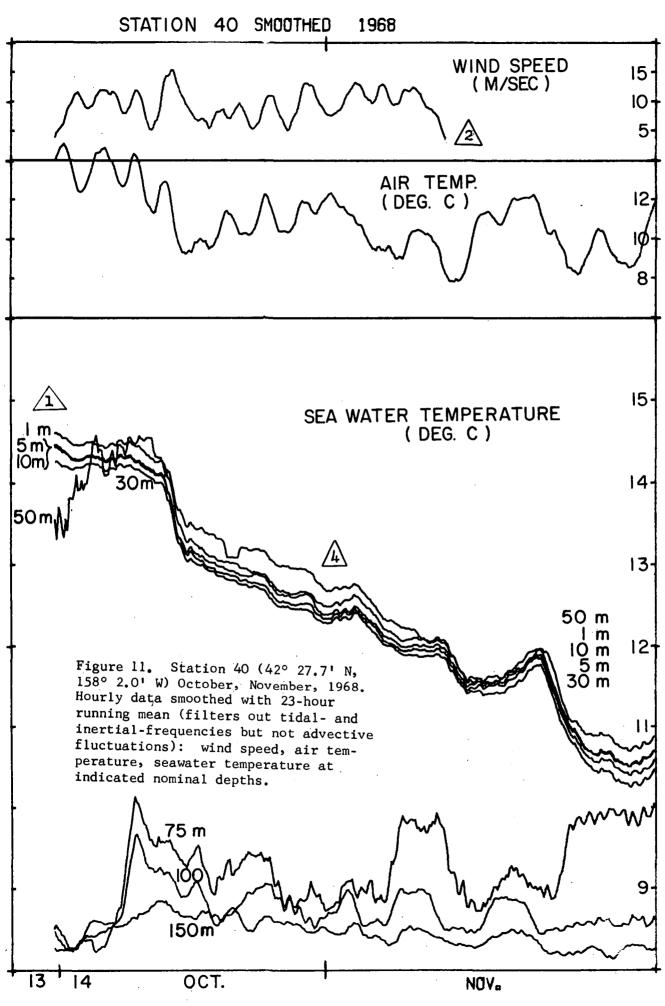
Table 4. Number of days of acceptable data for North Pacific Study buoys processed through December, 1969.

Cause of lost data

- Camera failure
- 2. Sensor failure
- 3. Sensor or indicator removed and not replaced
- 4. Indicator failure
- 5. Timing failure
- 6. Indicator not readable on film
- 7. No sensor

cruise. The water temperature thermistors have been calibrated against Nansen casts, TDS, and XBT's, and have shown that calibrations do not detectably change. After a year, the system remains accurate within 0.1 or 0.2° C, which is the limit of our film recording, and is adequate in the upper layers of the ocean.





FUTURE PLANS

Some of the plans for deep-mooring improvements include improved sensors, the testing of a 20-ft (6 m) bumblebee buoy with instrumentation to collect BT type data, digital acquisition system, and power generation to charge batteries.

Improved sensors, especially barometer, wind speed, and a new model instrument cable are presently being tested on the buoys in the North Pacific Study.

The winching and recording system for the continuous profiler was recently tested aboard a 20-ft (6 m) bumblebee buoy, anchored six miles off Scripps. It had on board a small specially-designed winch and the necessary electronics, battery power, and wind-mill power alternator to lower and retrieve temperature and depth sensors to 100 meters. Our first experiments were to determine if tangling of the anchor wire and profiler wire were a problem. The tests indicated that this would not normally be a problem and that if it occurred the design allowed the wires to untangle as the wire was retrieved. This system was automatically cycled four times a day. To our knowledge tangling never occurred naturally, although the wire was purposely tangled many times, with automatic untangling always taking place. Over 100 temperature-depth records were obtained. A progress report is in preparation on the design problems and tests related to the automatic continuous profiling buoy system. The design of the digital acquisition system is now going ahead since it appears that the system will work well. It is expected that a test system winch and digital

acquisition equipment will be moored in August or September, 1970. A completely adequate power source for the winch remains a problem. At present we are using a wind-powered alternator, which is adequate most of the time. The power required for the data acquisition system will be no more than our present film recording system. It is apparent that these small, durable buoys could handle equipment designed to radio data collected each day thousands of miles to Scripps via satellite.

ACKNOWLEDGEMENT'S

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Table 2. Data for Bumblebee moorings.

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	#31	#32
DATE MOORED	September 25, 1967	October 14, 1967
LOCATION	34° 03' N, 163° 59' E	30° N, 140° W
DEPTH	3230 fathoms (5907 m)	2288 fathoms (4184 m)
MOORING LINE	1/2" 3 strand gold nylon (12.7 mm) dia. 1262 ft (385 m) polyurethene jacketed nylon	1/2" 3 strand gold nylon (12.7 mm) dia. 1262 ft (385 m) polyurethene jacketed nylon
INSTRUMENT LINE	1/4" (6.35 mm) SS cable, 1493 ft (455 m)	1493 ft (455 m) 1/4" (6.35 mm) SS cable with transducer breakouts at 500' (152 m), 1000' (305 m), and 1500' (457 m)
INSTRUMENTATION	Rustrak Recorder, buoy pitch and roll, line tension, and battery voltage	Time and day, relative wind direction and wind speed, pressure transducers at 500' (152 m) and 1000' (305 m) depths, mooring line tension, pitch roll, and battery voltage
MOORING SHIP	USCGC WACHUSETT	USCGC TANEY
LAST SIGHTED	Removed May 8, 1968	October 15, 1967
LENGTH OF KNOWN TIME MOORED	7 months	1 day
REMARKS	 First of 2 prototype bumblebee catamarans. Constructed by Sea R and D Co. Line cut by Japanese longline boat. 	 Mooring eye on the float came loose because the cotter key was not inserted to lock the nut in place.
KNOWN MAXIMUM WEATHER CONDITIONS	90 knot winds (47 m/sec), 45 ft (14 m) seas during a typhoon, \sim 3 knot currents.	

	#33	#34
DATE_MOORED	February 13, 1968	February 15, 1968
LOCATION	30° 02' N, 139° 56' W	36° 39.7' N, 122° 07' W
DEPTH	2350 fathoms (4298 m)	1110 fathoms (1847 m)
OORING LINE	l/2" 3 strand gold nylon (12.7 mm) dia.	l.2" 3 strand gold nylon (12,7 mm) dia 1200 ft (366 m) polyur≉thene jacketed nylon
INSTRUMENT LINE	1493 ft (455 m) 1/4" (6.35 mm) SS cable with transducer breakouts at 500' (152 m), 1000' (305 m) and 1500' (457 m)	Prototype thermistor cable mfg. by Global Oceanographic, 500 m length 10 thermistors, 1 pressure transducer
<u>INSTRUMENTATION</u>	Time and day, relative wind direction and wind speed, pressure transducers at 500' (152 m) and 1000' (305 m) depths, mooring line tension, pitch roll, and battery voltage	10 sea temperatures, line depth, line tension, wind speed and direction, barometric pressure, compass reading, air temperature, battery voltage, time, insolation
MOORING SHIP	USCGC TANEY	OCEANEER
LAST SIGHTED	May 7, 1968	March 19, 1968 - still moored March 21, 1968 - sighted at Fort Ord, Monterey Bay, beached
LENGTH OF KNOWN TIME MOORED	3 months	1 month
<u>REMARKS</u>	 Mooring #32 was the same float as #33. Second of 2 prototype bumblebee catamarans. Constructed by Arben Marine Co. Buoy has been sighted adrift several times. 	 Built by SIO's Marine Facility. Tested newly designed meteorological sensors and mast and a newly developed barometer. Tested prototype electronic thermometer mfg. by Burnett Electronics and Oceanic Enterprises. Tested Accutron clock with days register in clock. Tested Epply Pyroheliometer. Tested 12" (30.5 cm) radar reflector. Fatigue failure of the strength member in the instrument cable just below float attachment point caused the float to break loose
KNOWN MAXIMUM WEATHER CONDITIONS	Spring conditions at 30° N	43 knots (22 m/sec) winds recorded on buoy #35

Table 2 (continued).

	#35	#36
DATE MOORED	February 15, 1968	April 24, 1968
LOCATION	36° 39' N, 122° 07.2' W	32° 54.7' N, 117° 21.5' W
DEP TH	1134 fathoms (2074 m)	320 fathoms (586 m)
MOORING LINE	l/2" 3 strand gold nylon (l2.7 mm) dia. l200 ft (366 m) polyurethene jacketed nylon	l/2" 3 strand gold nylon (l2.7 mm) dia. l200 ft (366 m) polyurethene jacketed nylon
INSTRUMENT LINE	Prototype thermistor cable mfg. by South Bay Cable, 500 m length. 10 thermistors, 1 pressure transducer	None
INSTRUMENTATION	1) thermometers, 1 depth, line tension, wind speed and direction, compass heading, air temperature, time, battery voltage, insolation	None
MOORING SHIP	OCEANEER	WANDO' RIVER
LAST SIGHTED	Removed January 27, 1969	Removed June 24, 1968
LENGTH OF KNOWN TIME MOORED	ll months	2 months
<u>REMARKS</u>	 Built by SIO's Marine Facility. A General Instrument C. thermo- electric generator was tested. 24-inch radar reflector was tested. Tested prototype electronic thermometer mfg. by Ocean Applied Res. and Burnett Electronics. Tested Hy-Cal pyroheliometer. 	Experimental test mooring.
KNOWN MAXIMUM WEATHER CONDITIONS	43 knots (22 m/sec) winds recorded, two winters off Monterey, California	

	#38	#39
DATE MOORED	October 9, 1968	October 11, 1968
LOCATION	42° N, 164° 00.1' W	42° 55.7' N, 158° 12.0' W
DEPTH	2945 fathoms (5486 m)	2910 fathoms (5222 m)
MOORING LINE	9/16" 3 strand gold nylon (14.5 mm) dia. 1200 ft (366 m) polyurethene jacketed nylon	9/16" 3 strand gold nylon (14.5 mm) dia. 1200 ft (366 m) polyurethene jacketed nylon
INSTRUMENT LINE	South Bay Cable Co., Model #2 Thermistors at 1, 5, 10, 30, 50, 75, 100, 150, and 300 m. Pressure transducers at 150 and 300 m.	South Bay Cable Co., Model #2 Thermistors at 1, 5, 10, 30, 50, 75, 100, 150, and 300 m. Pressure transducers at 150 and 300 m.
<u>INSTRUMENTATION</u>	9 sea water temperatures, 2 sea water pressure transducers, line tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year, time (GMT)	9 sea water temperatures, 2 sea water pressure transducers, line tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year, time (GMT)
MOORING SHIP	USCGC ACUSHNET - WAGO 167	USCGC ACUSHNET - WAGO 167
LAST SIGHTED	Removed April 21, 1970	October 1, 1969
LENGTH OF KNOWN TIME MOORED	18 months	12 months
REMARKS	 Instruments removed December 5, 1969. Mooring could not be recovered because of weather. Mooring #47 replaces #38. 	 May 29, 1969, buoy was found to have had all external and internal instruments stolen and extensive damage to the hull. Buoy not found in December, 1969.
KNOWN MAXIMUM WEATHER CONDITIONS	52 knots (27 m/sec) winds recorded two winters in central North Pacific.	35 knots (18 m/sec wind recorded (record incomplete) one winter in central North Pacific.

Note: There was no #37 bumblebee mooring.

	#40	#41
DATE MOORED	September 21, 1968	October 11, 1968
LOCATION	42° 27.7' N, 158° 02.0' W	42° 55.1' N, 157° 46.8' W
DEPTH	3050 fathoms (5578 m)	2850 fathoms (5212 m)
MOORING LINE	9/16" 3 strand gold nylon (14.5 mm) dia. 1200 ft (366 m) polyurethene jacketed nylon	9/l6" 3 strand gold nylon (l4.5 mm) dia. l200 ft (366 m) polyurethene jacketed nylon
INSTRUMENT LINE	South Bay Cable Co., Model #2 Thermistors at 1, 5, 10, 30, 50, 75, 100, 150, and 300 m. Pressure transducers at 150 and 300 m	SIO hand made sensor cable, 50 m length Thermistors at 1, 2.5, 5, 10, 15, 20, 30, 40, and 50 m
INSTRUMENTATION	9 sea water temperatures, 2 sea water pressure transducers, line tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year, time (GMT)	9 sea water temperatures, line tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year, time (GMT)
MOORING SHIP	USCGC ACUSHNET - WAGO 167	USCGC ACUSHNET - WAGO 167
LAST SIGHTED	November 22, 1969	Removed June 4, 1969
LENGTH OF KNOWN TIME MOORED	14 months	8 months
REMARKS	1. Not found in April, 1970.	 December 6, 1968. All instruments had been stolen and the hull was badly damaged, apparently by a ship.
KNOWN MAXIMUM WEATHER CONDITIONS	45 knots (23 m/sec) wind record (record incomplete) 2 winters in central North Pacific	One winter in central North Pacific

Table 2 (continued).

	<i>#</i> 42	#43
DATE MOORED	September 19, 1968	September 27, 1968
LOCATION	43° 35.6' N, 157° 48.6' W	35° 05' N, 157° 49.0' W
DEPTH	2925 fathoms (5349 m)	3130 fathoms (5724 m)
MOORING LINE	9/16" 3 strand gold nylon (14.5 mm) dia. 1200 ft (366 m) polyurethene jacketed nylon	9/16" 3 strand gold nylon (14.5 mm) dia. 1200 ft (366 m) polyurethene jacketed nylon
INSTRUMENT LINE	South Bay Cable Co., Model #2 Thermistors at 1, 5, 10, 30, 50, 75, 100, 150, and 300 m Pressure measured at 150 and 300 m	South Bay Cable Co., Model #2 Thermistors at 1, 5, 10, 30, 50, 75, 100, 150, and 300 m Pressure tranducers at 150 and 300 m
<u>INSTRUMENTATION</u>	9 sea water temperatures, 2 sea water pressure transducers, line tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year and time (GMT)	9 sea water temperatures, 2 sea water pressure transducers, line-tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year, time (GMT)
MOORING SHIP	UXCGC ACUSHNET - WAGO 167	USCGC ACUSHNET - WAGO 167
LAST SIGHTED	September 27, 1969	December, 1968, by merchant ship
LENGTH OF KNOWN TIME MOORED	12 months	3 months
REMARKS	 Not found in December, 1969. Found adrift and recovered by fisherman near Kodiak Island, Alaska, April, 1970. Mooring plate in the buoy broken from vibration fatigue. 	 Reported in position by a ship in December, 1968. Reported at 30° N, 162° W October 16, 1969 with 4 ft (1.2 m) dia. hole on port side,
KNOWN MAXIMUM WEATHER CONDITIONS	31 knots (16 m/sec) wind record (record incomplete). One winter in central North Pacific.	Part of a winter in central North Pacific

Table 2 (continued),

	#44	#45
DATE MOORED	September 20, 1968	October 19, 1968
LOCATION	43° 00.7' N, 157° 20.9' W	41° N, 148° 02.0' W
DEPTH	3000 fathoms (5486 m)	2670 fathoms (4792 m)
MOORING LINE	9/16" 3 strand gold nylon (14.5 mm) dia. 1200 ft (366 m) polyurethene jacketed nylon	9/16" 3 strand gold nylon (14.5 mm) dia. 1200 ft (366 m) polyurethene jacketed nylon
INSTRUMENT LINE	South Bay Cable Co., Model #2 Thermistors at 1, 5, 10, 30, 50 75, 100, 150, and 300 m Pressure transducers at 150 and 300 m	South Bay Cable Co., Model #2 Inermistors at 1, 5, 10, 30, 50, 75, 100, 150, and 300 m Pressure transducers at 150 and 300 m
INSTRUMENTATION	9 sea water temperatures, 2 sea water pressure transducers, line tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year, time (GMT)	9 sea water temperatures, 2 sea water pressure transducers, line tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year, time (GMT)
MOORING SHIP	USCGC ACUSHNET - WAGO 167	USCGC ACUSHNET - WAGO 167
LAST SIGHTED	Day moored, September 20, 1968	Removed April 15, 1970
LENGTH OF KNOWN TIME MOORED	One day	18 months
REMARKS	 Never sighted or reported after mooring day. 	 December, 1968, service cruise found mast and radar reflector ripped out of buoy.
KNOWN MAXIMUM WEATHER CONDITIONS		70 knot (37 m/sec) wind recorded (wind record incomplete). Two winters in central North Pacific.

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	#46	#47
DATE MOORED	April 28, 1969	December 4, 1969
LOCATION	43° 02.0' N, 157° 17.6' W	41° 53.5' N, 163° 55.0' W
DEPTH	2820 fathoms (5157 m)	2913 fathoms (5327 m)
MOORING LINE	9/l6" 3 strand gold nylon (14.5 mm) dia. l200 ft (366 m) polyurethene jacketed nylon	9/16" 3 strand gold nylon (14.5 mm) dia. 1200 ft (366 m) polyurethene jacketed nylon
INSTRUMENT LINE	South Bay Cable Co., Model #2 Thermistors at 1, 5, 10, 30, 50, 75, 100, 150, and 300 m. Lagged thermistors added at 1 and 5 m. Pressure transducers at 150 and 300 m	South Bay Cable Co., Model #3 Thermistors at 1, 5, 10, 30, 50, 75, 100, 150, and 300 m. Pressure transducers at 150 and 300 m.
<u>INSTRUMENTATION</u>	<pre>11 sea water temperatures, 2 sea water pressure transducers, line tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year, time (GMT)</pre>	9 sea water temperatures, 2 sea water pressure transducers, line tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year, time (GMT)
MOORING SHIP	USCGC ACUSHNET - WAGO 167	USCGC ACUSHNET - WAGO 167
LAST SIGHTED	April 19, 1970	Date moored
LENGTH OF KNOWN TIME MOORED	12 months	0
REMARKS	 Replacement for #44. Lagged thermistor time constant is approximately 3 hours. 	 Replacement for #38 Not found in April, 1970.
KNOWN MAXIMUM WEATHER CONDITIONS	Part of a winter in central North Pacific. (Records are still being processed.)	

Table 2 (continued).

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	#X47	#48
DATE MOORED	September 29, 1969	April 15, 1970
LOCATION	32° 54.6' N, 117° 21.9' W	41° 00.5' N, 148° 02.0' W
DEPTH	315 fathoms (576 m)	2650 fathoms (4846 m)
MOORING LINE	1/2" 3 strand gold nylon (12.7 mm) dia. 1200 ft (366 m) polyurethene jacketed nylon	9/16" 3 strand gold nylon (14.5 mm) dia. 1200 ft (366 m) polyurethene jacketed nylon
<u>INSTRUMENT LINE</u>	No conventional instrument line. This buoy contains an experimental BT winch with a temperature/depth probe attached.	South Bay Cable Co., Model #3 Thermistors at 1, 5, 10, 30, 50, 75, 100, 150, and 300 m. Pressure transducers at 150 and 300 m
<u>INSTRUMENTATION</u>	Temperature vs depth was monitored on a Rustrack Recorder. A wind- powered generator was installed to charge the BT winch batteries. A second Rustrack Recorder monitors charging current and load current.	9 sea water temperatures, 2 sea water pressure transducers, line tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year, time (GMT)
MOORING SHIP	E. B. SCRIPPS	USCGC ACUSHNET - WAGO 167
LAST SIGHTED	Removed for modification January 29, 1970	Date moored.
LENGTH OF KNOWN TIME MOORED	4 months	0
REMARKS	 20 ft (6 m) model experimental system. 	1. Replacement for #45.
KNOWN MAXIMUM WEATHER CONDITIONS	Estimated 30 knots (15 m/sec) wind.	Unknown

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Table 2 (continued).

	#49
DATE MOORED	April 20, 1970
LOCATION	42° 25.7' N, 157° 59.8' W
DEPTH	2713 fathoms (4962 m)
MOORING LINE	9/16" 3 strand gold nylon (14.5 mm) dia. 1200 ft (366 m) polyurethene jacketed nylon
<u>INSTRUMENT LINE</u>	South Bay Cable Co., Model #3 Thermistors at 1, 5, 10, 30, 50, 75, 100, 150, and 300 m. Pressure transducers at 150 and 300 m
INSTRUMENTATION	9 sea water temperatures, 2 sea water pressure transducers, line tension, compass heading, air temperature, wind direction, wind speed, barometer, wind transport, insolation, battery voltage, day of year, time (GMT)
MOORING SHIP	USCGC ACUSHNET - WAGO 167
LAST SIGHTED	Date moored
LENGTH OF KNOWN TIME MOORED	0
REMARKS	1. Replacement for #40.
KNOWN MAXIMUM WEATHER CONDITIONS	Unknown.